



Integration of Common Spacecraft Interfaces & Support Functions

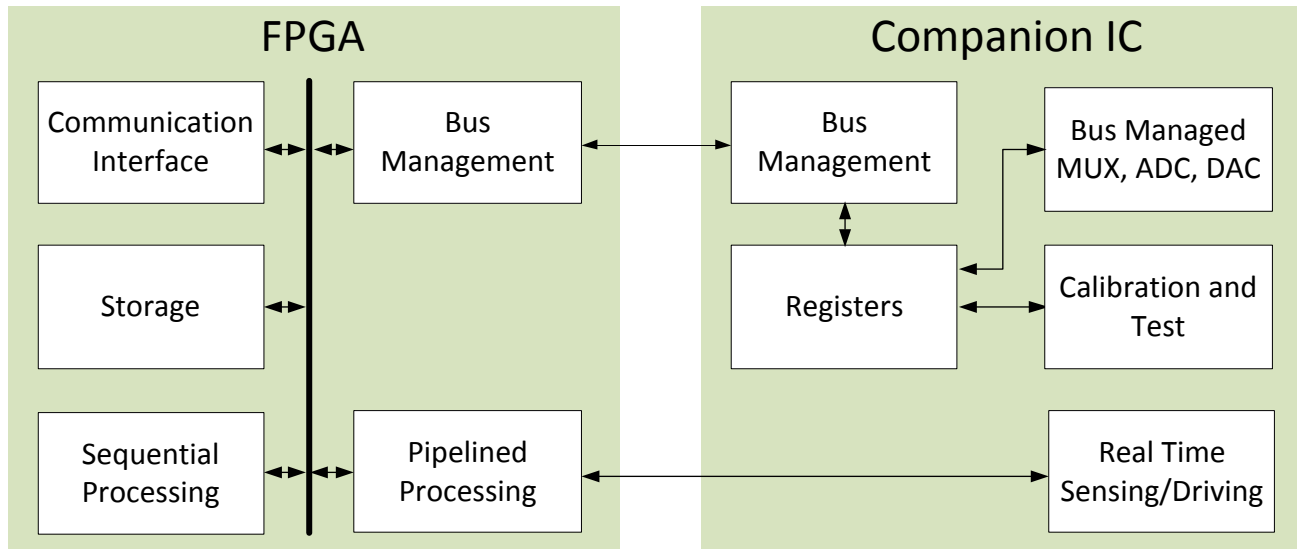
Microsemi Space Forum Russia – November 2013

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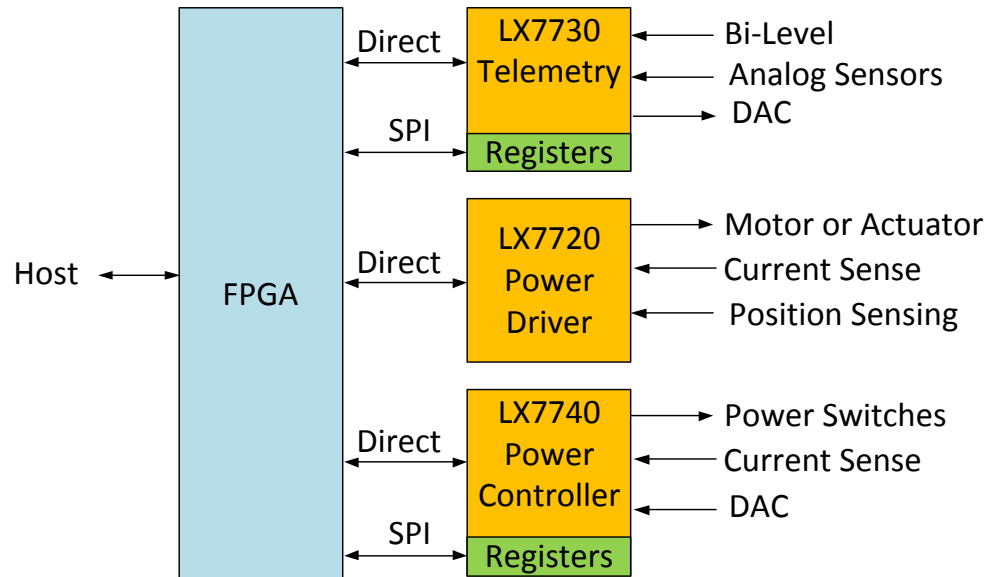
Space System Manager Concept

- Space System Manager (SSM) is a combination of an FPGA with a special purpose analog or power companion IC.
- The companion IC is intended to work with an FPGA
 - I/O levels and timing are compatible
 - The companion IC has a minimal amount of hard coded internal logic



Space System Manager Characteristics

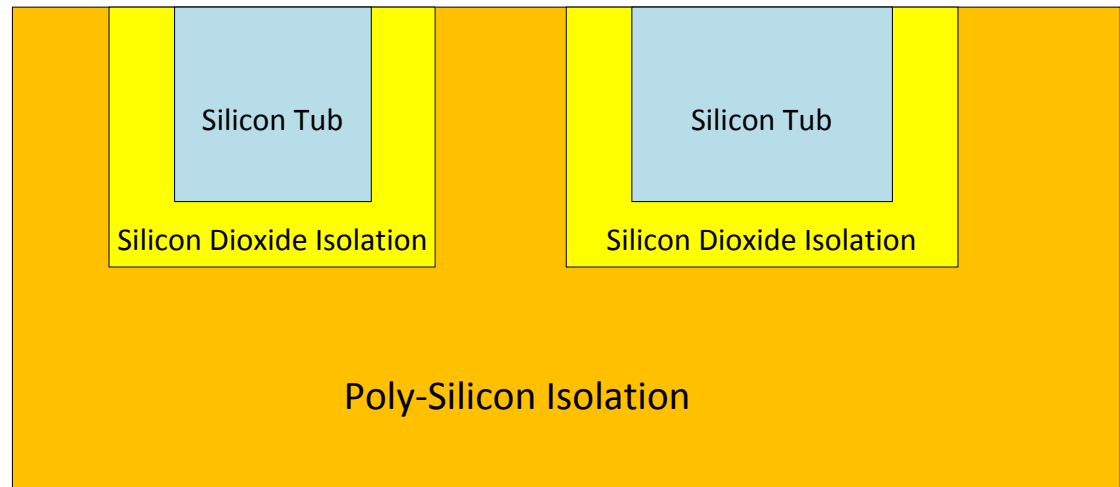
- Both the FPGA and the Companion IC are standard parts that are space qualified and DLA listed
- Companion IC standard attributes
 - Radiation Tolerant: 100krad TID; 50krad ELDRS, SE tolerant
 - Inputs are cold spared and dielectrically isolated
 - ESD and overvoltage clamping



IC Process for Fault Isolation

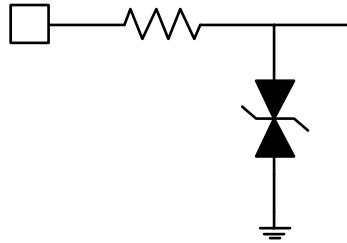
- The companion IC uses a special Dielectric Isolated (DI) process such that if any channel within the IC becomes compromised due to an external fault, the remaining IC continues to function normally
 - There is not a common substrate connection like is used with other IC processes
 - This process is similar in performance to the isolation achieved in Hybrid circuits
 - Isolation between tubs of at least 350V

Dielectric Isolation
Cross Section

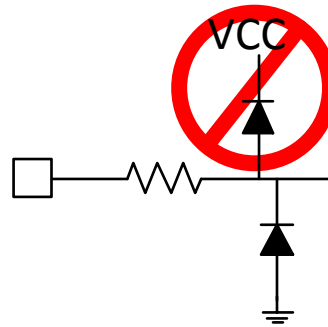


IC Process for Cold Sparing

- An isolated ESD structure for each Companion IC pin along with design techniques considering low leakage with power removed allows the companion IC to be cold spared (becomes a high impedance with the power removed)



Cold Sparing

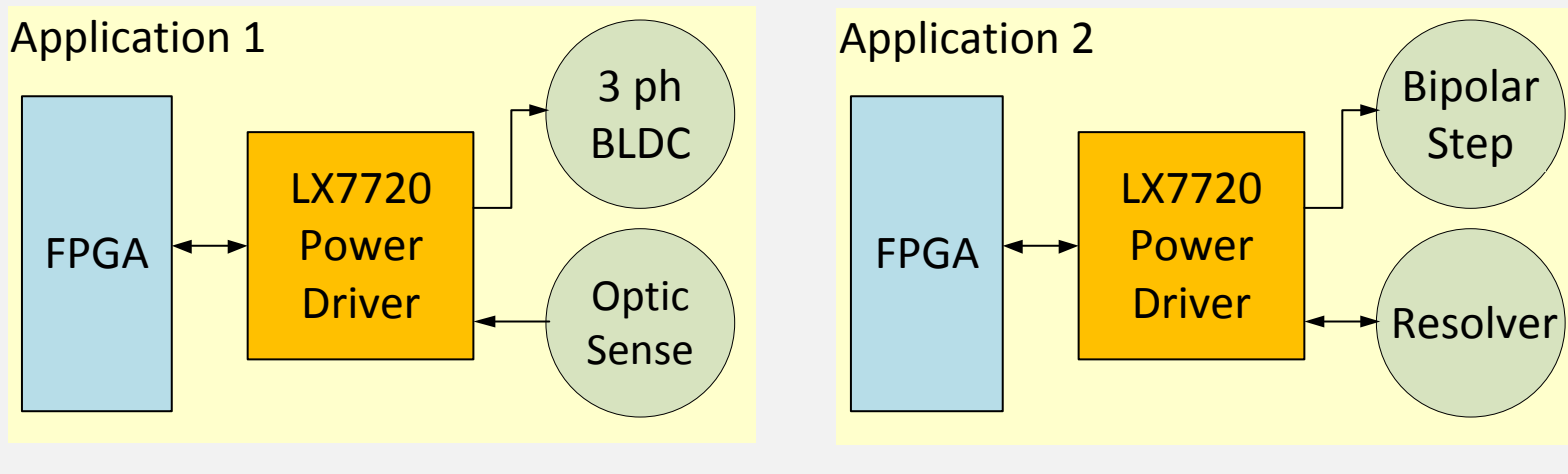


Typical ESD Protection

Companion IC Application Versatility

- Companion ICs exploit commonality between applications
 - Servo motor drivers require high power switches and position sensing
 - Telemetry monitoring requires an analog MUX, ADC and bi-level inputs

Different applications using the same IC part numbers.



System Manager System Integration

- FPGA HDL module examples are
 - Data sampling and logging
 - Motor micro-stepping
 - Brushless DC servo loop
 - Resolver to digital conversion
 - Sigma Delta filtering and dissemination
- Companion IC registers examples
 - Passive sensor drive current levels
 - ADC input range setting
 - MUX selection of inputs
- External Components adjust
 - External NMOS power sizing for motor drivers
 - Bi-level threshold levels

HDL Modules

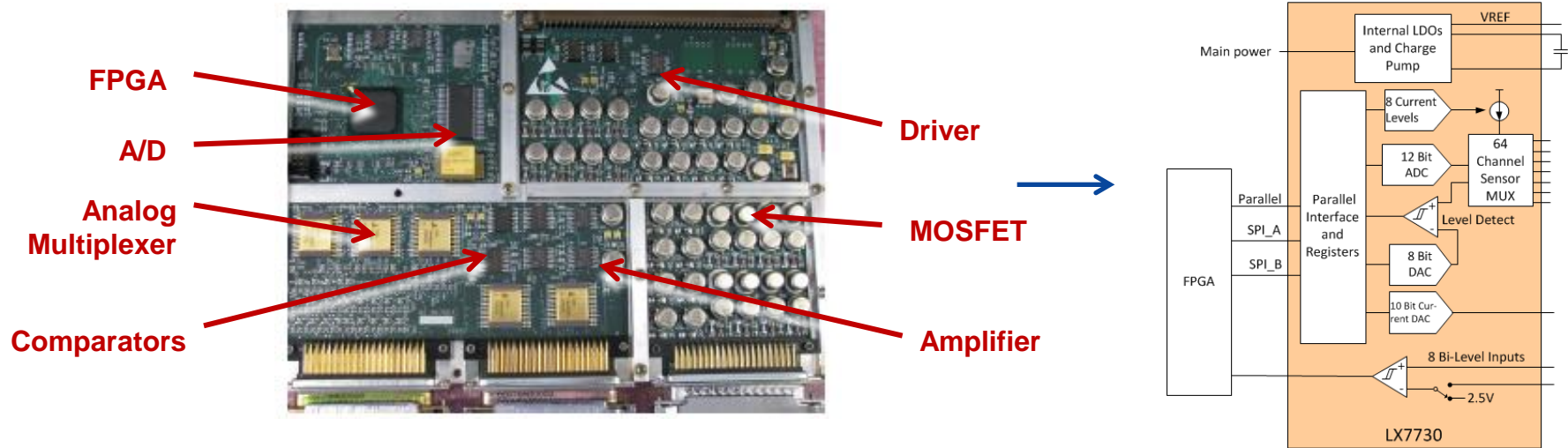
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Register Map

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Power Sizing &
Programming
Components

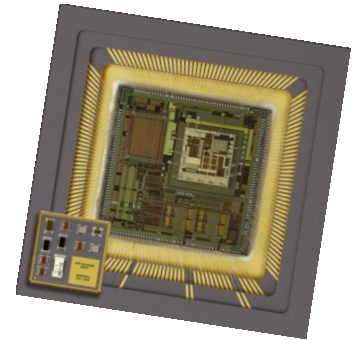
Approach Comparison - Discrete Components



- A typical circuit uses an FPGA with analog interface functions implemented with many single function ICs and discrete components
- Companion IC integrates commonly used functions into one package to reduce circuit board area and weight
- Although utilization may not be 100% for the space system manager, it is still likely to be a more compact solution

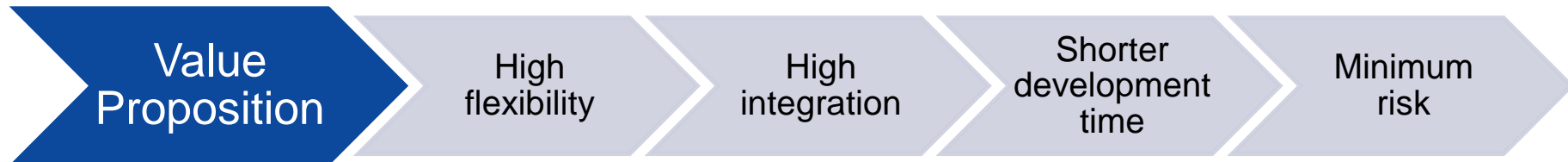
Approach Comparison - Custom ASIC

- The custom rad-hard mixed-signal solution provides an efficient solution but presents a number of challenges
 - Development Cost for a Mixed-Signal ASIC for Space applications is typically \$2M-\$4M
 - Development time typically of 2-4 man year.
 - Qualification is in excess of 1-2 year.
 - Time to production 4-5 years – very long R.O.I.
- Unlike the SSM, with a custom ASIC
 - Very few players are able to budget such development
 - Design to schedule and performance risk is usually high due to the high level of complexity associated with Rad Hard designs
 - The solution typically has minimal flexibility if requirements change



Reducing Risk While Maximizing Integration

| | Discrete Solution | Space System Manager | Custom ASIC Solution |
|------------------|-------------------|----------------------|----------------------|
| NRE | Low | Low | High |
| Development Time | Months | Months | Years |
| Qualification | Fast | Fast | Long |
| Risk | Small | Small | High |
| Flexibility | High | High | None |
| Power | Worst | Good | Best |
| Reliability | Average | Excellent | Excellent |
| Size and Weight | Poor | Good | Best |



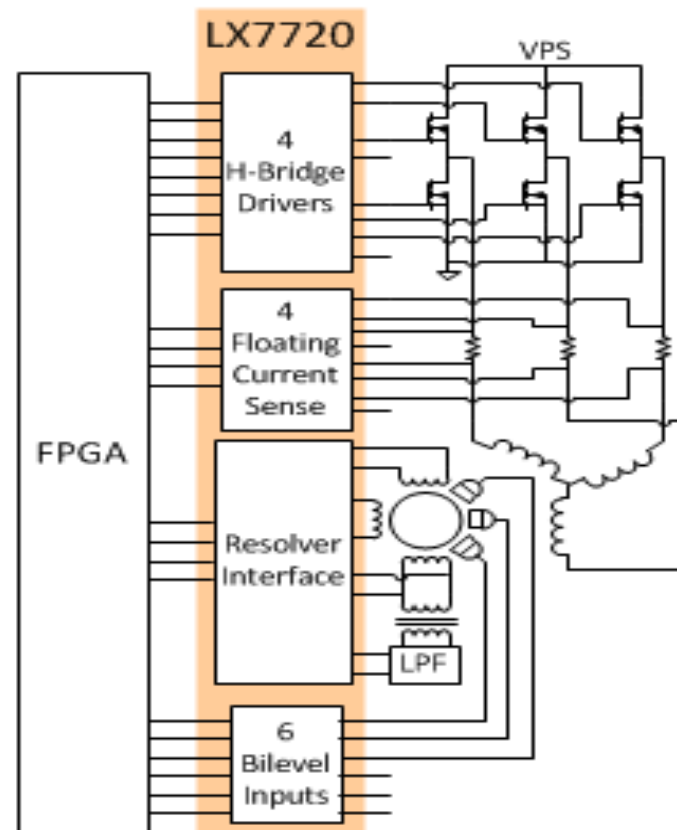
Companion ICs

- In Development
 - LX7720: Space Craft Power Driver with Rotation and Position Sensing
 - LX7730: 64 Analog Input Telemetry Controller

- In Definition Phase
 - LX7740: Power Sequencing and Management

LX7720 Power Driver w Position Feedback

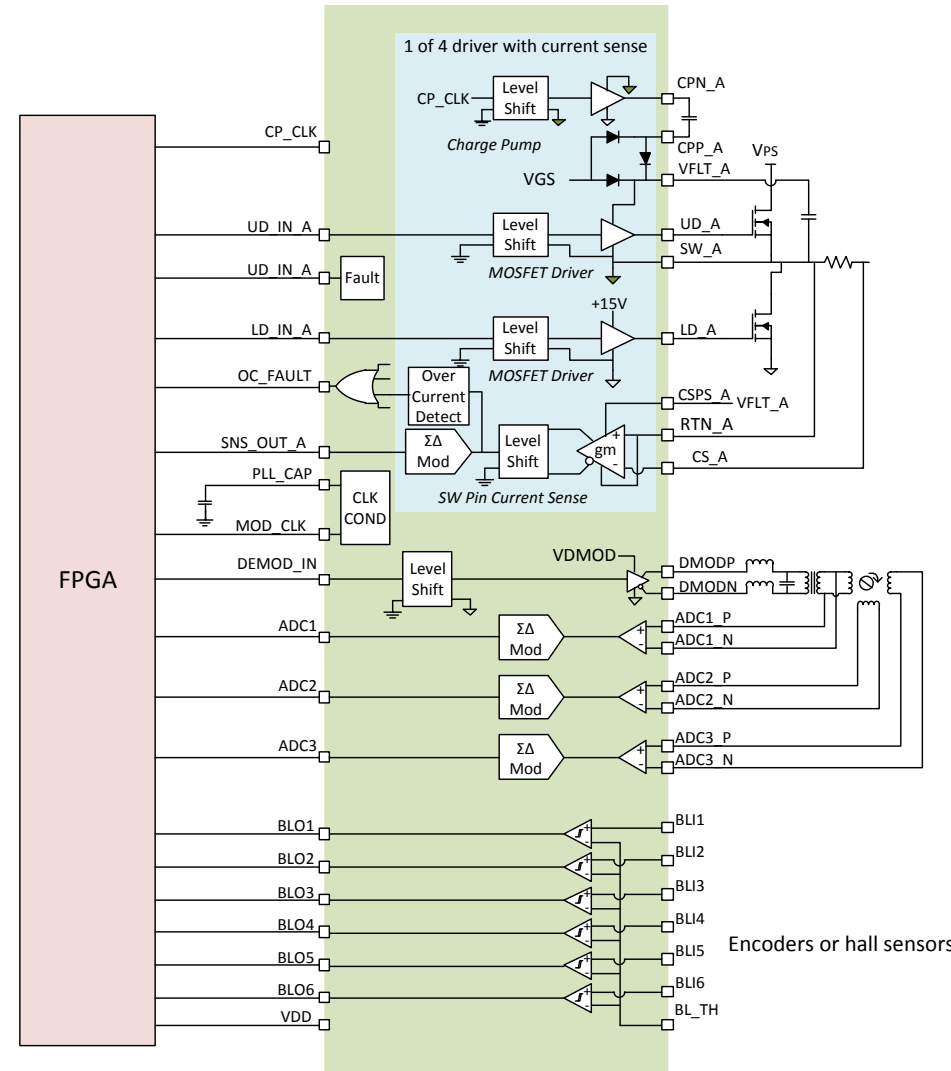
- Provides MOSFET motor drivers
 - 3 phase motors
 - Unipolar or bipolar steppers
- 4 high and low side relay drivers
- Up to 4 current sensors
 - In Line or to ground
 - Average current control loops
- Sensing for resolver or LVDT
- Detecting pulse sensors and limit switches



LX7720 Block Diagram

■ LX7720 Features

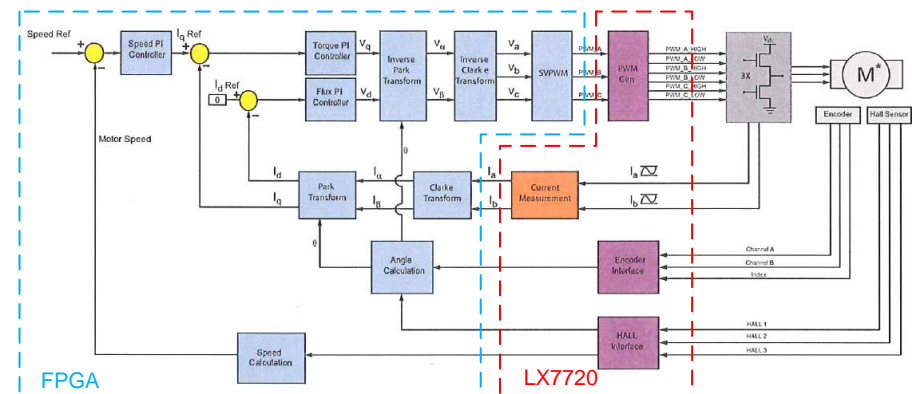
- Four H-Bridge Nch MOSFET drivers
- Four floating differential current sensors with $\Sigma\Delta$ modulated processed outputs to FPGA
- Pulse density modulated resolver exciter
- Three differential resolver sensors with $\Sigma\Delta$ modulated processed outputs to FPGA
- Six bi-level logic inputs
- 100V isolation FPGA-to-Motor



LX7720 HDL Module Tool Kit

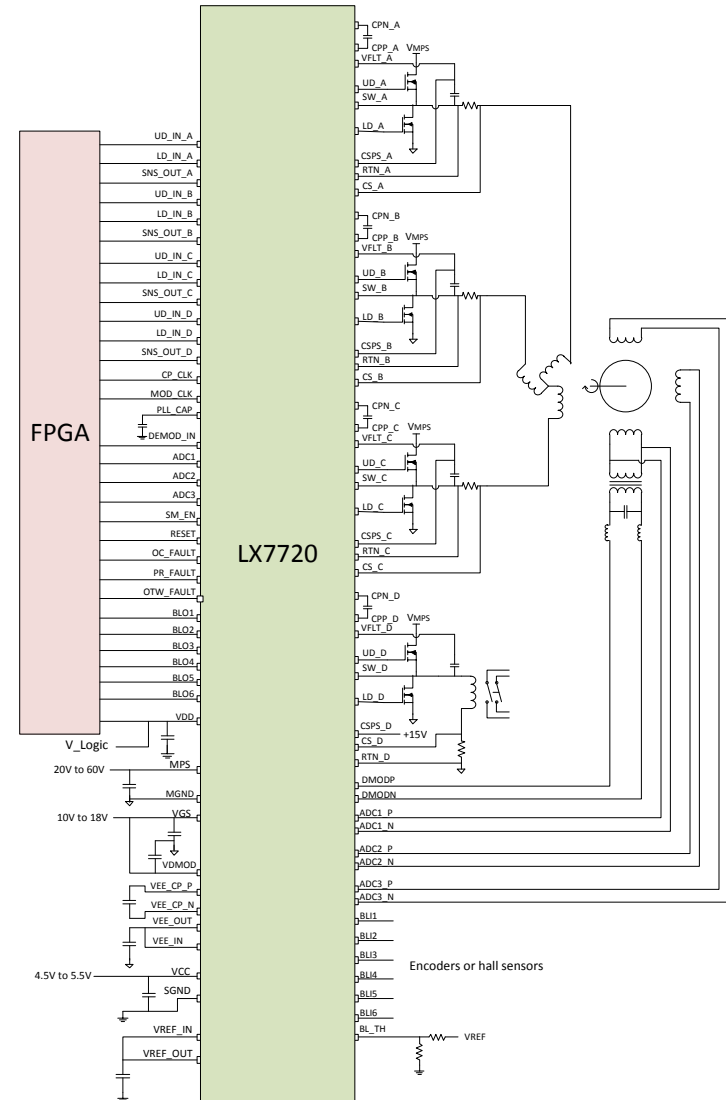
■ HDL Modules

- 2 phase bipolar drive with modes for cardinal steps, max torque and microstepping using average current regulation
- Sinc3 filter and disseminator with 7 to 14 bit ADC accuracy
- Pulse density exciter drive /tracking resolver-to-digital converter
- BLDC control with trapezoid drive
- PMSM control with sinusoidal drive
- Field oriented transformations
- Space vector modulation
- Fault management



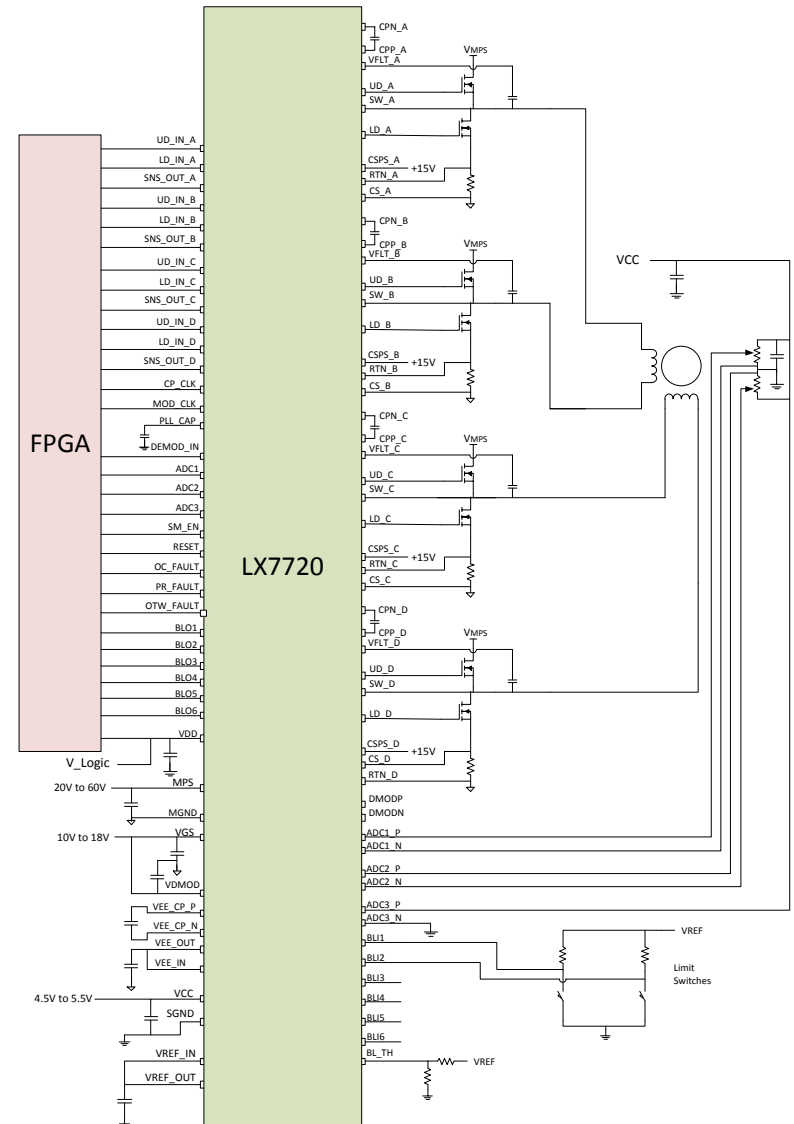
LX7720 PMSM Application

- Three phase PMSM motor
- Tracking resolver
- In line current sensing
- Phase D used for relay driver with current sense in return path



LX7720 Bipolar Microstepper

- Bipolar stepper motor
- Return path current sensing
- Potentiometer position sensing
- Limit switch sensing



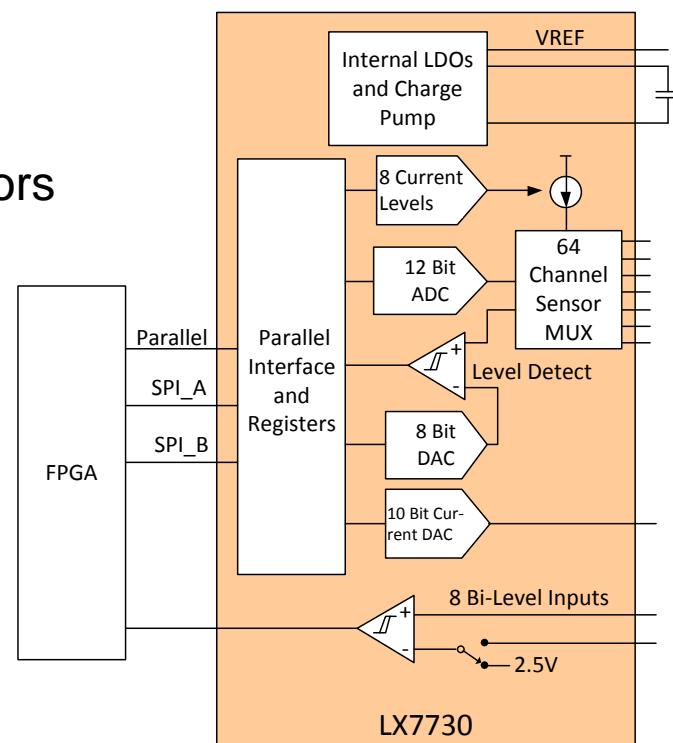
LX7720 Performance Highlights

- LX7720 Performance

| Parameter | Comment | Min | Typ | Max | Units |
|----------------------------|-----------------|------|-----|-----|----------|
| Motor Power Supply | De-rated by 20% | 20 | 48 | 80 | V |
| MOSFET driver impedance | Source or sink | | 1 | | Ω |
| PWM frequency | | DC | | 200 | kHz |
| Current sense range | | -250 | | 250 | mV |
| Current sense accuracy | | | 7 | | bits |
| Current sense latency | | | 4 | | μ S |
| Resolver carrier frequency | | 0.36 | | 20 | kHz |
| Resolver accuracy | | | 16 | | bits |
| Bi-level threshold range | | 0.5 | | 4.6 | V |
| Bi-level propagation delay | | | 1 | | us |

LX7730 64 Analog Input Telemetry Controller

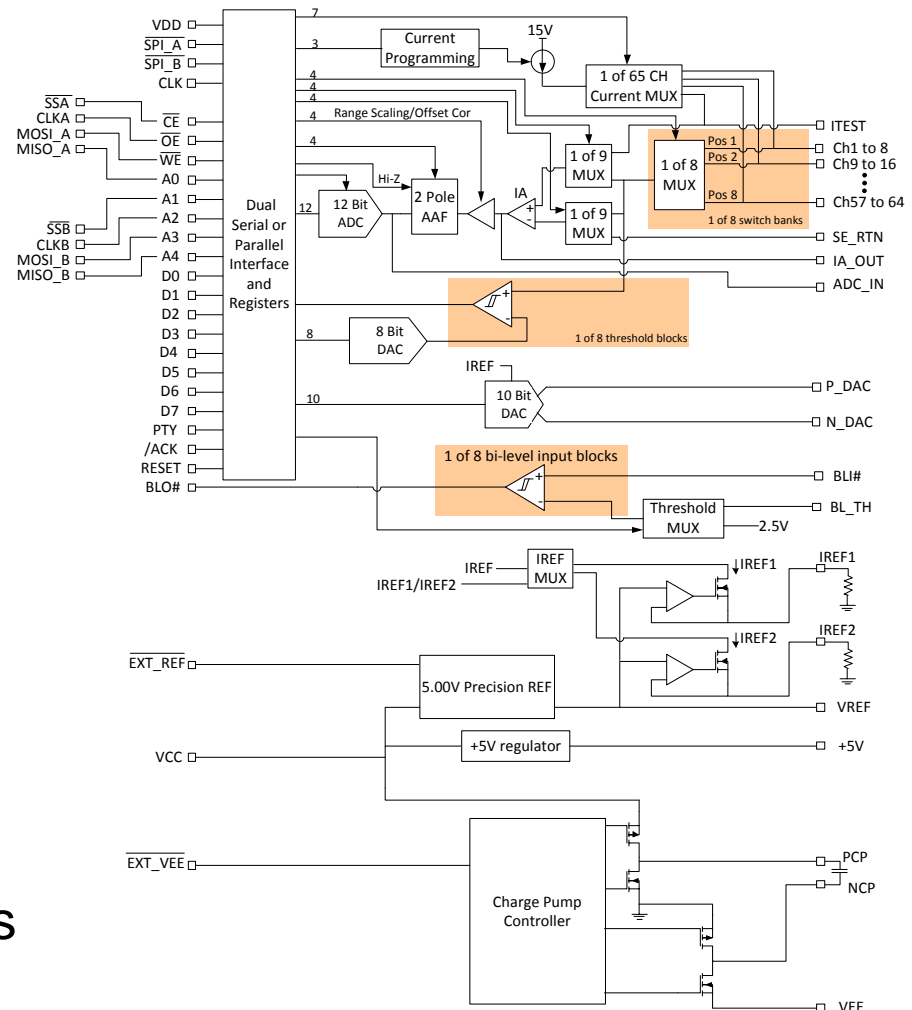
- Single ended sensing for 64 sensors with simultaneous monitoring of 8 sensors
- Differential (Kelvin) sensing of 32 sensors
- Current demux to any input for driving passive sensors
- Voltage reference to bias bridge networks
- ADC ranging accurately measures low level voltage changes
- DAC out for level control
- 8 bi-level logic translators



LX7730 Block Diagram

■ 64 universal General Purpose Sensor Interfaces

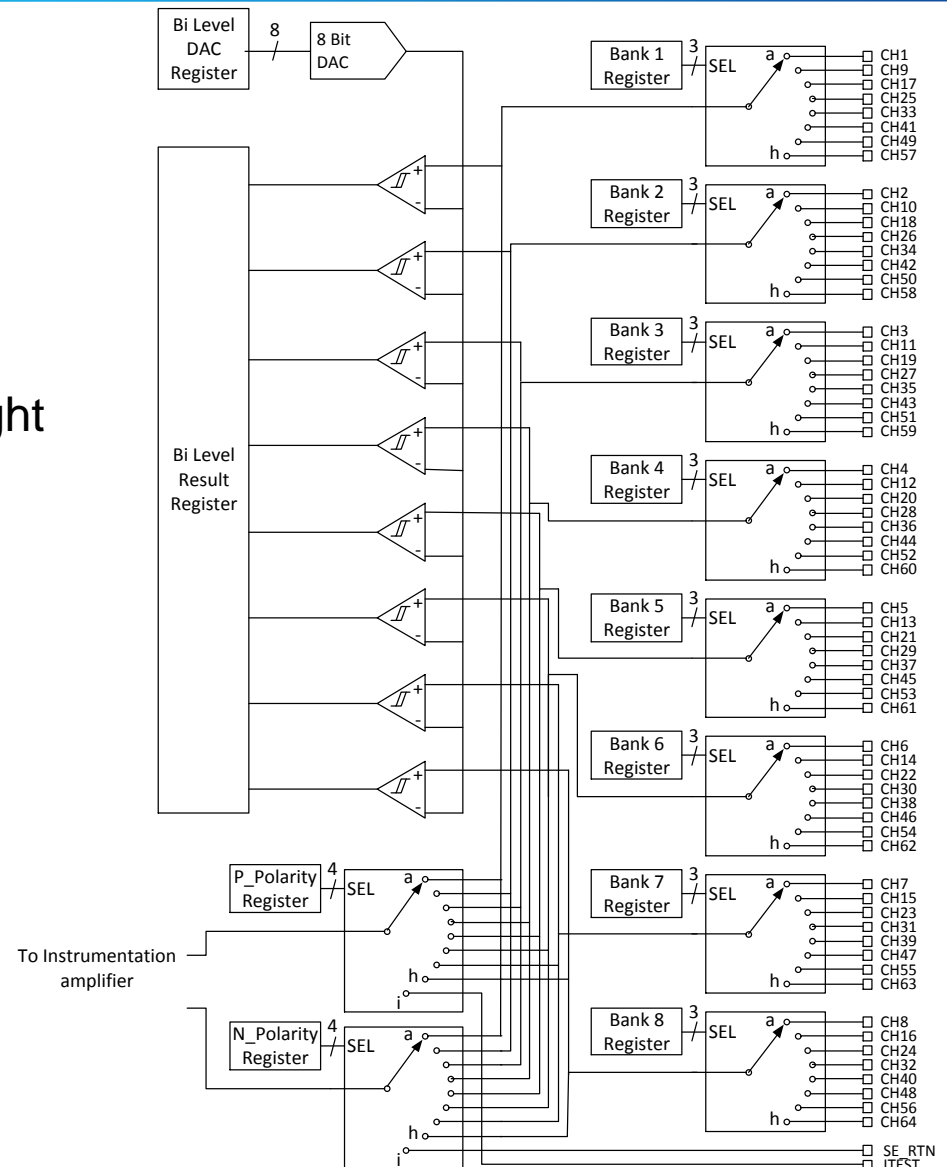
- 64 single ended or 32 differential
- ADC range scaling
- Level monitoring of 8 SE channels
- Make before break switching
- 100ksps 12 bit ADC
- Optional 2 pole anti-aliasing filter
- 8 fixed bi-level logic interfaces
 - Internal or external threshold setting
- 10 bit current DAC
 - Complementary outputs
- 1% precision reference
- 2% current references
- Parallel or Dual SPI interface
- Built in test and calibration
- +15 VCC input to internal regulators



LX7730 Switch Matrix

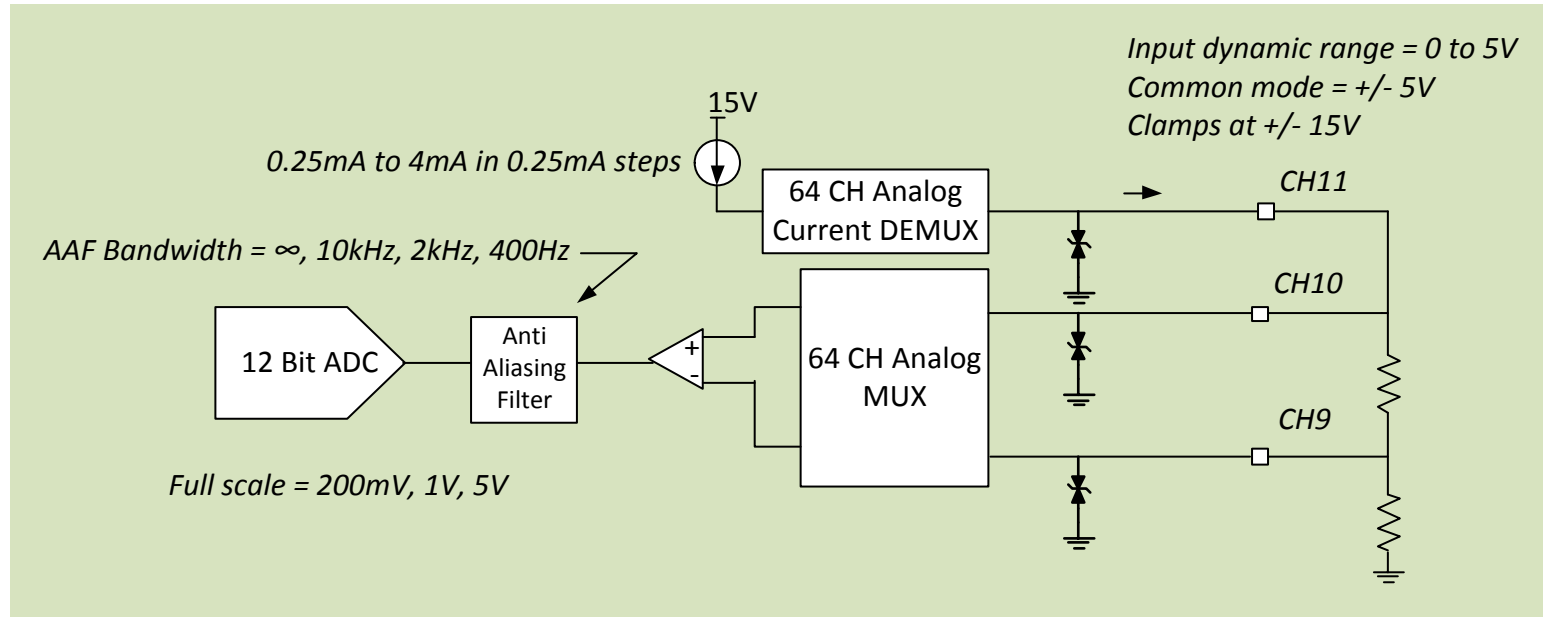
- Inputs are grouped in banks of 8.
- Differential measurements require inputs from 2 banks of 8
- SE_RTN input provides a common reference for up to 64 single ended measurements
- Simultaneous level monitoring for eight single ended inputs

| | Pos 1 | Pos 2 | Pos 3 | Pos 4 | Pos5 | Pos 6 | Pos 7 | Pos 8 |
|--------|-------|-------|-------|-------|------|-------|-------|-------|
| Bank 1 | CH1 | CH9 | CH17 | CH25 | CH33 | CH41 | CH49 | CH57 |
| Bank 2 | CH2 | CH10 | CH18 | CH26 | CH34 | CH42 | CH50 | CH58 |
| Bank 3 | CH3 | CH11 | CH19 | CH27 | CH35 | CH43 | CH51 | CH59 |
| Bank 4 | CH4 | CH12 | CH20 | CH28 | CH36 | CH44 | CH52 | CH60 |
| Bank 5 | CH5 | CH13 | CH21 | CH29 | CH37 | CH45 | CH53 | CH61 |
| Bank 6 | CH6 | CH14 | CH22 | CH30 | CH38 | CH46 | CH54 | CH62 |
| Bank 7 | CH7 | CH15 | CH23 | CH31 | CH39 | CH47 | CH55 | CH63 |
| Bank 8 | CH8 | CH16 | CH24 | CH32 | CH40 | CH48 | CH56 | CH64 |



LX7730 Current Source and Kelvin Sense

- Supports differential or single ended sensing
- Adjustable current source and DEMUX
- ADC range scaling
- Adjustable anti-aliasing filter



LX7730 HDL Module Tool Kit

■ HDL Modules

- Single register reads and writes
- Data logging loop
- Calibration
- SPI interface
- Parallel interface

LX7730 Direct Register Access

LX7730 Interface: ☐ SPIA ☒ SPIB ☐ Parallel

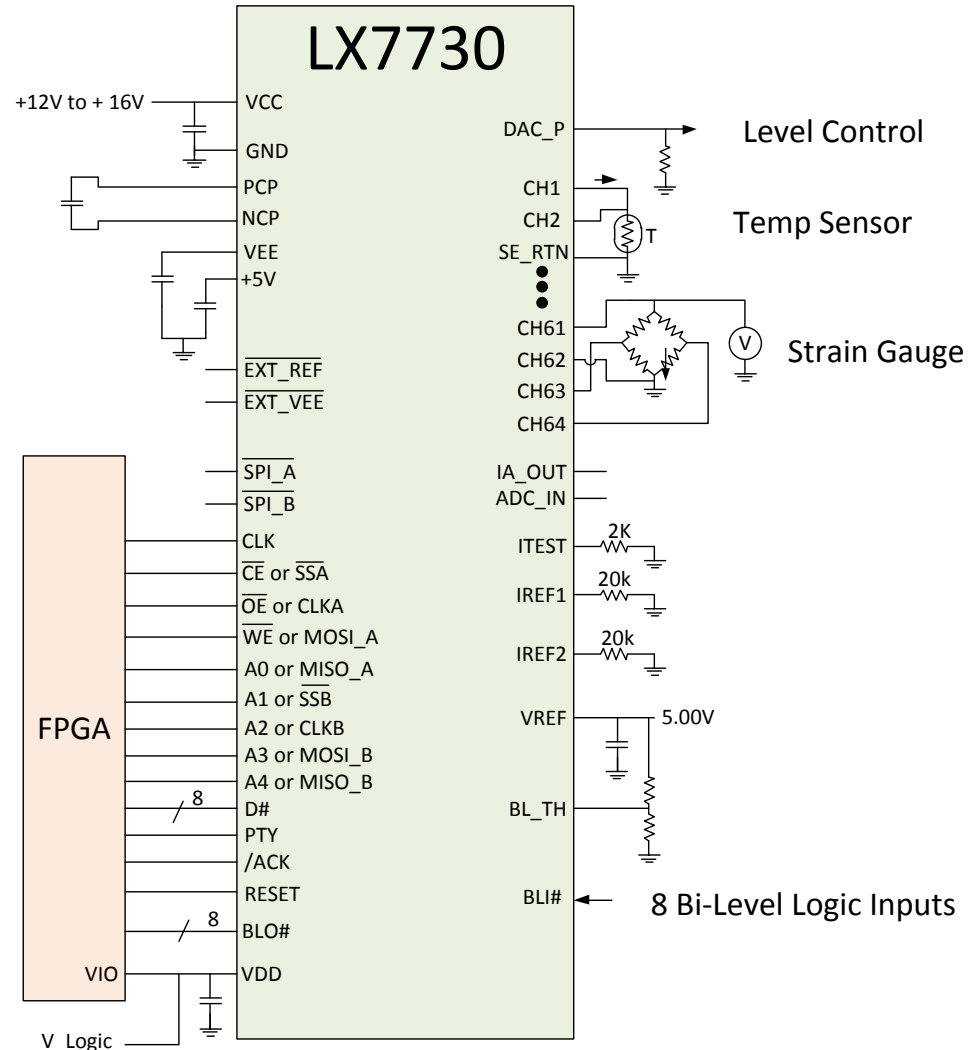
Parity Errors Detected:

| Register Map | Contents | New Value | |
|-----------------------------------|---------------------------------------|---------------------------------------|--------------------------------------|
| ADDR 0: Master Reset | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 1: Function Enable | <input type="text" value="11111111"/> | <input type="text" value="11111111"/> | <input type="button" value="Write"/> |
| ADDR 2: Power Status | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 3: Non-Inverting Chan Mux | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 4: Inverting Channel Mux | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 5: Current Source Level | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 6: Current Source DEMUX | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 7: Signal Conditioning Amp | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 8: ADC Control | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 9: ADC Upper Byte | <input type="text" value="00000000"/> | | |
| ADDR 10: ADC Lower Bits | <input type="text" value="00000000"/> | | |
| ADDR 11: Bi-Level Threshold DAC | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 12: Bi-Lvl Position and BLTH | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 13: Bi-Level Status | <input type="text" value="00000000"/> | | |
| ADDR 14: 10 Bit DAC Upper Byte | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 15: 10 Bit DAC Lower Bits | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 16: Calibration | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |
| ADDR 17: Power and Ref Adjust | <input type="text" value="00000000"/> | <input type="text" value="00000000"/> | <input type="button" value="Write"/> |

Fixed Bi-Level Input Status (BLO7 to BLO0):

LX7730 Application Figure

- Level control
- Temp sensors monitor
- Strain gauges monitor
- Bi-level logic translation



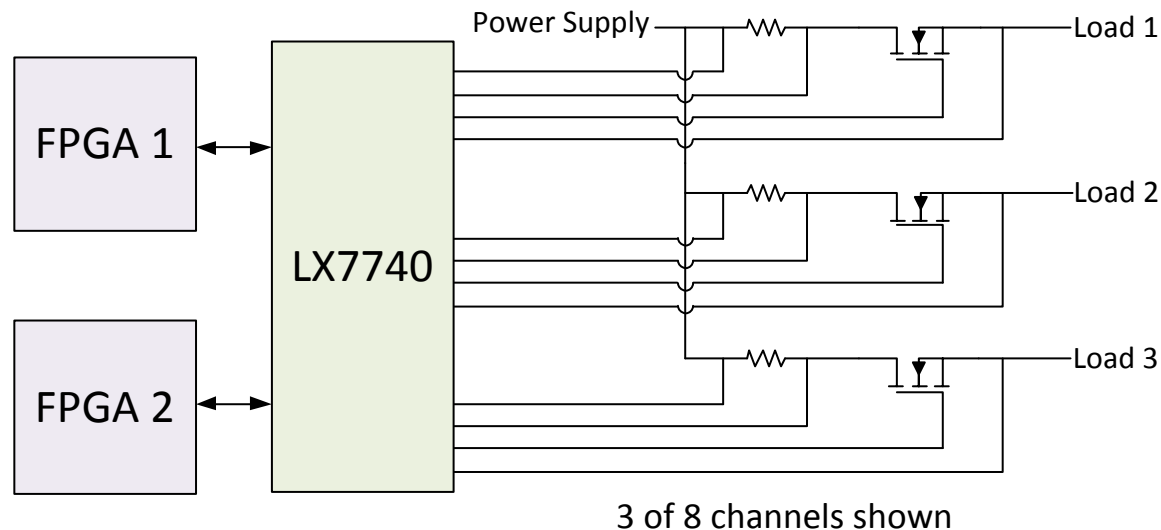
LX7730 Performance Highlights

■ LX7720 Performance

| Parameter | Comment | Min | Typ | Max | Units |
|--------------------------------------|-----------------|------|------|------|-------|
| SE or Diff sensor input | | 0 | | 5 | V |
| Differential Sensor common mode | | -5 | | 5 | V |
| ADC conversion rate | | | 100 | | kHz |
| ADC acquisition time | | | | 500 | ns |
| Reference voltage | Internal VREF | 4.95 | 5.00 | 5.05 | V |
| ADC non-linearity (integral or diff) | | -1 | 0 | 1 | LSB |
| MUX settling time | | | 1.5 | | us |
| MUX leakage current | Power on or off | -100 | | 100 | nA |
| Bi-level threshold range | | 0.5 | | 4.6 | V |
| Bi-level propagation delay | | | 1 | | us |
| DAC compliance range | | 0 | | 3.0 | V |
| DAC full scale current | Sourcing | 1.94 | 2.00 | 2.06 | mA |

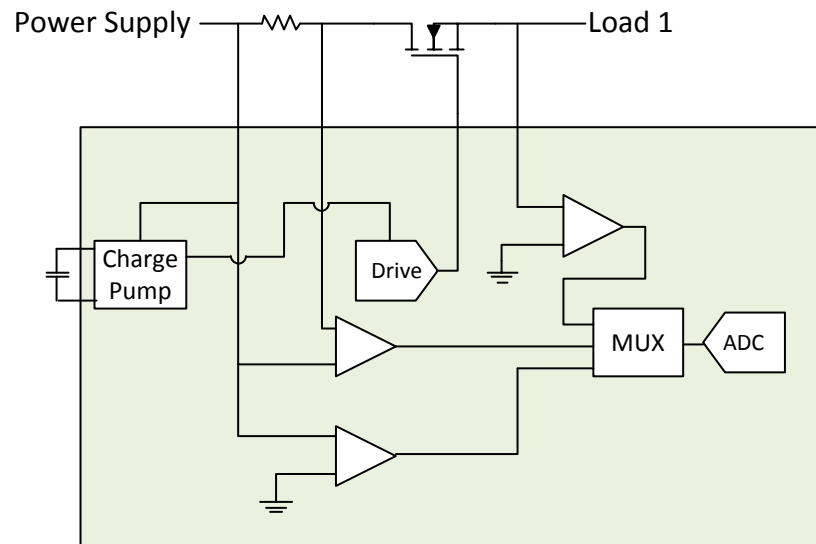
LX7740 Power Sequencing and Management

- Power Sequencing
 - Controls Ramp Rate and timing
 - Provides a clean power-up profile
- Power Management
 - Monitors analog voltage, current, temp
- Power Management
 - Fault detection and counter measures



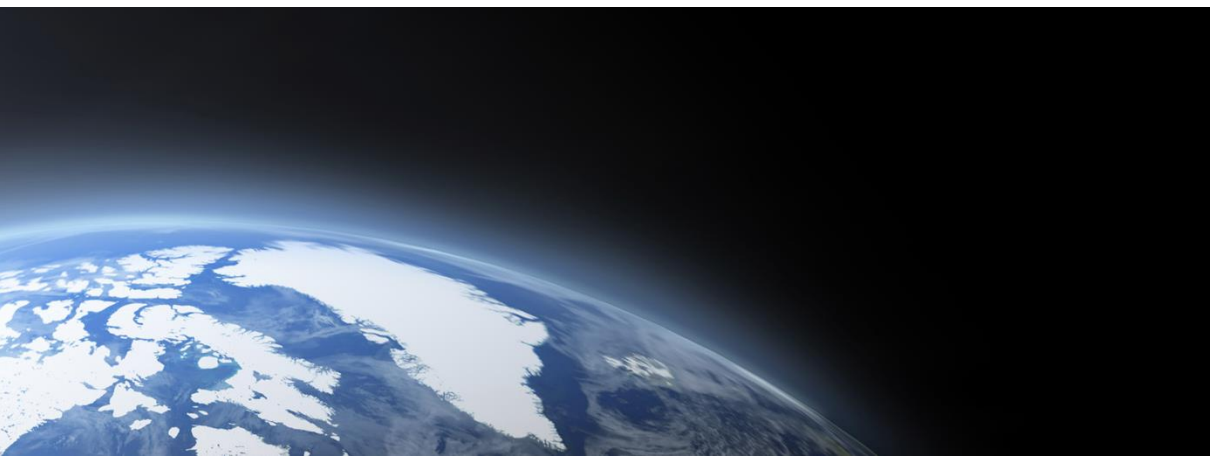
LX7740 Basic Element

- 8 Analog Quads
 - Monitor voltage, current temperature
 - Digital drive to ramp external switch
 - Charge pump provides V_{gs} for Nch switch full enhancement



Companion Chip Advantages Summary

- Companion IC
 - Provides a high level of integration (smaller size and weight).
 - Is a standard part so there is minimal design risk or qualification risk.
 - No hardware development NRE.
 - Designed to work with the FPGA so flexibility designed in.
 - Designed for space applications so additional buffers and level shifting are not necessary.
 - Radiation tolerance, TID > 100kRad; ELDRS > 50KRad; SEL tolerant
 - Cold spared
 - Fault tolerant



Thank You