AC492 Application Note Running BareMetal User Applications on PolarFire SoC FPGA





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Contents

	Revision History 1.1 Revision 2.0 1.2 Revision 1.0	. 1
	Running BareMetal User Applications on PolarFire SoC FPGA 2.1 Prerequisites	
3	Running the BareMetal User Applications 3.1 System Services 3.1.1 Running the System Service Application	. 3



Figures

Figure 1	Debug Configurations	3
Figure 2	Launching the Debugger	4
Figure 3	Confirm Perspective Switch Message	4
Figure 4	Resume Debugging	5
Figure 5	System Services Options	5
Figure 6	Read Device Serial Number	5
Figure 7	Read Device User-code	5
Figure 8	Read Device Design-info	5
Figure 9	Read Device Certificate	
Figure 10	Read Digest	7
Figure 11	Security Locks	
Figure 12	Read Debug Information	7
Figure 13	Digital Signature	8
Figure 14	PUF Emulation Service	8
Figure 15	Nonce Value	8



1 Revision History

The revision history describes the changes that were implemented in the document. The changes are listed by revision, starting with the most current publication.

1.1 Revision 2.0

Updated for Libero SoC v12.6.

1.2 Revision 1.0

The first publication of this document.



2 Running BareMetal User Applications on PolarFire SoC FPGA

Microchip's PolarFire[®] SoC FPGAs include industry's first RISC-V based Microprocessor Subsystem (MSS) and a fabric that inherits all the features of the PolarFire family. The PolarFire SoC MSS includes 5x 64-bit RISC-V processor cores, AXI Switch, DDR Controller, fabric Interface Controllers (FIC), and a rich set of peripherals. For more information about the PolarFire SoC MSS and its components, see *UG0880: PolarFire SoC FPGA MSS User Guide*. PolarFire SoC FPGAs are ideal for running BareMetal applications.

PolarFire SoC standalone MSS Configurator (no separate license required) facilitates independent configuration of MSS for use in Libero[®] SoC and SoftConsole. The standalone MSS configurator provides a seamless interface and can be used by Embedded Software developers and FPGA designers. For more information, see *PolarFire SoC Standalone MSS Configurator User Guide*. FPGA designers can add fabric components by using Libero SoC SmartDesign and IP Library.

Microchip's MPFS-ICICLE-KIT features the MPFS250T_ES SoC FPGA, a rich set of peripherals, ROM, and RAM options. For ROM requirement, the kit includes an 8 GB eMMC Flash memory. For external RAM requirement, the kit includes a 2 GB LPDDR4 device. The kit also features an SD Card slot. For more information, see *UG0882: PolarFire SoC FPGA ICICLE Kit User Guide*.

This application note describes how to run BareMetal user applications on MPFS-ICICLE-KIT.

2.1 **Prerequisites**

Before running the BareMetal user applications, the ICICLE kit must be programmed with the ICICLE reference design. Ensure to follow the documentation provided on *GitHub* and program the ICICLE kit reference design with one of the FlashPro Express programming files.



3 Running the BareMetal User Applications

Before you start, ensure to program the ICICLE KIT as described in Prerequisites. After successful programming, the following user applications can be run:

- System Services
- Single-Bit Error Detection and Correction for L2 LIM
- MicroPython

This document describes the steps to run the System Services application.

Note: For information about running other BareMetal user applications, see the *baremetal_applications GitHub* web page.

3.1 System Services

System Services SoftConsole project includes the following source files for running System Services:

- BareMetal MSS System Services driver which is available at the following location: https://github.com/polarfire-soc/polarfire-soc-bare-metal-library/tree/master/src/platform/driv-ers/mss_sys_services
- PolarFire SoC hardware abstraction layer source code (mpfs_hal). Using the mpfs_hal code, the user can access all of the PolarFire SoC MSS registers like E51 and U54 local interrupt registers, L2 cache, MPU, segmentation blocks, and others registers. This folder also includes the MSS peripherals base address file.
- **Note:** Hardware parameters like MSS clocks, memory, and peripheral source files are generated in SoftConsole using the MSS XML configuration file. The MSS XML configuration file is available at https://github.com/polarfire-soc/icicle-kit-reference-design/tree/master/XML.

3.1.1 Running the System Service Application

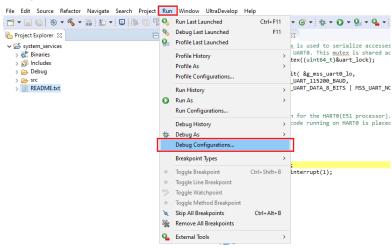
This section describes how to launch the System Services application in debug mode using SoftConsole and run the PolarFire SoC System Services via serial interface.

Note: This SoftConsole project can also be built in release mode and run from eNVM. Select Run > External Tools > PolarFire SoC program non secure boot mode 1 option to program the eNVM with the application and execute it.

To run the System Services:

- 1. Launch SoftConsole with the provided System Services project.
- 2. Click Run->Debug Configurations.

Figure 1 • Debug Configurations





- 3. In the Debug Configurations window, select the debug project highlighted in Figure 2.
- 4. Select the **Debug** option in the dialog box for launching the application in debug mode.

Figure 2 • Launching the Debugger

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	Name: system_services Debug			
ype filter text	🗎 Main 🔅 Debugger 🍉 Startup 🦆 S	Source 🔲 Common 🔀 SVD Path]	
C GDB OpenOCD Debugging	Project:			
🚜 Launch Group	system_services			Browse
Robot	C/C++ Application:			
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S UltraDevelop OCD	· · · · · · · · · · · · · · · · · · ·	Variables	Search Project	Browse
🄏 UltraDevelop Remote Target	Build (if required) before launching			
	Build Configuration: Select Automatically	/		~
	O Enable auto build	O Disable auto build		
	Use workspace settings	Configure Workspac		
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5. In the Confirm Perspective Switch window, click Switch to go to the debug view.

Figure 3 • Confirm Perspective Switch Message

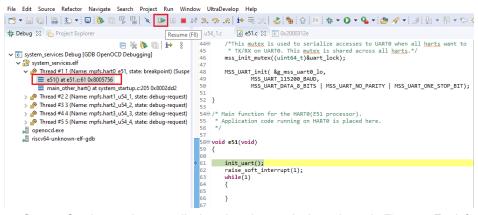
sc Con	firm Perspective Switch X		
?	This kind of launch is configured to open the Debug perspective when it suspends.		
	This Debug perspective is designed to support application debugging. It incorporates views for displaying the debug stack, variables and breakpoint management.		
	Do you want to switch to this perspective now?		
🗌 Ren	nember my decision Switch No		

The debugger stops at the <code>void e51 (void)</code> startup function in the <code>e51.c</code> file. This function initializes the UART interface and sends a software interrupt to the U54_1 processor core and releases it from the wait for interrupt mode (WFI). The <code>u54_1</code> hart starts executing the System Services functions.



6. Click Resume to start running System Services application as shown in Figure 4.

Figure 4 • Resume Debugging



7. System Services options are displayed on the terminal, as shown in Figure 5. For information about each System Service and output bit fields, see UG0905: PolarFire SoC FPGA System Services User Guide.



**** PolarFireSoC system services Example **** Notes: Return data from System controller is displayed byte-vise with LSB first Input data is provided LSB first. Each ASCII character is one Nibble of d ata
Select Service:
Device and Design Information Services:
1. Read Device Serial Number 2. Read Device User-code 3. Read Device Design-info 4. Read Device Design-info 5. Read Digest Certificate 5. Read Digest Security 6. Query Security 7. Read Debug Information Data Security Services:
8. Digital Signature 9. PUF Emulation a. Nonce

- 8. Enter 1 to select Read Device Serial Number.
 - The 128-bit Read Device Serial Number (DSN) is displayed, as shown in Figure 6.

Figure 6 • Read Device Serial Number

Device serial number: E24BABFEB7CA08B639F6FDB7D0E9EB45

Each PolarFire SoC FPGA device has a unique, publicly readable, 128-bit DSN. The DSN can be used in cryptographic protocols to uniquely identify the device. For more information, see *UG0918: PolarFire SoC FPGA Security User Guide*.

 Enter 2 to select Read Device User-code. This can be configured in the Libero SoC project from Design flow->Program Design->Configure Programming Options.

The 32-bit device USERCODE/Silicon signature is displayed, as shown in Figure 7.

Figure 7 • Read Device User-code

32bit USERCODE/Silicon signature (MSB first): ABCDEF01

- **Note:** In the Libero project, this USERCODE/silicon signature can be configured from Design flow->Program Design->Configure Programming Options. If the values are not entered, you can see zero.
 - 10. Enter 3 to select Read Device Design-info.
- Figure 8 Read Device Design-info

Design	ID:				
		000000000	000000000		
			000000000		
Design	Version:	0100			
Design	Back-Lev	el: 0000)		



The device design information consists of:

- 256-bit user-defined Design ID.
- 16-bit design version: This can be configured from Design flow->Program Design->Configure Programming Options. In auto update programming, the current design version is compared with the available images in external SPI flash to initiate the auto update on power up.
- 16-bit design back-level: This can be configured from Design flow->Program Design->Configure Security. When back level protection is enabled, the device can only be programmed if the target design version is more than the back-level value.
- 11. Enter 4 to select Read Device certificate.

The device supply chain assurance certificate is displayed, as shown in Figure 9.

Figure 9 • Read Device Certificate



The Device Certificate is a 1024 bytes Microsemi-signed X-509 certificate programmed during manufacturing. The certificate is used to guarantee the authenticity of a device and its characteristics.



12. Enter 5 to select Read Digest.

The 576 bytes Digest contains the fabric digest, sNVM digest, and user key digests. The digest protects data integrity. Figure 10 shows the 576 bytes digest.

Figure 10 • Read Digest



13. Enter 6 to select Query Security.

The non-volatile states of user security lock is displayed, as shown in Figure 11.

The design does not include any user security settings for device security. Security locks can be configured from Design flow->Program and Debug Design->Configure Security.

Figure 11 • Security Locks



14. Enter 7 to select Read Debug Information.

The debug information is displayed, as shown in Figure 12. In Figure 12, the highlighted 4 bytes E1000000 (LSB first) indicates the number of times the device was programmed (programming cycles).

Figure 12 • Read Debug Information

Debug info:
000000CE280021002300CF09C409CB09
0A07B902CC1900000000000000000000
C101C44C0171198AFF00FFFF00000000
0003FFFFCA00000044040000E1000000
0080781015D4B19C000000000000010010
FF3E00007E000300030000000000

15. Enter 8 to select Digital Signature.



The digital signature in both Raw and DER formats is displayed, as shown in Figure 13.

Figure 13 • Digital Signature

Digital Signature service: 48 byte hash value: 1850c211898959574808084B47DD499D 1CD655Dc4C188187F4CE5866265F689D 1850c2118989595748080084B47DD499D Raw format: Digital Signature service successful. Output Digital Signature - Raw format: FCFACE438477C71DC45E37A95C996FD4 223B044547B1C914B5800647PFFC1D13 865DB76095864B4C51975E8936725A45 3287F42FEDDAC4F6452P14151BD0C754 BF18Ea57D679579B1F6EF40733F9E40BA 7EEF45F2D33F562A99D5243B2ECA61A8 DER format: Digital Signature service successful. Output Digital Signature - DER format: 3066023100A83885070B274618CAF277 33B889C06A8B87E9D48D6515E61D22CE1 540251979A623190B9D457652591E 640251979A623190B9D245769CE911E 900C2125DFC2E777A052BB5AE5E77959 6418BB7005F2E289963A2E852643ACEA

The digital signature service takes a user supplied SHA384 hash and signs it with the devices private key. The application randomly generates the SHA384 hash value. The Digital Signature service sends the hash value to the System Controller. The System Controller Cryptoprocessor runs the Elliptic Curve Digital Signature Algorithm (ECDSA) using the hash and the device private key to generate the signature.

16. Enter 9 to select PUF Emulation service.

The PUF emulation service provides a mechanism for authenticating a device, or for generating a pseudo-random bit strings that can be used for different purposes. When this service is selected, the service by default accepts a 128-bit challenge and an 8-bit optype, and returns a 256-bit response unique to the challenge and the optype as shown in Figure 14.

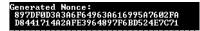
Figure 14 • PUF Emulation Service

The challenge OPTYPE range(0x0 to 0xFF): C8
16 byte challenge:
C8B02F4FB7F702B1A08AD1FECBACCC63
PUF emulation service successful.Generated Response:
23C8C11D424C6837C1DFCCBFAFE60D05
59C96927D179026E187E1B1FDE996DB6

17. Enter "a" to select Nonce service.

The 32 bytes nonce value is generated by the device as shown in Figure 15.

Figure 15 • Nonce Value



This concludes the running System Services application and the SoftConsole debug session can be terminated.