

# PolarFire FPGA Tcl Commands Reference Guide Libero SoC v12.1

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a  **MICROCHIP** company

**Microsemi Corporate  
Headquarters**

One Enterprise, Aliso Viejo,  
CA 92656 USA  
Within the USA: +1 (800) 713-4113  
Outside the USA: +1 (949) 380-6100  
Fax: +1 (949) 215-4996  
Email:  
[sales.support@microsemi.com](mailto:sales.support@microsemi.com)  
[www.microsemi.com](http://www.microsemi.com)

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# Introduction to Tcl Scripting

Tcl, the Tool Command Language, pronounced *tickle*, is an easy-to-learn scripting language that is compatible with Libero SoC software. You can run scripts from either the Windows or Linux command line or store and run a series of commands in a \*.tcl batch file.

This section provides a quick overview of the main features of Tcl:

- [Basic syntax](#)
- [Types of Tcl commands](#)
- [Variables](#)
- [Command substitution](#)
- [Quotes and braces](#)
- [Lists and arrays](#)
- [Control structures](#)
- [Print statement and Return values](#)

For complete information on Tcl scripting, refer to one of the books available on this subject. You can also find information about Tcl at web sites such as <http://www.tcl.tk>.

Libero SoC provides additional capabilities and built-in Tcl Commands:

- [Running Tcl scripts from the command line](#)
- [Exporting Tcl scripts](#)
- [extended\\_run\\_lib](#)
- Tcl Commands as specified in this document

## Tcl Commands and Supported Families

When we specify a family name, we refer to [the device family and all its derivatives](#), unless otherwise specified.

See Supported Families in the Tcl command help topics for the families supported for a specific Tcl command.

## Tcl Command Documentation Conventions

The following table shows the typographical conventions used for the Tcl command syntax.

| Syntax Notation                                   | Description                                                                                                                                                                                                                                                                                              |
|---------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| command -<br>argument                             | Commands and arguments appear in Courier New typeface.                                                                                                                                                                                                                                                   |
| <i>variable</i>                                   | <i>Variables appear in blue, italic Courier New typeface. You must substitute an appropriate value for the variable.</i>                                                                                                                                                                                 |
| [ <i>-argument</i> value]<br>[ <i>variable</i> ]+ | Optional arguments begin and end with a square bracket with one exception: if the square bracket is followed by a plus sign (+), then users must specify at least one argument. The plus sign (+) indicates that items within the square brackets can be repeated. Do not enter the plus sign character. |

**Note:** All Tcl commands are case sensitive. However, their arguments are not.

## Examples

Syntax for the `get_clocks` command followed by a sample command:

```
get_clocks variable
```

```
get_clocks clk1
```

Syntax for the `backannotate` command followed by a sample command:

```
backannotate -name file_name -format format_type -language language -dir directory_name [-netlist] [-pin]
```

```
backannotate -dir \
{..\design} -name "fanouttest_ba.sdf" -format "SDF" -language "VERILOG" \
-netlist
```

## Wildcard Characters

You can use the following wildcard characters in names used in Tcl commands:

| Wildcard | What it Does                                                                                                                       |
|----------|------------------------------------------------------------------------------------------------------------------------------------|
| \        | Interprets the next character literally                                                                                            |
| ?        | Matches any single character                                                                                                       |
| *        | Matches any string                                                                                                                 |
| [ ]      | Matches any single character among those listed between brackets (that is, [A-Z] matches any single character in the A-to-Z range) |

**Note:** The matching function requires that you add a slash (\) before each slash in the port, instance, or net name when using wildcards in a PDC command. For example, if you have an instance named "A/B12" in the netlist, and you enter that name as "A\\B\*" in a PDC command, you will not be able to find it. In this case, you must specify the name as A\\B\*.

## Special Characters [ ], { }, and \

Sometimes square brackets ([ ]) are part of the command syntax. In these cases, you must either enclose the open and closed square brackets characters with curly brackets ({ }) or precede the open and closed square brackets ([ ]) characters with a backslash (\). If you do not, you will get an error message.

For example:

```
pin_assign -port {LFSR_OUT[0]} -pin 15
or
pin_assign -port LFSR_OUT\[0\] -pin 180
```

**Note:** Tcl commands are case sensitive. However, their arguments are not.

## Entering Arguments on Separate Lines

To enter an argument on a separate line, you must enter a backslash (\) character at the end of the preceding line of the command as shown in the following example:

```
backannotate -dir \
{..\design} -name "fanouttest_ba.sdf" -format "SDF" -language "VERILOG" \
-netlist
```

### See Also

[Introduction to Tcl scripting](#)

[Basic syntax](#)

## Basic Syntax

Tcl scripts contain one or more commands separated by either new lines or semicolons. A Tcl command consists of the name of the command followed by one or more arguments. The format of a Tcl command is:

```
command arg1 ... argN
```

The command in the following example computes the sum of 2 plus 2 and returns the result, 4.

```
expr 2 + 2
```

The **expr** command handles its arguments as an arithmetic expression, computing and returning the result as a string. All Tcl commands return results. If a command has no result to return, it returns an empty string.

To continue a command on another line, enter a backslash (\) character at the end of the line. For example, the following Tcl command appears on two lines:

```
import -format "edif" -netlist_naming "Generic" -edif_flavor "GENERIC" {prepi.edn}
```

Comments must be preceded by a hash character (#). The comment delimiter (#) must be the first character on a line or the first character following a semicolon, which also indicates the start of a new line. To create a multi-line comment, you must put a hash character (#) at the beginning of each line.

**Note:** Be sure that the previous line does not end with a continuation character (\). Otherwise, the comment line following it will be ignored.

## Special Characters

Square brackets ([ ]) are special characters in Tcl. To use square brackets in names such as port names, you must either enclose the entire port name in curly braces, for example, `pin_assign -port {LFSR_OUT[15]} -iostd lvttl -slew High`, or lead the square brackets with a slash (/) character as shown in the following example:

```
pin_assign -port LFSR_OUT\[15\] -iostd lvttl -slew High
```

## Sample Tcl Script

```
#Create a new project and set up a new design
new_project -location {D:/2Work/my_pf_proj} -name {my_pf_proj} -project_description {} \
-block_mode 0 -standalone_peripheral_initialization 0 -use_enhanced_constraint_flow 1 \
-hdl {VERILOG} -family {PolarFire} -die {MPF300TS_ES} -package {FCG1152} -speed {-1} \
-die_voltage {1.0} -part_range {EXT} -adv_options {IO_DEFT_STD:LVCOS 1.8V} \
-adv_options {RESTRICTPROBEPINS:1} -adv_options {RESTRICTSPIPINS:0} \
-adv_options {SYSTEM_CONTROLLER_SUSPEND_MODE:1} -adv_options {TEMPR:EXT} \
-adv_options {VCCI_1.2_VOLTR:EXT} -adv_options {VCCI_1.5_VOLTR:EXT} \
-adv_options {VCCI_1.8_VOLTR:EXT} -adv_options {VCCI_2.5_VOLTR:EXT} \
-adv_options {VCCI_3.3_VOLTR:EXT} -adv_options {VOLTR:EXT}

#Import HDL source file
import_files -convert_EDN_to_HDL 0 -hdl_source {C:/test/prep1.v}

#Import HDL stimulus file
import_files -convert_EDN_to_HDL 0 -stimulus {C:/test/prep1tb.v}

#set the top level design name
set_root -module {prep1::work}

#Associate SDC constraint file to Place and Route tool
organize_tool_files -tool {PLACEROUTE} -file {D:/2Work/my_pf_proj/constraint/user.sdc} \
-module {prep1::work} -input_type {constraint}

#Associate SDC constraint file to Verify Timing tool
organize_tool_files -tool {VERIFYTIMING} -file
{D:/2Work/my_pf_proj/constraint/user.sdc} \
-module {prep1::work} -input_type {constraint}

#Run synthesize
```

```

run_tool -name {SYNTHESIZE}
#Configure Place and Route tool
configure_tool -name {PLACERROUTE} -params {DELAY_ANALYSIS:MAX} -params
{EFFORT_LEVEL:false}\
  -params {INCRPLACEANDROUTE:false} -params {MULTI_PASS_CRITERIA:VIOLATIONS}\
  -params {MULTI_PASS_LAYOUT:false} -params {NUM_MULTI_PASSES:5} -params {PDPR:false}\
  -params {RANDOM_SEED:0} -params {REPAIR_MIN_DELAY:false} -params
{SLACK_CRITERIA:WORST_SLACK} \
  -params {SPECIFIC_CLOCK:} -params {START_SEED_INDEX:1} -params
{STOP_ON_FIRST_PASS:false}\
  -params {TDPR:true}
#Run Place and Route
run_tool -name {PLACERROUTE}
#Configure Timing Report Generation
configure_tool -name {VERIFYTIMING} -run_tool -name {PLACERROUTE}params
{CONSTRAINTS_COVERAGE:1}\
  -params {FORMAT:XML} -params {MAX_TIMING_FAST_HV_LT:0} -params {MAX_TIMING_SLOW_LV_HT:1}
\
  -params {MAX_TIMING_SLOW_LV_LT:0} -params {MAX_TIMING_VIOLATIONS_FAST_HV_LT:0} \
  -params {MAX_TIMING_VIOLATIONS_SLOW_LV_HT:1} -params
{MAX_TIMING_VIOLATIONS_SLOW_LV_LT:0}\
  -params {MIN_TIMING_FAST_HV_LT:1} -params {MIN_TIMING_SLOW_LV_HT:0} -params
{MIN_TIMING_SLOW_LV_LT:0} -params {MIN_TIMING_VIOLATIONS_FAST_HV_LT:1} -params
{MIN_TIMING_VIOLATIONS_SLOW_LV_HT:0} \
  -params {MIN_TIMING_VIOLATIONS_SLOW_LV_LT:0}
#Run Verify Timing tool
run_tool -name {VERIFYTIMING}
#Run Power Verification tool
run_tool -name {VERIFYPOWER}
#Export bitstream
export_bitstream_file -file_name {prep1} \
  -export_dir {D:\2Work\my_pf_proj\designer\prep1\export} -format {STP} -master_file 0 \
  -master_file_components {} -encrypted_uk1_file 0 -encrypted_uk1_file_components {} \
  -encrypted_uk2_file 0 -encrypted_uk2_file_components {} \
  -trusted_facility_file 1 -trusted_facility_file_components {FABRIC}

```

## Types of Tcl commands

This section describes the following types of Tcl commands:

- [Built-in commands](#)
- [Procedures created with the proc command](#)

### Built-in commands

Built-in commands are provided by the Tcl interpreter. They are available in all Tcl applications. Here are some examples of built-in Tcl commands:

- Tcl provides several commands for manipulating file names, reading and writing file attributes, copying files, deleting files, creating directories, and so on.
- exec - run an external program. Its return value is the output (on stdout) from the program, for example:

```

set tmp [ exec myprog ]
puts stdout $tmp

```

- You can easily create collections of values (lists) and manipulate them in a variety of ways.
- You can create arrays - structured values consisting of name-value pairs with arbitrary string values for the names and values.
- You can manipulate the time and date variables.

- You can write scripts that can wait for certain events to occur, such as an elapsed time or the availability of input data on a network socket.

## Procedures created with the proc command

You use the `proc` command to declare a procedure. You can then use the name of the procedure as a Tcl command.

The following sample script consists of a single command named **proc**. The `proc` command takes three arguments:

- The name of a procedure (`myproc`)
- A list of argument names (`arg1 arg2`)
- The body of the procedure, which is a Tcl script

```
proc myproc { arg1 arg2 } {
  # procedure body
}
myproc a b
```

## Variables

With Tcl scripting, you can store a value in a variable for later use. You use the `set` command to assign variables. For example, the following `set` command creates a variable named `x` and sets its initial value to 10.

```
set x 10
```

A variable can be a letter, a digit, an underscore, or any combination of letters, digits, and underscore characters. All variable values are stored as strings.

In the Tcl language, you do not declare variables or their types. Any variable can hold any value. Use the dollar sign (\$) to obtain the value of a variable, for example:

```
set a 1
set b $a
set cmd expr
set x 11
$cmd $x*$x
```

The dollar sign \$ tells Tcl to handle the letters and digits following it as a variable name and to substitute the variable name with its value.

## Global Variables

Variables can be declared global in scope using the Tcl `global` command. All procedures, including the declaration can access and modify global variables, for example:

```
global myvar
```

## Command substitution

By using square brackets ([ ]), you can substitute the result of one command as an argument to a subsequent command, as shown in the following example:

```
set a 12
set b [expr $a*4]
```

Tcl handles everything between square brackets as a nested Tcl command. Tcl evaluates the nested command and substitutes its result in place of the bracketed text. In the example above, the argument that appears in square brackets in the second `set` command is equal to 48 (that is,  $12 * 4 = 48$ ).

Conceptually,

```
set b [expr $a * 4]
```

expands to

```
set b [expr 12 * 4 ]
```

and then to

```
set b 48
```

## Quotes and braces

The distinction between braces ({} ) and quotes (" ") is significant when the list contains references to variables. When references are enclosed in quotes, they are substituted with values. However, when references are enclosed in braces, they are not substituted with values.

Example

| With Braces                  | With Double Quotes           |
|------------------------------|------------------------------|
| set b 2                      | set b 2                      |
| set t { 1 \$b 3 }            | set t " 1 \$b 3 "            |
| set s { [ expr \$b + \$b ] } | set s " [ expr \$b + \$b ] " |
| puts stdout \$t              | puts stdout \$t              |
| puts stdout \$s              | puts stdout \$s              |

will output

```
1 $b 3
[ expr $b + $b ]
```

vs.

```
1 2 3
4
```

## Filenames

In Tcl syntax, filenames should be enclosed in braces {} to avoid backslash substitution and white space separation. Backslashes are used to separate folder names in Windows-based filenames. The problem is that sequences of "\n" or "\t" are interpreted specially. Using the braces disables this special interpretation and specifies that the Tcl interpreter handle the enclosed string literally. Alternatively, double-backslash "\\n" and "\\t" would work as well as forward slash directory separators "/" and "/t". For example, to specify a file on your Windows PC at c:\newfiles\thisfile.adb, use one of the following:

```
{C:\newfiles\thisfile.adb}
C:\\newfiles\\thisfile.adb
"C:\\newfiles\\thisfile.adb"
C:/newfiles/thisfile.adb
"C:/newfiles/thisfile.adb"
```

If there is white space in the filename path, you must use either the braces or double-quotes. For example:

```
C:\program data\thisfile.adb
```

should be referenced in Tcl script as

```
{C:\program data\thisfile.adb} or "C:\\program data\\thisfile.adb"
```

If you are using variables, you cannot use braces {} because, by default, the braces turn off all special interpretation, including the dollar sign character. Instead, use either double-backslashes or forward slashes with double quotes. For example:

```
"$design_name.adb"
```

**Note:** To use a name with special characters such as square brackets [], you must put the entire name between curly braces {} or put a slash character \ immediately before each square bracket.

The following example shows a port name enclosed with curly braces:

```
pin_assign -port {LFSR_OUT[15]} -iostd lvttl -slew High
```

The next example shows each square bracket preceded by a slash:

```
pin_assign -port LFSR_OUT\[15\] -iostd lvttl -slew High
```

## Lists and arrays

A list is a way to group data and handle the group as a single entity. To define a list, use curly braces { } and double quotes ". For example, the following set command {1 2 3 }, when followed by the list command, creates a list stored in the variable "a." This list will contain the items "1," "2," and "3."

```
set a { 1 2 3 }
```

Here's another example:

```
set e 2
set f 3
set a [ list b c d [ expr $e + $f ] ]
puts $a
```

displays (or outputs):

```
b c d 5
```

Tcl supports many other list-related commands such as lindex, linsert, llength, lrange, and lappend. For more information, refer to one of the books or web sites available on this subject.

## Arrays

An array is another way to group data. Arrays are collections of items stored in variables. Each item has a unique address that you use to access it. You do not need to declare them nor specify their size.

Array elements are handled in the same way as other Tcl variables. You create them with the set command, and you can use the dollar sign (\$) for their values.

```
set myarray(0) "Zero"
set myarray(1) "One"
set myarray(2) "Two"
for {set i 0} {$i < 3} {incr i 1} {
```

Output:

```
Zero
One
Two
```

In the example above, an array called "myarray" is created by the set statement that assigns a value to its first element. The for-loop statement prints out the value stored in each element of the array.

## Special arguments (command-line parameters)

You can determine the name of the Tcl script file while executing the Tcl script by referring to the \$argv0 variable.

```
puts "Executing file $argv0"
```

To access other arguments from the command line, you can use the lindex command and the argv variable:

To read the the Tcl file name:

```
lindex $argv 0
```

To read the first passed argument:

```
lindex $argv 1
```

Example

```
puts "Script name is $argv0" ; # accessing the scriptname
puts "first argument is [lindex $argv 0]"
puts "second argument is [lindex $argv 1]"
puts "third argument is [lindex $argv 2]"
puts "number of argument is [llength $argv]"
set des_name [lindex $argv 0]
puts "Design name is $des_name"
```

## Control structures

Tcl control structures are commands that change the flow of execution through a script. These control structures include commands for conditional execution (if-then-elseif-else) and looping (while, for, catch).

An "if" statement only executes the body of the statement (enclosed between curly braces) if the Boolean condition is found to be true.

### if/else statements

```
if { "$name" == "paul" } then {
...
# body if name is paul
} elseif { $code == 0 } then {
...
# body if name is not paul and if value of variable code is zero
} else {
...
# body if above conditions is not true
}
```

### for loop statement

A "for" statement will repeatedly execute the body of the code as long as the index is within a specified limit.

```
for { set i 0 } { $i < 5 } { incr i } {
...
# body here
}
```

### while loop statement

A "while" statement will repeatedly execute the body of the code (enclosed between the curly braces) as long as the Boolean condition is found to be true.

```
while { $p > 0 } {
...
}
```

### catch statement

A "catch" statement suspends normal error handling on the enclosed Tcl command. If a variable name is also used, then the return value of the enclosed Tcl command is stored in the variable.

```
catch { open "$inputFile" r } myresult
```

## Print statement and Return values

### Print Statement

Use the puts command to write a string to an output channel. Predefined output channels are "stdout" and "stderr." If you do not specify a channel, then puts display text to the stdout channel.

**Note:** The STDIN Tcl command is not supported by Microsemi SoC tools.

Example:

```
set a [ myprog arg1 arg2 ]
puts "the answer from myprog was $a (this text is on stdout)"
puts stdout "this text also is on stdout"
```

## Return Values

The return code of a Tcl command is a string. You can use a return value as an argument to another function by enclosing the command with square brackets [ ].

Example:

```
set a [ prog arg1 arg2 ]
exec $a
```

The Tcl command “exec” will run an external program. The return value of “exec” is the output (on stdout) from the program.

Example:

```
set tmp [ exec myprog ]
puts stdout $tmp
```

## Exporting Tcl Scripts

You can write out a Tcl script file that contains the commands executed in the current session. You can then use this exported Tcl script to re-execute the same commands interactively or in batch. You can also use this exported script to become more familiar with Tcl syntax.

You can export Tcl scripts from the Project Manager.

**To export a Tcl session script from the Project Manager:**

1. From the **File** menu, choose **Export Script File**. The **Export Script** dialog box appears.
2. Click **OK**. The **Script Export Options** dialog box appears:

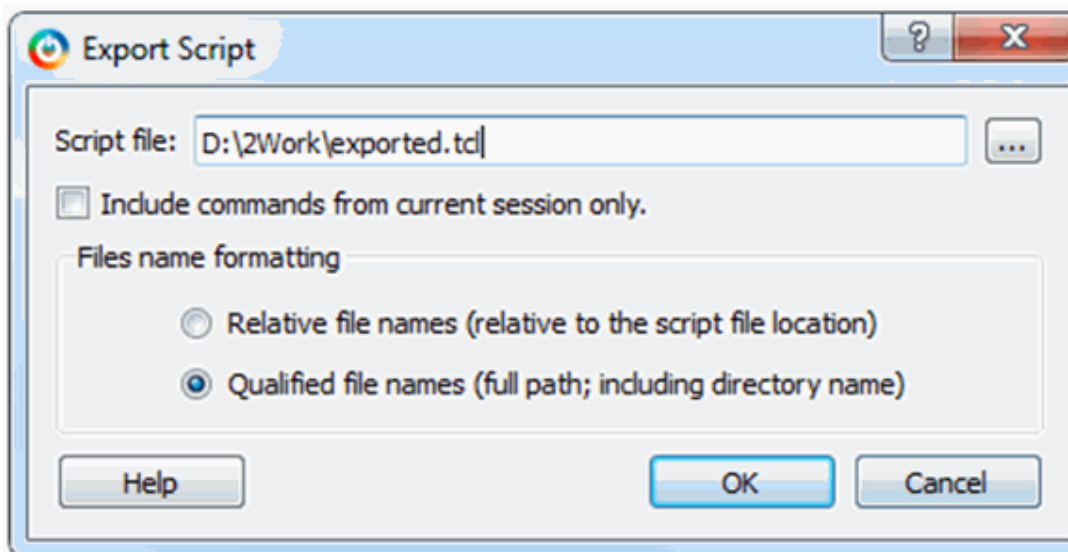


Figure 1 · Script Export Options

3. Check the **Include Commands from Current Design [Project] Only** checkbox. This option applies only if you opened more than one design or project in your current session. If so, and you do not check this box, Project Manager exports all commands from your current session.
4. Select the radio button for the appropriate filename formatting. To export filenames relative to the current working directory, select **Relative filenames (default)** formatting. To export filenames that include a fully specified path, select **Qualified filenames (full path; including directory name)** formatting.

Choose **Relative filenames** if you do not intend to move the Tcl script from the saved location, or **Qualified filenames** if you plan to move the Tcl script to another directory or machine.

5. Click **OK**.

Project Manager saves the Tcl script with the specified filename.

**Note:**

- When exporting Tcl scripts, Project Manager always encloses filenames in curly braces to ensure portability.
- Libero SoC software does not write out any Tcl variables or flow-control statements to the exported Tcl file, even if you had executed the design commands using your own Tcl script. The exported Tcl file only contains the tool commands and their accompanying arguments.

## extended\_run\_lib

**Note:** This is not a Tcl command; it is a shell script that can be run from the command line.

The extended\_run\_lib Tcl script enables you to run the multiple pass layout in batch mode from a command line.

```
$ACTEL_SW_DIR/bin/libero script:$ACTEL_SW_DIR/scripts/extended_run_lib.tcl
logfile:extended_run.log "script_args:-root path/designer/module_name [-n numPasses] [-
starting_seed_index numIndex] [-compare_criteria value] [-c clockName] [-analysis value] [-
slack_criteria value] [-stop_on_success] [-timing_driven|standard] [-power_driven value]
[-placer_high_effort value]"
```

**Note:**

- There is no option to save the design files from all the passes. Only the (Timing or Power) result reports from all the passes are saved.

## Arguments

-root path/designer/module\_name

The path to the root module located under the designer directory of the Libero project.

[-n numPasses]

Sets the number of passes to run. The default number of passes is 5.

[-starting\_seed\_index numIndex]

Indicates the specific index into the array of random seeds which is to be the starting point for the passes. Value may range from 1 to 100. If not specified, the default behavior is to continue from the last seed index that was used.

[-compare\_criteria value]

Sets the criteria for comparing results between passes. The default value is set to frequency when the -c option is given or timing constraints are absent. Otherwise, the default value is set to violations.

| Value      | Description                                                                                                                                                                                            |
|------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| frequency  | Use clock frequency as criteria for comparing the results between passes. This option can be used in conjunction with the -c option (described below).                                                 |
| violations | Use timing violations as criteria for comparing the results between passes. This option can be used in conjunction with the -analysis, -slack_criteria and -stop_on_success options (described below). |
| power      | Use total power as criteria for comparing the results between passes, where lowest total power is the goal.                                                                                            |

[-c clockName]

Applies only when the clock frequency comparison criteria is used. Specifies the particular clock that is to be examined. If no clock is specified, then the slowest clock frequency in the design in a given pass is used. The clock name should match with one of the Clock Domains in the Summary section of the Timing report.

[-analysis value]

Applies only when the timing violations comparison criteria is used. Specifies the type of timing violations (the slack) to examine. The following table shows the acceptable values for this argument:

| Value | Description                                                                                   |
|-------|-----------------------------------------------------------------------------------------------|
| max   | Examines timing violations (slack) obtained from maximum delay analysis. This is the default. |
| min   | Examines timing violations (slack) obtained from minimum delay analysis.                      |

`[-slack_criteria value]`

Applies only when the timing violations comparison criteria is used. Specifies how to evaluate the timing violations (slack). The type of timing violations (slack) is determined by the -analysis option. The following table shows the acceptable values for this argument:

| Value | Description                                                                                                                                                                                                                                                                                                                                        |
|-------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| worst | Sets the timing violations criteria to Worst slack. For each pass obtains the most amount of negative slack (or least amount of positive slack if all constraints are met) from the timing violations report. The largest value out of all passes will determine the best pass. This is the default.                                               |
| tns   | Sets the timing violations criteria to Total Negative Slack (tns). For each pass it obtains the sum of negative slack values from the first 100 paths from the timing violations report. The largest value out of all passes determines the best pass. If no negative slacks exist for a pass, then the worst slack is used to evaluate that pass. |

`[-stop_on_success]`

Applies only when the timing violations comparison criteria is used. The type of timing violations (slack) is determined by the -analysis option. Stops running the remaining passes if all timing constraints have been met (when there are no negative slacks reported in the timing violations report).

`[-timing_driven|-standard]`

Sets layout mode to timing driven or standard (non-timing driven). The default is -timing\_driven or the mode used in the previous layout command.

`[-power_driven value]`

Enables or disables power-driven layout. The default is off or the mode used in the previous layout command. The following table shows the acceptable values for this argument:

| Value | Description                       |
|-------|-----------------------------------|
| off   | Does not run power-driven layout. |
| on    | Enables power-driven layout.      |

`[-placer_high_effort value]`

Sets placer effort level. The default is off or the mode used in the previous layout command. The following table shows the acceptable values for this argument:

| Value | Description                        |
|-------|------------------------------------|
| off   | Runs layout in regular effort.     |
| on    | Activates high effort layout mode. |

## Return

A non-zero value will be returned on error.

## Exceptions

None

### See Also

[Place and Route - PolarFire](#)

[Multiple Pass Layout - PolarFire](#)

## Sample Tcl Script - Project Manager

The following Tcl commands create a new project and set your project options.

```
new_project -location {D:/2Work/my_pf_proj} -name {my_pf_proj} -project_description {} \
  -block_mode 0 -standalone_peripheral_initialization 0 -use_enhanced_constraint_flow 1 \
  -hdl {VERILOG} -family {PolarFire} -die {MPF300TS_ES} -package {FCG1152} -speed {-1} \
  -die_voltage {1.0} -part_range {EXT} -adv_options {IO_DEFT_STD:LVCNMOS 1.8V} \
  -adv_options {RESTRICTPROBEPINS:1} -adv_options {RESTRICTSPIPINS:0} \
  -adv_options {SYSTEM_CONTROLLER_SUSPEND_MODE:1} -adv_options {TEMPR:EXT} \
  -adv_options {VCCI_1.2_VOLTR:EXT} -adv_options {VCCI_1.5_VOLTR:EXT} \
  -adv_options {VCCI_1.8_VOLTR:EXT} -adv_options {VCCI_2.5_VOLTR:EXT} \
  -adv_options {VCCI_3.3_VOLTR:EXT} -adv_options {VOLTR:EXT}

#Import HDL source file
import_files -convert_EDN_to_HDL 0 -hdl_source {C:/test/prepl.v}
#Import HDL stimulus file
import_files -convert_EDN_to_HDL 0 -stimulus {C:/test/prepltb.v}
#set the top level design name
set_root -module {prepl::work}
#Associate SDC constraint file to Place and Route tool
organize_tool_files -tool {PLACERROUTE} -file {D:/2Work/my_pf_proj/constraint/user.sdc} \
  -module {prepl::work} -input_type {constraint}
#Associate SDC constraint file to Verify Timing tool
organize_tool_files -tool {VERIFYTIMING} -file {D:/2Work/my_pf_proj/constraint/user.sdc} \
  -module {prepl::work} -input_type {constraint}
#Run synthesize
run_tool -name {SYNTHESIZE}
#Configure Place and Route tool
configure_tool -name {PLACERROUTE} -params {DELAY_ANALYSIS:MAX} -params
{EFFORT_LEVEL:false} \
  -params {INCRPLACEANDROUTE:false} -params {MULTI_PASS_CRITERIA:VIOLATIONS} \
  -params {MULTI_PASS_LAYOUT:false} -params {NUM_MULTI_PASSES:5} -params {PDPR:false} \
  -params {RANDOM_SEED:0} -params {REPAIR_MIN_DELAY:false} -params
{SLACK_CRITERIA:WORST_SLACK} \
  -params {SPECIFIC_CLOCK:} -params {START_SEED_INDEX:1} -params
{STOP_ON_FIRST_PASS:false} \
  -params {TDPR:true}
#Run Place and Route
run_tool -name {PLACERROUTE}
#Configure Timing Report Generation
configure_tool -name {VERIFYTIMING} -run_tool -name {PLACERROUTE}params
{CONSTRAINTS_COVERAGE:1} \
  -params {FORMAT:XML} -params {MAX_TIMING_FAST_HV_LT:0} -params {MAX_TIMING_SLOW_LV_HT:1}
\
  -params {MAX_TIMING_SLOW_LV_LT:0} -params {MAX_TIMING_VIOLATIONS_FAST_HV_LT:0} \
  -params {MAX_TIMING_VIOLATIONS_SLOW_LV_HT:1} -params
{MAX_TIMING_VIOLATIONS_SLOW_LV_LT:0} \
  -params {MIN_TIMING_FAST_HV_LT:1} -params {MIN_TIMING_SLOW_LV_HT:0} -params
```

```
{MIN_TIMING_SLOW_LV_LT:0} -params {MIN_TIMING_VIOLATIONS_FAST_HV_LT:1} -params
{MIN_TIMING_VIOLATIONS_SLOW_LV_HT:0} \
-params {MIN_TIMING_VIOLATIONS_SLOW_LV_LT:0}

#Run Verify Timing tool
run_tool -name {VERIFYTIMING}
#Run Power Verification tool
run_tool -name {VERIFYPOWER}
#Export bitstream
export_bitstream_file -file_name {prep1} \
-export_dir {D:\2Work\my_pf_proj\designer\prep1\export} -format {STP} -master_file 0 \
-master_file_components {} -encrypted_uek1_file 0 -encrypted_uek1_file_components {} \
-encrypted_uek2_file 0 -encrypted_uek2_file_components {} \
-trusted_facility_file 1 -trusted_facility_file_components {FABRIC}
```

## How to Derive Required Part Information from A "Part Number"

In order to use Tcl Commands such as [set\\_device](#) or [new\\_design](#) ; certain part information items must be specified. Many of these items can be derived from the "Part Number" you have chosen. For example, suppose the Part Number is: **MPF300XT-1FCG784I**

- **-family <family name>**  
The <family name> usually known, e.g.  
-family {PolarFire}
- **-die <die name>**  
From the Part Number, the characters before the "-": **MPF300XT-1FCG784I**  
-die {MPF300XT}
- **-speed <speed grade>**  
If there is a digit immediately after the "-", <digit> will be the <speed grade> value (preceded by a "-"). In this case: **MPF300XT-1FCG784**  
-speed {-1}
  - NOTE: If there is no digit, the default speed grade is STD.
- **-package <package name>**  
The next sequence of letters, followed by a sequence of digits will constitute the package type and "size".  
NOTE: If there is a trailing letter after the <digits>; this letter is **not** part of the <package name>; but is rather part of the <part range> (see below).
  - For PolarFire, this combination will simply constitute the <package name> e.g.: **MPF300XT-1FCG784I**  
-package {FCG784}
- **-part\_range <part range>**  
The last letter (if any) will indicate the <part\_range> according to the following table:

| last letter | expansion value |
|-------------|-----------------|
| I           | IND             |
| E           | EXT             |
| M           | MIL             |
| <none>      | COM             |

- In this case: **MPF300XT-1FCG784I**  
-part\_range {IND}

---

# Project Manager Tcl Commands

---

## add\_file\_to\_library

Tcl command; adds a file to a library in your project.

```
add_file_to_library
-library name
-file name
```

### Arguments

-library *name*

Name of the library where you wish to add your file.

-file *name*

Specifies the new name of the file you wish to add (must be a full pathname).

### Example

Add a file named foo.vhd from the ./project/hdl directory to the library 'my\_lib'

```
add_file_to_library -library my_lib -file ./project/hdl/foo.vhd
```

#### See Also

[add\\_library](#)

[remove\\_library](#)

[rename\\_library](#)

## add\_library

Tcl command; adds a VHDL library to your project.

```
add_library
-library name
```

### Arguments

-library *name*

Specifies the name of your new library.

### Example

Create a new library called 'my\_lib'.

```
add_library -library my_lib
```

#### See Also

[remove\\_library](#)

[rename\\_library](#)

## add\_modelsim\_path

Tcl command; adds a ModelSim simulation library to your project.

```
add_modelsim_path -lib library_name [-path library_path] [-remove " "]
```

### Arguments

-lib *library\_name*

Name of the library you want to add.

-path *library\_path*

Path to library that you want to add.

-remove " "

Name of library you want to remove (if any).

### Example

Add the ModelSim library 'msim\_update2' located in the c:\modelsim\libraries directory and remove the library 'msim\_update1':

```
add_modelsim_path -lib msim_update2 [-path c:\modelsim\libraries] [-remove msim_update1]
```

## add\_profile

Tcl command; sets the same values as the [Add or Edit Profile dialog box](#). The newly added profile becomes the active tool profile for the specified *type* of tool.

```
add_profile -name profilename -type value -tool profiletool -location tool_location [-args tool_parameters] [-batch value]
```

### Arguments

-name *profilename*

Specifies the name of your new profile.

-type *value*

Specifies your profile type, where value is one of the following:

| Value      | Description                       |
|------------|-----------------------------------|
| synthesis  | New profile for a synthesis tool  |
| simulation | New profile for a simulation tool |
| stimulus   | New profile for a stimulus tool   |
| flashpro   | New FlashPro tool profile         |

-tool *profiletool*

Name of the tool you are adding to the profile.

-location *tool\_location*

Full pathname to the location of the tool you are adding to the profile.

-args *tool\_parameters*

Profile parameters (if any).

-batch *value*

Runs the tool in batch mode (if TRUE). Possible values are:

| Value | Description                            |
|-------|----------------------------------------|
| TRUE  | Runs the profile in batch mode         |
| FALSE | Does not run the profile in batch mode |

## Example

Create a new Synthesis tool profile called 'synpol' linked to a Synplify Pro ME installation in my /sqatest/bin directory

```
add_profile -type synthesis -name synpol -tool "Synplify Pro ME" -location
"/sqatest9/bin/synplify_pro" -batch FALSE
```

## associate\_stimulus

Tcl command; associates a stimulus file in your project.

```
associate_stimulus
[-file name]*
[-mode value]
-module value
```

## Arguments

-file *name*

Specifies the name of the file to which you want to associate your stimulus files.

-mode *value*

Specifies whether you are creating a new stimulus association, adding, or removing; possible values are:

| Value  | Description                                     |
|--------|-------------------------------------------------|
| new    | Creates a new stimulus file association         |
| add    | Adds a stimulus file to an existing association |
| remove | Removes an stimulus file association            |

-module *value*

Sets the module, where value is the name of the module.

## Example

The example associates a new stimulus file 'stim.vhd' for stimulus.

```
associate_stimulus -file stim.vhd -mode new -module stimulus
```

## change\_link\_source

Tcl command; changes the source of a linked file in your project.

```
change_link_source -file filename -path new_source_path
```

## Arguments

-file *filename*

Name of the linked file you want to change.

-path *new\_source\_path*

Location of the file you want to link to.

## Example

Change the link to a file 'sim1.vhd' in your project and link it to the file in  
c:\microsemi\link\_source\simulation\_test.vhd

```
change_link_source -file sim1.vhd -path c:\microsemi\link_source\simulation_test.vhd
```

## check\_fdc\_constraints

This Tcl command checks FDC constraints files associated with the Synthesis tool.

```
check_fdc_constraints -tool {synthesis}
```

## Arguments

-tool {synthesis}

## Example

```
check_fdc_constraints -tool {synthesis}
```

## Return Value

This command returns "0" on success and "1" on failure.

## check\_hdl

Tcl command; checks the HDL in the specified file.

```
check_hdl -file filename
```

## Arguments

-file *filename*

Name of the HDL file you want to check.

## Example

Check HDL on the file hdl1.vhd.

```
check_hdl -file hdl1.vhd
```

## check\_ndc\_constraints

This Tcl command checks NDC constraints files associated with the Synthesis tool. NDC constraints are used to optimize the post-synthesis netlist with the Libero SoC Compile engine.

```
check_ndc_constraints -tool {synthesis}
```

## Arguments

-tool {synthesis}

## Example

```
check_ndc_constraints -tool {synthesis}
```

## check\_pdc\_constraints

This Tcl command checks PDC constraints files associated with the Libero Place and Route tool.

```
check_pdc_constraints -tool {designer}
```

### Arguments

-tool {designer}

### Example

```
check_pdc_constraints -tool {designer}
```

### Return Value

This command returns “0” on success and “1” on failure.

## check\_sdc\_constraints

This Tcl command checks SDC constraints files associated with the Libero tools: designer, synthesis, or timing.

```
check_sdc_constraints -tool {tool_name}
```

### Arguments

-tool {synthesis|designer|timing}

### Example

This command checks the SDC constraint files associated with Timing Verification.

```
check_sdc_constraints -tool {timing}
```

This command checks the SDC constraint files associated with Place and Route.

```
check_sdc_constraints -tool {designer}
```

This command checks the SDC constraint files associated with Synthesis.

```
check_sdc_constraints -tool {synthesis}
```

### Return Value

The command returns “0” on success and “1” on failure.

## close\_design

Tcl command; closes the current design and brings Designer to a fresh state to work on a new design. This is equivalent to selecting the Close command from the File menu.

```
close_design
```

### Arguments

None

### Example

```
if { [catch { close_design } ] } {  
    puts "Failed to close design"  
    # Handle Failure  
}  
else {
```

```

    puts "Design closed successfully"
    # Proceed with processing a new design
  }

```

### See Also

[open design](#)  
[close design](#)  
[new design](#)

## close\_project

Tcl command; closes the current project in Libero SoC. Equivalent to clicking the File menu, and choosing Close Project.

```
close_project
```

### Arguments

None

### Example

```
close_project
```

### See Also

[open project](#)

## configure\_tool

configure\_tool is a general-purpose Tcl command that is used to set the parameters for any tool called by Libero. The command requires the name of the tool and one or more parameters in the format `tool_parameter:value`. These parameters are separated and passed to the tool to set up its run.

```

configure_tool
-name {<tool_name>} # Each tool_name has its own set of parameters
-params {<parameter>:<value>} # List of parameters and values
tool_name ::=  CONFIGURE_PROG_OPTIONS | SYNTHESIZE | PLACEROUTE |
GENERATEPROGRAMMINGFILE | PROGRAMDEVICE | PROGRAMMER_INFO | IO_PROGRAM_STATE | SPM |
VERIFYTIMING | PROGRAM_SPI_FLASH_IMAGE | SPM_OTP

```

### Supported tool\_names

The following table lists the supported tool\_names.

| tool_name                            | Parameter (-params)                           | Description                    |
|--------------------------------------|-----------------------------------------------|--------------------------------|
| "CONFIGURE_PROG_OPTIONS " on page 94 | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">SYNTHESIZE</a>           | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">PLACEROUTE</a>           | See the topic for parameter names and values. | See the topic for description. |

| tool_name                             | Parameter (-params)                           | Description                    |
|---------------------------------------|-----------------------------------------------|--------------------------------|
| "GENERATEPROGRAMMINGFILE" on page 94  | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">PROGRAMDEVICE</a>         | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">PROGRAMMER_INFO</a>       | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">IO_PROGRAMMING_STATE</a>  | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">SPM</a>                   | See the topic for parameter names and values. | See the topic for description. |
| VERIFYTIMING                          | See the topic for parameter names and values. | See the topic for description. |
| "PROGRAM_SPI_FLASH_IMAGE" on page 100 | See the topic for parameter names and values. | See the topic for description. |
| <a href="#">SPM_OTP</a>               | See the topic for parameter names and values. | See the topic for description. |

## See Also

[Tcl documentation conventions](#)

## create\_and\_configure\_core

Tcl command; creates a configured core component for a core selected from the Libero Catalog.

To use this command to create a configured core component with valid parameters and values, it is recommended to use the GUI to configure the core as desired. Then export the core configuration Tcl description by selecting the "Export Component Description(Tcl)" action on the right-click menu of the component in the Design Hierarchy. You can then use the exported Tcl command to create the configured core in a regular Tcl script.

```
create_and_configure_core \
-core_vlnv Vendor:Library:Name:version \
-component_name component_name \
[-params core_parameters]
```

## Arguments

`-core_vlnv` *Vendor:Library:Name:Version*

Specifies the version identifier of the core being configured. It is mandatory.

`-component_name` *component\_name*

Specifies the name of the configured core component. It is mandatory.

`-params` *core\_parameters*

Specifies the parameters that need to be configured for the core component. It is optional. If the core parameters are not specified with this argument, the component is configured and generated with the core's default configuration. It is recommended to specify all the core parameters of interest as a part of this argument in this command.

## Examples

```
create_and_configure_core -core_vlnv {Actel:SgCore:PF_CCC:1.0.115} -
component_name {PF_CCC_C3} -params { \
  "PLL_IN_FREQ_0:25" \
  "GLO_0_IS_USED:true" \
  "GLO_0_OUT_FREQ:150" \
  "GLO_1_IS_USED:true" \
  "GLO_1_OUT_FREQ:50" }
```

## Notes

For DirectCore and Solutions cores, refer to the core handbook or the core user guide for a list of valid parameters and values.

### See Also

[Tcl Command Documentation Conventions](#)

## create\_set

Tcl command; creates a set of paths to be analyzed. Use the arguments to specify which paths to include. To create a set that is a subset of a clock domain, specify it with the `-clock` and `-type` arguments. To create a set that is a subset of an inter-clock domain set, specify it with the `-source_clock` and `-sink_clock` arguments. To create a set that is a subset (filter) of an existing named set, specify the set to be filtered with the `-parent_set` argument.

```
create_set\ -name <name>\ -parent_set <name>\ -type <set_type>\ -clock <clock_name>\ -
source_clock <clock_name>\ -sink_clock <clock_name>\ -in_to_out\ -source <port/pin pattern>\
-sink <port/pin pattern>
```

## Arguments

`-name <name>`

Specifies a unique name for the newly created path set.

`-parent_set <name>`

Specifies the name of the set to filter from.

`-clock <clock_name>`

Specifies that the set is to be a subset of the given clock domain. This argument is valid only if you also specify the `-type` argument.

`-type <value>`

Specifies the predefined set type on which to base the new path set. You can only use this argument with the `-clock` argument, not by itself.

| Value             | Description                                       |
|-------------------|---------------------------------------------------|
| reg_to_reg        | Paths between registers in the design             |
| async_to_reg      | Paths from asynchronous pins to registers         |
| reg_to_async      | Paths from registers to asynchronous pins         |
| external_recovery | The set of paths from inputs to asynchronous pins |
| external_removal  | The set of paths from inputs to asynchronous pins |
| external_setup    | Paths from input ports to registers               |

| Value         | Description                          |
|---------------|--------------------------------------|
| external_hold | Paths from input ports to registers  |
| clock_to_out  | Paths from registers to output ports |

-in\_to\_out

Specifies that the set is based on the “Input to Output” set, which includes paths that start at input ports and end at output ports.

-source\_clock <clock\_name>

Specifies that the set will be a subset of an inter-clock domain set with the given source clock. You can only use this option with the -sink\_clock argument.

-sink\_clock <clock\_name>

Specifies that the set will be a subset of an inter-clock domain set with the given sink clock. You can only use this option with the -source\_clock argument.

-source <port/pin\_pattern>

Specifies a filter on the source pins of the parent set. If you do not specify a parent set, this option filters all pins in the current design.

-sink <port/pin\_pattern>

Specifies a filter on the sink pins of the parent set. If you do not specify a parent set, this option filters all pins in the current design.

## Examples

```
create_set -name { my_user_set } -source { C* } -sink { D* }
create_set -name { my_other_user_set } -parent_set { my_user_set } -source { CL* }
create_set -name { adder } -source { ALU_CLOCK } -type { REG_TO_REG } -sink { ADDER* }
create_set -name { another_set } -source_clock { EXTERN_CLOCK } -sink_clock {
MY_GEN_CLOCK }
```

## create\_links

Tcl command; creates a link (or links) to a file/files in your project.

```
create_links [-hdl_source file]* [-stimulus file]* [-sdc file]* [-pin file]* [-dcf file]* [-gcf file]* [-pdc file]* [-crt file]* [-vcd file]*
```

## Arguments

-hdl\_source file

Name of the HDL file you want to link.

-stimulus file

Name of the stimulus file you want to link.

-sdc file

Name of the SDC file you want to link.

-pin file

Name of the PIN file you want to link.

-dcf file

Name of the DCF file you want to link.

-gcf file

Name of the GCF file you want to link.

-pdc file

Name of the PDC file you want to link.

-crt *file*

Name of the crt file you want to link.

-vcd *file*

Name of the VCD file you want to link.

## Example

Create a link to the file hdl1.vhd.

```
create links [-hdl_source hdl1.vhd]
```

## create\_smartdesign

Tcl command; creates a SmartDesign.

```
create_smartdesign \  
-sd_name smartdesign_component_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component to be created. It is mandatory.

## Examples

```
create_smartdesign -sd_name {top}
```

### See Also

[Tcl Command Documentation Conventions](#)

## download\_core

Tcl command; downloads a core and adds it to your repository.

```
download_core [-vlnv "vlnv"]+ [-location "location"]
```

## Arguments

-vlnv *vlnv*

Vendor, library, name and version of the core you want to download.

-location *core\_name*

Location of the repository where you wish to add the core.

## Example

Download the core CoreAXI to the repository [www.actel-ip.com/repositories/SgCore](http://www.actel-ip.com/repositories/SgCore):

```
download_core -vlnv {Actel:SystemBuilder:PF_DDR4:1.0.102} -location {www.actel-  
ip.com/repositories/SgCore}
```

## download\_latest\_cores

This Tcl command is used to download the latest cores into the vault. A project does not need to be open to run this command.

```
download_latest_cores
```

This command takes no arguments.

If there are no cores to be downloaded, you will see the following message:

Info:All the latest cores are present in the vault.

## edit\_profile

Tcl command; sets the same values as the [Add or Edit Profile dialog box](#).

```
edit_profile -name profilename -type value -tool profiletool -location profilelocation [-args
parameters] [-batch value] [-new_name name]
```

### Arguments

-name *profilename*

Specifies the name of your new profile.

-type *value*

Specifies your profile type, where value is one of the following:

| Value      | Description                       |
|------------|-----------------------------------|
| synthesis  | New profile for a synthesis tool  |
| simulation | New profile for a simulation tool |
| stimulus   | New profile for a stimulus tool   |
| flashpro   | New FlashPro tool profile         |

-tool *profiletool*

Name of the tool you are adding to the profile.

-location *profilelocation*

Full pathname to the location of the tool you are adding to the profile.

-args *parameters*

Profile tool parameters (if any).

-batch *value*

Runs the tool in batch mode (if TRUE). Possible values are:

| Value | Description                            |
|-------|----------------------------------------|
| TRUE  | Runs the profile in batch mode         |
| FALSE | Does not run the profile in batch mode |

-new\_name *name*

Name of new profile.

### Example

Edit a FlashPro tool profile called 'myflashpro' linked to a new FlashPro installation in my c:\programs\actel\flashpro\bin directory, change the name to updated\_flashpro.

```
edit_profile -name myflashpro -type flashpro -tool flashpro.exe -location
c:\programs\actel\flashpro\bin\flashpro.exe -batch FALSE -new_name updated_flashpro
```

## export\_as\_link

Tcl command; exports a file to another directory and links to the file.

```
export_as_link -file filename -path link_path
```

### Arguments

-file *filename*

Name of the file you want to export as a link.

-path *link\_path*

Path of the link.

### Example

Export the file hdl1.vhd as a link to c:\microsemi\link\_source.

```
export_as_link -file hdl1.vhd -path c:\microsemi\link_source
```

## export\_ba\_files

Tcl command to export the backannotated files. The backannotated files are <design\_name>\_ba.v (Verilog backannotated netlist) or <design\_name>\_ba.vhd (VHDL backannotated netlist) and <design\_name>\_ba.sdf (Standard Delay Format) timing file. These files are passed to the default simulator for postlayout simulation.

```
export_ba_files
-export_dir {absolute path to folder location}
-export_file_name {name of file}
-vhdl {value}
-min_delay {value}
```

### Arguments

-export\_dir {*absolute path to directory/folder location*}

Folder/directory location.

-export\_file\_name {*name of file*}

File name to generate the files. If not specified, it takes <design\_name> as the default.

-vhdl {*value*}

Generates the <design\_name>\_ba.v and <design\_name>\_ba.sdf when set to 0 and <design\_name>\_ba.vhd and <design\_name>\_ba.sdf when set to 1. Default is 0.

-min\_delay {*value*}

Set to 1 to export enhanced min delays to include your best-case timing results in your Back Annotated file. Default is 0.

### Returns

Returns 0 on success, 1 on failure.

### Example

```
export_ba_files\
-export_dir {E:\designs\export\sd1}\
-export_file_name {test}\
-vhdl 0\
-min_delay 1
```

## export\_bitstream\_file

Configures the parameters for the bitstream to be exported from Libero.

```
export_bitstream_file
[-file_name file]
[-export_dir dir]
[-format PPD | STP | DAT | SPI]
[-master_file 0 | 1]
[-master_file_components SECURITY | FABRIC | SNVM]
[-encrypted_uek1_file 1 | 0]
[-encrypted_uek1_file_components FABRIC | SNVM]
[-encrypted_uek2_file 1 | 0]
[-encrypted_uek2_file_components FABRIC | SNVM]
[-trusted_facility_file 1 | 0]
[-trusted_facility_file_components FABRIC | SNVM]
[-zeroization_likenew_action 0 | 1]
[-zeroization_unrecoverable_action 0 | 1]
[-master_backlevel_bypass 0 | 1]
[-uek1_backlevel_bypass 0 | 1]
[-uek2_backlevel_bypass 0 | 1]
[-master_include_plaintext_passkey 0 | 1]
[-uek1_include_plaintext_passkey 0 | 1]
[-uek2_include_plaintext_passkey 0 | 1]
```

### Arguments

-file\_name *file*

The name of the file. File name must start with design name. If omitted, design name will be used.

-export\_dir *dir*

Location where the bitstream file will be exported. If omitted, design export folder will be used.

-format *PPD | STP | CHAIN\_STP | DAT | SPI*

Specifies the bitstream file formats to be exported. Space is used as a delimiter. If omitted, PPD and DAT files will be exported.

#### Zeroization Options:

-zeroization\_likenew\_action *0 | 1*

Specifies that all the data will be erased and the device can be reprogrammed immediately

-zeroization\_unrecoverable\_action *0 | 1*

Specifies that all the data will be erased and the device cannot be reprogrammed and it must be scrapped.

#### Security-related options:

Note: One of the trusted\_facility\_file or master\_file or encrypted\_uek1\_file or encrypted\_uek2\_file must be set to "1". 1 indicates that this particular file type will be exported; 0 indicates that it will not be exported. For example, if trusted\_facility\_file is set to 1, all other file types must be set to 0.

Or, if trusted\_facility\_file is set to 0, a combination of master\_file and euk1\_file and euk2\_file can be set to 1. In this case, master\_file must be set to 1.

Bitstream encryption with default key (default security):

-trusted\_facility\_file *1 | 0*

Specifies the bitstream file to be exported.

-trusted\_facility\_file\_components *FABRIC | SNVM*

Specifies the components of the design that will be saved to the bitstream file. The value can only be FABRIC and SNVM.

Custom security options:

-master\_file *0 | 1*

Specifies the bitstream files to be exported. Depends on the selected security.

**Note:** If `-master_file` is 1, SECURITY must be selected.

`-master_file_components` *SECURITY | FABRIC | SNVM*

Specifies the components in the design that will be saved to the bitstream file. The value can be any either SECURITY or SECURITY, FABRIC and SNVM

**Notes:**

1. The SECURITY option is available in `-bitstream_file_components` only when file type is MASTER in `-bitstream_file_type`.
2. SNVM should be programmed with FABRIC
3. Security only programming must be performed only on erased or new devices. If performed on device with fabric programmed, the fabric will be disabled after performing security only programming. You must reprogram the fabric to re-enable it.

`-encrypted_uek1_file` *0 | 1*

`-encrypted_uek1_file_components` *FABRIC | SNVM*

Specifies the components of the design that will be saved to uek1 bitstream.

**Note:** SNVM should be programmed with FABRIC

`-encrypted_uek2_file` *0 | 1*

`-encrypted_uek2_file_components` *FABRIC | SNVM*

Specifies the components of the design that will be saved to uek2 bitstream.

**Note:** SNVM should be programmed with FABRIC

`-master_include_plaintext_passkey` *0 | 1*

Specifies that the master file includes plaintext passkey. This argument is optional.

`-uek1_include_plaintext_passkey` *0 | 1*

Specifies that uek1 includes plaintext passkey. This argument is optional.

`-uek2_include_plaintext_passkey` *0 | 1*

Specifies that uek2 includes plaintext passkey. This argument is optional.

**Bypass Back Level Protection Options:**

`-master_backlevel_bypass` *0 | 1*

Specifies the Bypass Back Level protection for Golden/Recovery bitstream if back level protection is enabled in `_master` file.

`-uek1_backlevel_bypass` *0 | 1*

Specifies the Bypass Back Level Protection for Golden/Recovery bitstream if back level protection is enabled in `_uek1` file.

`-uek2_backlevel_bypass` *0 | 1*

Specifies the Bypass Back Level Protection for Golden/Recovery bitstream if back level protection is enabled in `_uek2` file.

Bitstream file to be exported and the components of the design that will be saved to the bitstream file are required.

**Note:** A TCL script file exported from Libero will include all command options. You can modify options you need and remove options you do not need.

## Example

Export a bitstream file:

**Export bitstream file for design with default security**

```
export_bitstream_file \
  -trusted_facility_file 1
  -trusted_facility_file_components {FABRIC SNVM}
```

## Export bitstream file for design with custom security options

Export bitstreams to master, uek1 and uek2 encrypted files. Master file to include security, fabric and SNVM components and Export Pass Key in Plaintext, uek1 and uek2 encrypted files to include FABRIC and SNVM with Like new Zeroization option enabled.

```
export_bitstream_file\
  -file_name {fftousram_new} \
  -export_dir
  {X:\10_docs_review\pf2.2_sp1\Programming_sars\99412\clkint_fftousram_ac_latch_launch\des
  igner\fftousram_new\export} \
  -format {PPD DAT}\
  -master_file 1 \
  -master_file_components {SECURITY FABRIC SNVM} \
  -encrypted_uek1_file 1 \
  -encrypted_uek1_file_components {FABRIC SNVM} \
  -encrypted_uek2_file 1 \
  -encrypted_uek2_file_components {FABRIC SNVM} \
  -trusted_facility_file 0 \
  -trusted_facility_file_components {} \
  -zeroization_likenew_action 1 \
  -zeroization_unrecoverable_action 0 \
  -master_backlevel_bypass 0 \
  -uek1_backlevel_bypass 0 \
  -uek2_backlevel_bypass 0
  -master_include_plaintext_passkey 1 \
  -uek1_include_plaintext_passkey 0 \
  -uek2_include_plaintext_passkey 0
```

## export\_bsd1\_file

Tcl command to export the BSDL to a specified file. The exported file has a \*.bsd file name extension.

```
export_bsd1_file
-file {absolute path and name of BSDL file}
```

### Arguments

-file {absolute path and name of BSDL file}

Specifies the \*.bsd file.

### Returns

Returns 0 on success, 1 on failure.

### Example

```
export_bsd1_file\
  -file {E:/designs/export/sd1.bsd}
```

## export\_component\_to\_tcl

Tcl command; exports the Tcl command for the selected component. The components can be SmartDesign components, configured cores and HDL+ cores.

```
export_component_to_tcl \
-component component_name \
```

```
[-library library_name] \  
[-package package_name] \  
-file file_path
```

## Arguments

-component *component\_name*

Specifies the name of the component for which the Tcl command is exported. It is mandatory.

-library *library\_name*

Specifies the name of the library the component belongs to. It is optional.

-package *package\_name*

Specifies the name of the package the HDL+core belongs to. It is optional.

-file *file\_path*

Specifies the path where you wish to export the Tcl file. It is mandatory.

## Example

```
export_component_to_tcl -component {pattern_gen_checker} -library {work} -package {} -  
file {./pattern_gen_checker.tcl}
```

## export\_design\_summary

This Tcl command exports an HTML file containing information about your root SmartDesign in your project. The HTML report provides information on:

- Generated Files
- I/Os
- Hardware Instances
- Firmware
- Memory Map

```
export_design_summary -file {D: /Designs/test/sd1.html}
```

## Returns

Returns 0 on success, 1 on failure.

## export\_fp\_pdc

Tcl command to export the Floorplanning Physical Design Constraint (\*.pdc) File. The exported file has a \*\_fp.pdc file name extension.

```
export_fp_pdc  
-file {absolute path and name of *_fp.pdc file}  
-mode {PDC_PLACE | PDC_FULL_PLACEMENT}
```

## Arguments

-file {*absolute path and name of \*\_fp.pdc file*}

Specifies the \*\_fp.pdc file.

-mode {*PDC\_PLACE* | *PDC\_FULL\_PLACEMENT*}

Use PDC\_PLACE to export user's floorplanning constraints, for example, fixed logic and regions.

Use PDC\_FULL\_PLACEMENT to export information about all of the physical design constraints (I/O constraints, I/O Banks, routing constraints, region constraints, global and local clocks).

## Returns

Returns 0 on success, 1 on failure.

## Example

```
export_fp_pdc\  
-file {E:/designs/export/sd1_fp.pdc}\  
-mode {PDC_FULL_PLACEMENT}
```

## export\_ibis\_file

Tcl command to export the IBIS (Input/Output Buffer Information Specification) model report. The exported file has a \*.ibs file name extension.

```
export_ibis_file  
-file {absolute path and name of *.ibs file}
```

## Arguments

-file {*absolute path and name of \*.ibs file*}  
Specifies the IBIS file to export.

## Returns

Returns 0 on success, 1 on failure.

## Example

```
export_ibis_file\  
-file {E:/designs/export/sd1.ibs}
```

## export\_io\_pdc

Tcl command to export the I/O constraints Physical Design Constraint (\*.pdc) File. The exported file has a \*\_io.pdc file name extension.

```
export_io_pdc  
-file {absolute path and name of *_io.pdc file}
```

## Arguments

-file {*absolute path and name of \*\_io.pdc file*}  
Specifies the \*\_io.pdc file.

## Returns

Returns 0 on success, 1 on failure.

## Example

```
export_io_pdc\  
-file {E:/designs/export/sd1_io.pdc}
```

## export\_netlist\_file

Tcl command to export the netlist after the compile state has completed. The netlist can be either Verilog or VHDL. Microsemi recommends exporting the netlist after the compile state has successfully completed.

```
export_netlist_file
-file {absolute path and filename for netlist}
-vhdl {value}
```

### Arguments

-file {*absolute path and filename*}

Specifies the path and name of netlist file.

-vhdl {*value*}

Generates the netlist in VHDL (when set to 1) or Verilog (when set to 0). Default is 0 (Verilog netlist).

### Returns

Returns 0 on success, 1 on failure.

### Example

```
export_netlist_files\
-file {E:/designs/export/sd1/sd1.v}\
-vhdl 0
```

## export\_pin\_reports

Tcl command to configure and export a pin report file to a specified folder/directory location.

```
export_pin_reports
-export_dir {absolute path to folder location}
-pin_report_by_name {value}
-pin_report_by_pkg_pin {value}
-bank_report {value}
-io_report {value}
```

### Arguments

-export\_dir {*absolute or relative path to the folder for pin report file*}

Specifies the folder.

-pin\_report\_by\_name {*value*}

Set to 1 to have the pin report sorted by pin name. Default is 1.

- pin\_report\_by\_pkg\_pin {*value*}

Set to 1 to have pin report sorted by package pin number, 0 to not sort by package pin number. Default is 1.

- bank\_report {*value*}

Set to 1 to generate the I/O bank report, 0 to not generate the report. Default is 1.

- io\_report {*value*}

Set to 1 to generate the I/O report, 0 to not generate the report. Default is 1.

At least one argument must be specified for this command.

### Returns

Returns 0 on success, 1 on failure.

## Example

```
export_pin_reports\  
-export_dir {E:/designs/export}\  
-pin_report_by_name {1}\  
-pin_report_by_pkg_pin {0}\  
-bank_report {1}\  
-io_report {1}
```

## export\_profiles

Tcl command; exports your tool profiles. Performs the same action as the [Export Profiles dialog box](#).

```
export_profile -file name [-export value]
```

## Arguments

-file *name*

Specifies the name of your exported profile.

-export *value*

Specifies your profile export options. The following table shows the acceptable values for this argument:

| Value      | Description                      |
|------------|----------------------------------|
| predefined | Exports only predefined profiles |
| user       | Exports only user profiles       |
| all        | Exports all profiles             |

## Example

The following command exports all profiles to the file 'all\_profiles':

```
export_profiles -file all_profiles [-export all]
```

## export\_prog\_job

Tcl command; configures the parameters for the FlashPro Express programming job to be exported.

```
export_prog_job  
-job_file_name file  
-export_dir dir  
-bitstream_file_type TRUSTED_FACILITY | MASTER | UEK1 | UEK2  
-bitstream_file_components SECURITY | FABRIC | SNVM  
-zeroization_likenew_action 0 | 1  
-zeroization_unrecoverable_action 0 | 1  
-program_design 0 | 1  
-program_spi_flash 0 | 1  
-include_plaintext_passkey 0 | 1 -design_bitstream_format PPD | STP
```

## Arguments

-job\_file\_name *file*

The name of the file. Name must start with design name. If omitted, design name will be used.

`-export_dir` *dir*

Location where the job file will be saved; any folder can be specified. The default folder is the Libero export folder.

`-bitstream_file_type` *TRUSTED\_FACILITY | MASTER | UEK1 | UEK2*

Bitstream file to be included in the programming job. Only one bitstream file can be included in a programming job.

`-bitstream_file_components` *SECURITY | FABRIC | SNVM*

The list of components to be included in the programming job. Components should be delimited by space. `bitstream_file_components` can be any one of SECURITY or SECURITY, FABRIC and SNVM

Notes:

1. The SECURITY option is available in `-bitstream_file_components` only when file type is MASTER in `-bitstream_file_type`.
2. SNVM must always be programmed with FABRIC.
3. Security-only programming must be performed only on erased or new devices. If performed on a device with fabric programmed, the fabric will be disabled after performing security-only programming. You must reprogram the fabric to re-enable it.

`-zeroization_likenew_action` *0 | 1*

Specifies that all data will be erased and the device can be reprogrammed immediately.

`-zeroization_unrecoverable_action` *0 | 1*

Specifies that all data will be erased. The device cannot be reprogrammed and it must be scrapped.

`-program_design` *0 | 1*

Specifies to program the design. This argument is optional.

`-program_spi_flash` *0 | 1*

Specifies to program SPI Flash. This argument is optional.

`-include_plaintext_passkey` *0 | 1*

Specifies to include plaintext passkey. This argument is optional.

`-design_bitstream_format` *PPD | STP*

Specifies the Bitstream file format. If omitted, the bitstream file will be in PPD format.

## Example

```
export_prog_job \
-job_file_name {fftousram_new} \
-export_dir
{X:\10_docs_review\12.0_Release\102018\clkint_fftousram_ac_latch_launch\designer\fftousra
m_new\export} \
-bitstream_file_type {MASTER} \
-bitstream_file_components {SECURITY FABRIC SNVM} \
-zeroization_likenew_action 0 \
-zeroization_unrecoverable_action 0 \
-program_design 1 \
-program_spi_flash 0 \
-include_plaintext_passkey 0 \
-design_bitstream_format {PPD}
```

## export\_script

Tcl command; `export_script` is a command that explicitly exports the Tcl command equivalents of the current Libero session. You must supply a file name with the `-file` parameter. You may supply the optional `-relative_path` parameter to specify whether an absolute or relative path is used in the exported script file.

```
export_script \
-file {<absolute or relative path to constraint file>} \
-relative_path <value> \
```

## Arguments

-file {<absolute or relative path to constraint file>}

Specifies the absolute or relative path to the constraint file; there may be multiple -file arguments (see example below).

-relative\_path {<value>}

Sets your option to use a relative or absolute path in the exported script; use 1 for relative path, 0 for absolute.

## Example

```
export_script -file {./exported.tcl} -relative_path 1
```

## generate\_component

Tcl command; generates a SmartDesign or a core component.

```
generate_component \
-component_name component_name \
[-recursive 0|1]
```

## Arguments

-component\_name component\_name

Specifies the name of the SmartDesign component or the core component to be generated. It is mandatory.

-recursive 0|1

Specifies if a SmartDesign component needs to be generated recursively. It is optional. It is '0' by default and generates only the specified component. If set to '1', all the dependent components which are in ungenerated state will be generated along with the SmartDesign component. It is recommended to generate all components individually.

## Examples

The following command generates SmartDesign "sd2" only.

```
generate_component -component_name {sd2}
```

The following command generates SmartDesign "TOP" and all its dependent components which are in ungenerated state.

```
generate_component -component_name {TOP} -recursive 1
```

### See Also

[Tcl Command Documentation Conventions](#)

## generate\_sdc\_constraint\_coverage

Tcl command to generate the constraint coverage report. The constraint coverage report contains information about the coverage of the paths from associated SDC constraints in the design. Two constraints coverage reports can be generated, one for Place and Route and one for Timing Verification.

To run this command, there is no need to run Place-and-Route first, but the design must be in the post-synthesis state. The generated constraint coverage reports (\*.xml) are listed in the Reports tab and are physically located in <prj\_folder>/designer/<module>/\*constraints\_coverage.xml.

```
generate_sdc_constraint_coverage -tool {PLACEROUTE | VERIFYTIMING}
```

## Arguments

```
-tool {PLACEROUTE|VERIFYTIMING}
```

Specifies whether the constraint coverage report is based on the SDC constraint file associated with Place and Route or associated with Timing Verification.

## Returns

Returns 0 on success, 1 on failure.

## Example

This command generates the SDC Constraint Coverage report for the SDC file associated with Place and Route:

```
generate_sdc_constraint_coverage -tool {PLACEROUTE}
```

This command generates the SDC Constraint Coverage report for the SDC file associated with Timing Verification:

```
generate_sdc_constraint_coverage -tool {VERIFYTIMING}
```

## See Also

Understanding Constraints Coverage Reports

## import\_files (Libero SoC)

Tcl command; enables you to import design source files and constraint files.

**SmartFusion2, IGLOO2, RTG4, PolarFire** : For importing constraint files, `import_files` has retired the `-pdc` parameter for SmartFusion2 and IGLOO2. It has been replaced with two new parameters to match the new design flow. Physical Design Constraints (PDC) Tcl must now be divided between I/O attribute and pin information from all floorplanning and timing constraints. These commands must now reside in and be imported as separate files. The new parameters specify the type of \*.pdc file being imported.

Use of the `-pdc` parameter with Smartfusion2 or IGLOO2 families will cause an error. The path to the file can be absolute or relative but must be enclosed in curly braces { }.

Use the `-can_convert_EDN_to_HDL` parameter to convert the EDIF file to HDL and then import the converted HDL file.

Note: The EDIF File is not imported.

```
import_files

-smartgen_core {file}
-ccp {file}
-stimulus {file}
-hdl_source {file}
-io_pdc {<absolute or relative path to file>} # For PDC containing I/O attribute and pin info
-fp_pdc {<absolute or relative path to file>} # For PDC containing timing and placement info
-edif {file}
-sdc {file}
-pin {file}
-dcf {file}
-pdc {file}

-vcd {file}
-saif {file}
-crt {file}
-simulation {file}
```

```

-profiles {file}
-cxf {file}
-templates {file}
-ccz {file}
-wf_stimulus {file}
-modelsim_ini {file}
-library {file}
-can_convert_EDN_to_HDL {true | false}

```

## Arguments

`-smartgen_core {file}`

Specifies the cores you wish to import into your project. Type parameter must be repeated for each file.

`-ccp {file}`

Specifies the ARM or Cortex-M1 cores you wish to import into your project. Type parameter must be repeated for each file.

`-stimulus {file}`

Specifies HDL stimulus files you wish to import into your project. Type parameter must be repeated for each file.

`-hdl_source {file}`

Specifies the HDL source files you wish to import into your project. Type parameter must be repeated for each file.

`-io_pdc {<absolute or relative path to file>}`

SmartFusion2 and IGLOO2 only - Specifies the PDC file that contains the I/O attribute and pin information.

`-fp_pdc {<absolute or relative path to file>}`

SmartFusion2 and IGLOO2 only - Specifies the PDC file that contains the timing and placement information.

`-edif {file}`

Specifies the EDIF files you wish to import into your project. Type parameter must be repeated for each file. This is a mandatory option if you want to convert EDIF to HDL with the `-can_convert_EDN_to_HDL` option.

`-can_convert_EDN_to_HDL {true | false | 1 | 0}` #Boolean {true | false | 1 | 0}

The `-edif` option is mandatory. If the `-edif` option is not specified or the `-can_convert_EDN_to_HDL` is used with another option, EDIF to HDL conversion will fail.

`-constraint_sdc {file}`

Specifies the SDC constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_pin {file}`

Specifies the PIN constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_dcf {file}`

Specifies the DCF constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_pdc {file}`

Specifies the PDC constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_gcf {file}`

Specifies the GCF constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_vcd {file}`

Specifies the VCD constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_saif {file}`

Specifies the SAIF constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-constraint_crt {file}`

Specifies the CRT constraint files you wish to import into your project. Type parameter must be repeated for each file.

`-simulation {file}`

Specifies the simulation files you wish to import into your Libero SoC project. Type parameter must be repeated for each file.

`-profiles {file}`

Specifies the profile files you wish to import into your Libero SoC project. Type parameter must be repeated for each file.

`-cxf {file}`

Specifies the CXF file (such as SmartDesign components) you wish to import into your Libero SoC project. Type parameter must be repeated for each file.

`-templates {file}`

Specifies the template file you wish to import into your IDE project.

`-ccz {file}`

Specifies the IP core file you wish to import into your project.

`-wf_stimulus {file}`

Specifies the WaveFormer Pro stimulus file you wish to import into your project.

`-modelsim_ini {file}`

Specifies the ModelSIM INI file that you wish to import into your project.

`-library {file}`

Specifies the library file that you wish to import into your project. If a library file is not available it will be created and added to the library.

## Example

The command below imports the HDL source files file1.vhd and file2.vhd:

```
import_files -hdl_source file1.vhd -hdl_source file2.vhd
```

## new\_project

Tcl command; creates a new project in Libero SoC. If you do not specify a location, Libero SoC saves the new project in your current working directory.

```
new_project -name project_name\
-location project_location -family family_name\
-project_description brief text description of project\
-die device_die -package package_name -hdl HDL_type\
-speed speed_grade -die_voltage value\
-ondemand_build_dh {1 | 0}\
-adv_options value\
```

## Arguments

`-name project_name`

The name of the project. This is used as the base name for most of the files generated from Libero SoC.

`-location project_location`

The location of the project. Must not be an existing directory.

-project\_description *project\_description*

A brief text description of the design in your project.

-family *family\_name*

The Microsemi SoC device family for your targeted design.

-die *device\_die*

Die for your targeted design.

-package *package\_name*

Package for your targeted design.

-hdl *HDL\_type*

Sets the HDL type for your new project.

| Value   | Description                             |
|---------|-----------------------------------------|
| VHDL    | Sets your new projects HDL type to VHDL |
| VERILOG | Sets your new projects to Verilog       |

-speed *speed\_grade*

Sets the speed grade for your project. Possible values depend on your device, die and package. See your device datasheet for details.

-die\_voltage *value*

Sets the die voltage for your project. Possible values depend on your device. See your device datasheet for details.

-ondemand\_build\_dh {1 | 0}

Enter "1" to enable or "0" (default) to disable On Demand Build Design Hierarchy.

-adv\_options *value*

Sets your advanced options, such as operating conditions.

| Value                          | Description                                                                                                                                                                                                                                                                                                                                                                                    |
|--------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| IO_DEFT_STD:LVTTL              | <p>Sets your I/O default value to LVTTL. This value defines the default I/O technology to be used for any I/Os that the user does not explicitly set a technology for in the I/O Editor. It could be any of :</p> <ul style="list-style-type: none"> <li>• LVTTL</li> <li>• LVCMOS 3.3V</li> <li>• LVCMOS 2.5V</li> <li>• LVCMOS 1.8V</li> <li>• LVCMOS 1.5V</li> <li>• LVCMOS 1.2V</li> </ul> |
| RESTRICTPROBEPINS              | <p>This value reserves your pins for probing if you intend to debug using SmartDebug. Two values are available:</p> <ul style="list-style-type: none"> <li>• 1 (Probe pins are reserved)</li> <li>• 0 (No probe pins are reserved)</li> </ul>                                                                                                                                                  |
| SYSTEM_CONTROLLER_SUSPEND_MODE | <p>Enables designers to suspend operation of the System Controller. Enabling this bit instructs the System Controller to place itself in a reset state once the device is powered up. This effectively suspends all system services from being performed. For a list of</p>                                                                                                                    |

| Value                                                                                                                                             | Description                                                                                                                                                                                                                                                                                              |
|---------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                                                                                                                                   | <p>system services, refer to the PolarFire FPGA Fabric User Guide for your device on the Microsemi website.</p> <p>Two values are available:</p> <ul style="list-style-type: none"> <li>1 (System Controller Suspend Mode is enabled)</li> <li>0 (System Controller Suspend Mode is disabled)</li> </ul> |
| The following options are for Analysis Operating Conditions so that Timing and Power analysis can be performed at different operating conditions. |                                                                                                                                                                                                                                                                                                          |
| TEMPR                                                                                                                                             | Sets your default temperature range for operatingcondition analysis to EXT or IND                                                                                                                                                                                                                        |
| VCCI_1.2_VOLTR                                                                                                                                    | <p>Sets the Default I/O Voltage Range for 1.2V to EXT or IND</p> <p>These settings are propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis</p>                                                                                                          |
| VCCI_1.5_VOLTR                                                                                                                                    | <p>Sets the Default I/O Voltage Range for 1.5V to EXT or IND</p> <p>These settings are propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis</p>                                                                                                          |
| VCCI_1.8_VOLTR                                                                                                                                    | <p>Sets the Default I/O Voltage Range for 1.8V to EXT or IND</p> <p>These settings are propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis</p>                                                                                                          |
| VCCI_2.5_VOLTR                                                                                                                                    | <p>Sets the Default I/O Voltage Range for 2.5V to EXT or IND</p> <p>These settings are propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis</p>                                                                                                          |
| VCCI_3.3_VOLTR                                                                                                                                    | <p>Sets the Default I/O Voltage Range for 3.3V to EXT or IND</p> <p>These settings are propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis</p>                                                                                                          |
| VOLTR                                                                                                                                             | Sets the core voltage range for operating condition analysis to EXT or IND. This setting is propagated to Verify Timing, Verify Power and Backannotated Netlist to perform Timing/Power Analysis.                                                                                                        |
| PART_RANGE                                                                                                                                        | Sets your default temperature range for your project to EXT or IND.                                                                                                                                                                                                                                      |

## Example

```
#Create a new project and set up a new design
new_project -location {D:/2Work/my_pf_proj} -name {my_pf_proj} -project_description {} \-
block_mode 0 -standalone_peripheral_initialization 0 -use_enhanced_constraint_flow 1 \-
hdl {VERILOG} -family {PolarFire} -die {MPF300TS_ES} -package {FCG1152} -speed {-1} \-
die_voltage {1.0} -part_range {EXT} -adv_options {IO_DEFT_STD:LVC MOS 1.8V} \-adv_options
{RESTRICTPROBEPINS:1} -adv_options {RESTRICTSPIPINS:0} \-adv_options
{SYSTEM_CONTROLLER_SUSPEND_MODE:1} -adv_options {TEMPR:EXT} \-adv_options
{VCCI_1.2_VOLTR:EXT} -adv_options {VCCI_1.5_VOLTR:EXT} \-adv_options
{VCCI_1.8_VOLTR:EXT} -adv_options {VCCI_2.5_VOLTR:EXT} \-adv_options
{VCCI_3.3_VOLTR:EXT} -adv_options {VOLTR:EXT}
#Import HDL source file
```

```

import_files -convert_EDN_to_HDL 0 -hdl_source {C:/test/prepl.v}
#Import HDL stimulus file
import_files -convert_EDN_to_HDL 0 -stimulus {C:/test/prepltb.v}
#set the top level design name
set_root -module {prepl::work}
#Associate SDC constraint file to Place and Route tool
organize_tool_files -tool {PLACERROUTE} -file {D:/2Work/my_pf_proj/constraint/user.sdc}
\ -module {prepl::work} -input_type {constraint}
#Associate SDC constraint file to Verify Timing tool
organize_tool_files -tool {VERIFYTIMING} -file
{D:/2Work/my_pf_proj/constraint/user.sdc} \ -module {prepl::work} -input_type
{constraint}
#Run synthesize
run_tool -name {SYNTHESIZE}
#Configure Place and Route tool
configure_tool -name {PLACERROUTE} -params {DELAY_ANALYSIS:MAX} -params
{EFFORT_LEVEL:false} \ -params {INCRPLACEANDROUTE:false} -params
{MULTI_PASS_CRITERIA:VIOLATIONS} \ -params {MULTI_PASS_LAYOUT:false} -params
{NUM_MULTI_PASSES:5} -params {PDPR:false} \ -params {RANDOM_SEED:0} -params
{REPAIR_MIN_DELAY:false} -params {SLACK_CRITERIA:WORST_SLACK} \ -params
{SPECIFIC_CLOCK:} -params {START_SEED_INDEX:1} -params {STOP_ON_FIRST_PASS:false} \ -
params {TDPR:true}

```

## See Also

[How to Derive Required Part Information from A "Part Number"](#)

## open\_project

Tcl command; opens an existing Libero SoC project.

```
open_project project_name -do_backup_on_convert value -backup_file backup_filename
```

## Arguments

*project\_name*

Must include the complete path to the PRJ file. If you do not provide the full path, Libero SoC infers that you want to open the project from your current working directory.

-do\_backup\_on\_convert *value*

Sets the option to backup your files if you open a project created in a previous version of Libero SoC.

| Value | Description                                              |
|-------|----------------------------------------------------------|
| TRUE  | Creates a backup of your original project before opening |
| FALSE | Opens your project without creating a backup             |

-backup\_file *backup\_filename*

Sets the name of your backup file (if you choose to do\_backup\_on\_convert).

## Example

Open project.prj from the c:/netlists/test directory.

```
open_project c:/netlists/test/project.prj
```

### See Also

[close\\_project](#)

[new\\_project](#)

[save\\_project](#)

## open\_smartdesign

Tcl command; opens a SmartdDesign. You must either open or create a SmartDesign before using any of the SmartDesign specific commands "sd\_\*".

```
open_smartdesign \
-sd_name smartdesign_component_name
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component to be opened. It is mandatory.

### Examples

```
open_smartdesign -sd_name {top}
```

### Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## organize\_constraints

Tcl command; organizes the constraint files in your project.

```
-organize_constraints
[-file name]*
[-mode value]
-designer_view name
-module value
-tool value
```

### Arguments

-file *name*

Specifies the name of the file to which you want to associate your stimulus files.

-mode *value*

Specifies whether you are creating a new stimulus association, adding, or removing; possible values are:

| Value  | Description                                     |
|--------|-------------------------------------------------|
| new    | Creates a new stimulus file association         |
| add    | Adds a stimulus file to an existing association |
| remove | Removes an stimulus file association            |

`-designer_view` *name*

Sets the name of the Designer View in which you wish to add the constraint file, where name is the name of the view (such as impl1).

`-module` *value*

Sets the module, where value is the name of the module.

`-tool` *value*

Identifies the intended use for the file, possible values are:

| Value     | Description                           |
|-----------|---------------------------------------|
| synthesis | File to be used for synthesis         |
| designer  | File to be used in Designer           |
| phsynth   | File to be used in physical synthesis |

## Example

The example adds the constraint file delta.vhd in the Designer View impl2 for the Designer tool.

```
-organize_constraints -file delta.vhd -mode new -designer_view impl2 -module constraint
-tool designer
```

## organize\_sources

Tcl command; organizes the source files in your project.

```
-organize_sources
[-file name]*
[-mode value]
-module value
-tool value
[-use_default value]
```

## Arguments

`-file` *name*

Specifies the name of the file to which you want to associate your stimulus files.

`-mode` *value*

Specifies whether you are creating a new stimulus association, adding, or removing; possible values are:

| Value  | Description                                     |
|--------|-------------------------------------------------|
| new    | Creates a new stimulus file association         |
| add    | Adds a stimulus file to an existing association |
| remove | Removes an stimulus file association            |

`-module` *value*

Sets the module, where value is the name of the module.

`-tool` *value*

Identifies the intended use for the file, possible values are:

| Value      | Description                    |
|------------|--------------------------------|
| synthesis  | File to be used for synthesis  |
| simulation | File to be used for simulation |

`-use_default` *value*

Uses the default values for synthesis or simulation; possible values are:

| Value | Description                                          |
|-------|------------------------------------------------------|
| TRUE  | Uses default values for synthesis or simulation.     |
| FALSE | Uses user-defined values for synthesis or simulation |

## Example

The example organizes a new stimulus file 'stim.vhd' using default settings.

```
-organize_sources -file stim.vhd -mode new -module stimulus -tool synthesis -use_default
TRUE
```

## See Also

[Project Manager Tcl Command Reference](#)

## organize\_tool\_files

This Tcl command is used to specify specific constraint files to be passed to and used by a Libero tool.

```
organize_tool_files \
-tool {tool_name}
-params {tool parameters}
-file {<absolute or relative path to constraint file>} \
-module {$design::work} \
-input_type {value}
```

## Arguments

`-tool` {<*tool\_name*>}

Specifies the name of the tool files you want to organize. Valid values are:

SYNTHESIZE | PLACEROUTE | SIM\_PRESYNTH | SIM\_POSTSYNTH | SIM\_POSTLAYOUT |  
VERIFYTIMING

`-file` {<*absolute or relative path to constraint file*>}

Specifies the absolute or relative path to the constraint file; there may be multiple `-file` arguments (see example below).

`-module` {<*design::work*>}

Module definition, format is <*\$design::work*>.

`-input_type` {<*constraint*>}

Specifies type of input file. Possible values are: constraint | source | simulation | stimulus |  
unknown

## Example

The following command organizes the `test_derived.sdc` and `user.sdc` files of SDC file type for the tool VERIFYTIMING for the `sd1: work` design.

```
organize_tool_files \
  -tool {VERIFYTIMING} \
  -file {D:/Designs/my_proj/constraints/test_derived.sdc} \
  -file {D:/Designs/my_proj/constraints/user.sdc} \
  -module {sd1:work} \
  -input_type {constraint}
```

## project\_settings

This Tcl command modifies project flow settings for your Libero SoC project.

```
project_settings [-hdl "VHDL | VERILOG"] \
[-verilog_mode {VERILOG_2K | SYSTEM_VERILOG}] \
[-vhdl_mode {VHDL_2008 | VHDL_93}] \
[-auto_update_modelsim_ini "TRUE | FALSE"] \
[-auto_update_viewdraw_ini "TRUE | FALSE"] \
[-block_mode "TRUE | FALSE"] \

[-auto_generate_synth_hdl "TRUE | FALSE"] \
[-auto_run_drc "TRUE | FALSE"] \
[-auto_generate_viewdraw_hdl "TRUE | FALSE"] \
[-auto_file_detection "TRUE | FALSE"] \
[-standalone_peripheral_initialization "1 | 0"] \

[-ondemand_build_dh "1 | 0"] \
[-enable_design_separation "1 | 0"] \
[-enable_set_mitigation "1 | 0"] \
[-display_fanout_limit {integer}]
```

## Arguments

`-hdl "VHDL | VERILOG"`

Sets your project HDL type.

`-verilog_mode {VERILOG_2K | SYSTEM_VERILOG}`

Sets the Verilog standard to Verilog-2001 or System Verilog.

`-vhdl_mode {VHDL_2008 | VHDL_93}`

Sets the VHDL standard to VHDL-2008 or VHDL-1993.

`-auto_update_modelsim_ini "TRUE | FALSE"`

Sets your auto-update modelsim.ini file option. TRUE updates the file automatically.

`-auto_update_viewdraw_ini "TRUE | FALSE"`

Sets your auto-update viewdraw.ini file option. TRUE updates the file automatically.

`-block_mode "TRUE | FALSE"`

Puts the Project Manager in Block mode, enables you to create blocks in your project.

`-auto_generate_synth_hdl "TRUE | FALSE"`

Auto-generates your HDL file after synthesis (when set to TRUE).

`-auto_run_drc "TRUE | FALSE"`

Auto-runs the design rule check immediately after synthesis (when set to TRUE).

`-auto_generate_viewdraw_hdl "TRUE | FALSE"`

Auto-generates your HDL netlist after a Save & Check in ViewDraw (when set to TRUE).

`-auto_file_detection "TRUE | FALSE"`

Automatically detects when new files have been added to the Libero SoC project folder (when set to TRUE).

```
-standalone_peripheral_initialization "1 | 0"
```

When set to 1, this option instructs System Builder not to build the initialization circuitry for your Peripherals. Set this option to 1 if you want to build your own peripheral initialization logic in SmartDesign to initialize each of the peripherals (MDDR/FDDR/SERDES) independently.

```
-ondemand_build_dh "1 | 0"
```

Enter "1" to enable or "0" (default) to disable On Demand Build Design Hierarchy.

```
-enable_design_separation "1 | 0"
```

Set it to "1" if your design is for security and safety critical applications and you want to make your design's individual subsystems (design blocks) separate and independent (in terms of physical layout and programming) to meet your design separation requirements. When set to "1", Libero generates a parameter file (MSVT.param) that details design blocks present in the design and the number of signals entering and leaving a design block. Microsemi provides a separate tool, known as Microsemi Separation Verification Tool (MSVT), which checks the final design place and route result against the MSVT.param file and determines whether the design separation meets your requirements.

```
-display_fanout_limit {integer}
```

Use this option to set the limit of high fanout nets to be displayed; the default value is 10. This means the top 10 nets with the highest fanout will appear in the <root>\_compile\_netlist.log file.

## Example

The following example sets your project to VHDL, disables the auto-update of the ModelSim INI or ViewDraw INI files, enables the auto-generation of HDL after synthesis, enables auto-detection for files, sets the display of high fanout nets to the top 12 high fanout nets, enables SET filters to mitigate radiation-induced transients, and enables design separation methodology for the design.

```
project_settings -hdl "VHDL" \
  -auto_update_modelsim_ini "FALSE" \
  -auto_update_viewdraw_ini "FALSE" \
  -block_mode "FALSE" -auto_generate_synth_hdl "TRUE" \
  -auto_file_detection "TRUE" \
  -display_fanout_limit {12} \
  -enable_set_mitigation {1} \
  -enable_design_separation {1}
```

## refresh

Tcl command; refreshes your project, updates the view and checks for updated links and files.

```
refresh .
```

## Example

```
refresh .
```

## remove\_core

Tcl command; removes a core from your project.

```
remove_core -name core_name
```

## Arguments

```
-name core_name
```

Name of the core you want to remove.

## Example

Remove the core ip-beta2:  
`remove_core -name ip-beta2.ccz`

## remove\_library

Tcl command; removes a VHDL library from your project.

```
remove_library  
-library name
```

## Arguments

`-library name`  
Specifies the name of the library you wish to remove.

## Example

Remove (delete) a library called 'my\_lib'.  
`remove_library -library my_lib`

## See Also

[add\\_library](#)  
[rename\\_library](#)

## remove\_profile

Tcl command; deletes a tool profile.

```
remove_profile -name profilename
```

## Arguments

`-name profilename`  
Specifies the name of the profile you wish to delete.

## Example

The following command deletes the profile 'custom1':  
`remove_profile -name custom1`

## rename\_file

This Tcl command renames a constraint file specified by the `-file` parameter to a different name specified by the `-target` parameter.

```
rename_file -file {filename} -target {new_filename}
```

## Arguments

`-file {filename}`  
Specifies the original name of the file.  
`-target {new_filename}`  
Specifies the new name of the file.

## Example

This command renames the file `a.sdc` to `b.sdc`.

```
rename_file -file {c:/user/a.sdc} -target {c:/user/b.sdc}
```

## Return Value

This command returns 0 on success and 1 on failure.

## rename\_library

Tcl command; renames a VHDL library in your project.

```
rename_library
-library name
-name name
```

## Arguments

-library *name*

Identifies the current name of the library that you wish to rename.

-name *name*

Specifies the new name of the library.

## Example

Rename a library from 'my\_lib' to 'test\_lib1'

```
rename_library -library my_lib -name test_lib1
```

## See Also

[add\\_library](#)

[remove\\_library](#)

## run\_tool

`run_tool` starts the specified tool. For tools that support command files, an optional command file can be supplied through the `-script` parameter.

```
run_tool
-name {<tool_name >} \
-script {<absolute or relative path to script file>}
```

-script is an optional parameter.

```
tool_name ::= SYNTHESIZE | COMPILE | SIM_PRESYNTH | SIM_POSTSYNTH | PLACEROUTE |
VERIFYTIMING | VERIFYPOWER | GENERATEPROGRAMMINGFILE | GENERATE_MEMORY_MAP |
PROGRAMDEVICE | CONFIGURE_CHAIN | SMARTDEBUG | SSANALYZER | GENERATE_SPI_FLASH_IMAGE
| PROGRAM_SPI_FLASH_IMAGE
```

## Return

`run_tool` returns 0 on success and 1 on failure.

## Supported tool\_names

The following table lists `tool_names` for `run_tool -name {tool_name}`.

| tool_name                | Parameter                         | Description                                                                                                                                                     |
|--------------------------|-----------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| SYNTHESIZE               | -script<br>{ <i>script_file</i> } | Runs synthesis on your design.                                                                                                                                  |
| COMPILE                  | N/A                               | Runs Compile with default or configured settings.                                                                                                               |
| SIM_PRESYNTH             | N/A                               | Runs pre-synthesis simulation with your default simulation tool                                                                                                 |
| SIM_POSTSYNTH            | N/A                               | Runs post-synthesis simulation with your default simulation tool.                                                                                               |
| PLACEROUTE               | N/A                               | Runs Layout with default or configured settings.                                                                                                                |
| VERIFYTIMING             | -script<br>{ <i>script_file</i> } | Runs timing analysis with default settings/configured settings in <i>script_file</i> .                                                                          |
| VERIFYPOWER              | -script<br>{ <i>script_file</i> } | Runs power analysis with default settings/configured settings in <i>script_file</i> .                                                                           |
| GENERATEPROGRAMMINGFILE  | N/A                               | Generates the bitstream used for programming within Libero.                                                                                                     |
| GENERATE_MEMORY_MAP      | N/A                               | Exports an XML file in <prj_folder> component/work/<design> /<design>_DataSheet.xml. The file contains information about your root SmartDesign in your project. |
| PROGRAMDEVICE            | N/A                               | Programs your device with configured parameters.                                                                                                                |
| CONFIGURE_CHAIN          | -script<br>{ <i>script_file</i> } | Takes a script that contains FlashPro-specific Tcl commands and passes them to FlashPro Express for execution.                                                  |
| SMARTDEBUG               | -script<br>{ <i>script_file</i> } | Takes a script that contains SmartDebug-specific Tcl commands and passes them to SmartDebug for execution.                                                      |
| GENERATE_SPI_FLASH_IMAGE | N/A                               | Generates SPI Flash Image file used for programming SPI FLASH Image within Libero.                                                                              |
| PROGRAM_SPI_FLASH_IMAGE  | N/A                               | Programs SPI Flash Image with configured parameters.                                                                                                            |

-script {*absolute or relative path to script file*}

Script file location.

## Example

```
run_tool \
  -name {COMPILE}
run_tool \
  -name {SYNTHESIZE} -script {./control_synopsys.tcl}
  #control_synopsys.tcl contains the synthesis-specific Tcl commands
run_tool \
  -name {VERIFYTIMING} \
  -script {./SmartTime.tcl}
  # Script file contains SmartTime-specific Tcl commands
run_tool \
  -name {VERIFYPOWER} \
  -script {./SmartPower.tcl}
  # Script file contains SmartPower-specific Tcl commands
run_tool \
  -name {SMARTDEBUG}
  -script {./sd_test.tcl}
  # Script file contains SmartDebug-specific Tcl commands
```

## Note

Where possible, the value of `tool_name` corresponds to the name of the tool in Libero SoC.

Invoking some tools will cause Libero SoC to automatically run some upstream tools in the design flow. For example, invoking Place and Route will invoke Synthesis (if not already run) before it runs Place and Route.

## save\_project\_as

Tcl command; the `save_project_as` command saves the current project in Libero SoC with a different name and in a specified directory. You must specify a location with the `-location` parameter.

```
save_project_as
-name project_name
-location project_location
-files value
-designer_views value
-replace_links value
```

## Arguments

`-name project_name`

Specifies the name of your new project.

`-location project_location`

Must include the complete path of the PRJ file. If you do not provide the full path, Libero SoC infers that you want to save the project to your current working directory. This is a required parameter.

`-files value`

Specifies the files you want to copy into your new project.

| Value   | Description                                                     |
|---------|-----------------------------------------------------------------|
| all     | Copies all your files into your new project                     |
| project | Copies only your Libero SoC project files into your new project |
| source  | Copies only the source files into your new project              |

| Value | Description                                                                                                     |
|-------|-----------------------------------------------------------------------------------------------------------------|
| none  | Copies none of the files into your new project; useful if you wish to manually copy only specific project files |

`-designer_views` *value*

Specifies the Designer views you wish to copy into your new project.

| Value   | Description                                                        |
|---------|--------------------------------------------------------------------|
| all     | Copies all your Designer views into your new project               |
| current | Copies only your current Designer view files into your new project |
| none    | Copies none of your views into your new project                    |

`-replace_links` *value*

Specifies whether or not you want to update your file links in your new project.

| Value | Description                                                        |
|-------|--------------------------------------------------------------------|
| true  | Replaces (updates) the file links in your project during your save |
| false | Saves your project without updating the file links                 |

## Example

Saves your current Libero SoC project as mydesign.prj in the c:/netlists/testprj/mydesign directory:

```
save_project_as -location c:/netlists/testprj/mydesign -name mydesign.prj
```

## See Also

[new\\_project](#)  
[open\\_project](#)  
[save\\_project](#)

## save\_log

Tcl command; saves your Libero SoC log file.

```
save_log -file value
```

## Arguments

`-file` *value*

Value is your name for the new log file.

## Example

Save the log file file\_log.

```
save_log -file file_log
```

## See Also

[close\\_project](#)  
[new\\_project](#)

## save\_project

Tcl command; the save\_project command saves the current project in Libero SoC.

```
save_project
```

## Arguments

None

## Example

Saves the project in your current working directory:

```
save_project
```

## See Also

[new\\_project](#)  
[open\\_project](#)

## save\_smartdesign

Tcl command; saves all the changes made in a SmartDesign component.

```
save_smartdesign \  
-sd_name smartdesign_component_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component to be saved. It is mandatory.

## Examples

```
save_smartdesign -sd_name {top}
```

### See Also

[Tcl Command Documentation Conventions](#)

## select\_profile

Tcl command; selects a profile to use in your project.

```
select_profile -name profilename
```

## Arguments

-name *profilename*

Specifies the name of the profile you wish to use.

## Example

The following command selects the profile 'custom1':

```
select_profile -name custom1
```

## set\_actel\_lib\_options

Tcl command; the `set_actel_lib_options` command sets your simulation library to default, or to another library (when you specify a path).

```
set_actel_lib_options -use_default_sim_path value -sim_path {path}
```

### Arguments

`-use_default_sim_path value`

Possible values are:

| Value | Description                                                                                                                                   |
|-------|-----------------------------------------------------------------------------------------------------------------------------------------------|
| TRUE  | Uses the default simulation library.                                                                                                          |
| FALSE | Disables the default simulation library; enables you to specify a different simulation library with the <code>-sim_path {path}</code> option. |

`-sim_path {path}`

Specifies the path to your simulation library.

### Example

Uses a simulation library in the directory `c:\sim_lib\test`.

```
set_actel_lib_options -use_default_sim_path FALSE -sim_path {c:\sim_lib\test}
```

## set\_as\_target

This Tcl command sets a SDC, PDC or FDC file as the target file to receive and store new constraints.

```
set_as_target -type {constraint_file_type} \  
-file {constraint_file_path}
```

### Arguments

`-type {sdc | pdc | fdc}`

Specifies the file type: SDC, PDC, or FDC.

### Example

This command sets the SDC file `<project_folder> /constraints/user.sdc` as the target to receive and store new SDC commands.

```
set_as_target -type {sdc} -file {./constraint/user.sdc}
```

This command sets the PDC file `<project_folder> /constraints/user.pdc` as the target to receive and store new PDC commands.

```
set_as_target -type {pdc} -file {./constraint/user.pdc}
```

### Return Value

This command returns 0 on success and 1 on failure.

## set\_device (Project Manager)

Tcl command; sets your device family, die, and package in the Project Manager.

```
set_device [-family family] [-die die] [-package package] [-speed speed_grade] [-adv_options value]
```

### Arguments

-family *family*

Sets device family.

-die *die*

Sets device die.

-package *package*

Sets device package.

-speed *speed\_grade*

Sets device speed grade.

-adv\_options *value*

Sets your advanced options, such as temperature and voltage settings.

| Value               | Description                                                                                                                  |
|---------------------|------------------------------------------------------------------------------------------------------------------------------|
| IO_DEFT_STD:LVTTTL  | Sets your I/O default value to LVTTTL                                                                                        |
| TEMPR:COM           | Sets your default temperature range; can be COM (Commercial), MIL (Military) or IND (industrial).                            |
| VCCI_1.5_VOLTR:COM  | Sets VCCI to 1.5 and voltage range to Commercial                                                                             |
| VCCI_1.8_VOLTR:COM  | Sets VCCI to 1.8 and voltage range to Commercial                                                                             |
| VCCI_2.5_VOLTR:COM  | Sets VCCI to 2.5 and voltage range to Commercial                                                                             |
| VCCI_3.3_VOLTR:COM  | Sets VCCI to 3.3 and voltage range to Commercial                                                                             |
| VOLTR:COM           | Sets your voltage range; can be COM (Commercial), MIL (Military) or IND (industrial).                                        |
| RESTRICTPROBEPINS:1 | (For SmartFusion2, IGLOO2 and RTG4 only) Sets to 1 to reserve your pins for probing if you intend to debug using SmartDebug. |

### See Also

[How to Derive Required Part Information from A "Part Number"](#)

## set\_modelsim\_options

Tcl command; sets your ModelSim simulation options.

```
set_modelsim_options
[-use_automatic_do_file value]
[-user_do_file {path}]
[-sim_runtime {value}]
[-tb_module_name {value}]
[-tb_top_level_name {value}]
```

```

[-include_do_file value
[-included_do_file {value}]
[-type {value}]
[-resolution {value}]
[-add_vsim_options {value}]
[-display_dut_wave value]
[-log_all_signals value]
[-do_file_args value]
[-dump_vcd "TRUE | FALSE"]
[-vcd_file "VCD file name"]

```

## Arguments

`-use_automatic_do_file value`

Uses an automatic.do file in your project. Possible values are:

| Value | Description                                                                 |
|-------|-----------------------------------------------------------------------------|
| TRUE  | Uses the default automatic.do file in your project.                         |
| FALSE | Uses a different *.do file; use the other simulation options to specify it. |

`-user_do_file {path}`

Specifies the location of your user-defined \*.do file.

`-sim_runtime {value}`

Sets your simulation runtime. Value is the number and unit of time, such as {1000ns}.

`-tb_module_name {value}`

Specifies your testbench module name, where value is the name.

`-tb_top_level_name {value}`

Sets the top-level instance name in the testbench, where value is the name.

`-include_do_file value`

Includes a \*.do file; possible values are:

| Value | Description                    |
|-------|--------------------------------|
| TRUE  | Includes the *.do file.        |
| FALSE | Does not include the *.do file |

`-included_do_file {value}`

Specifies the path of the included \*.do file, where value is the name of the file.

`-type {value}`

Resolution type; possible values are:

| Value | Description |
|-------|-------------|
| min   | Minimum     |
| typ   | Typical     |
| max   | Maximum     |

`-resolution {value}`

Sets your resolution value, such as {1ps}.

`-add_vsim_options {value}`

Adds more Vsim options, where value specifies the option(s).

`-display_dut_wave value`

Enables ModelSim to display signals for the tested design; possible values are:

| Value | Description                                                   |
|-------|---------------------------------------------------------------|
| 0     | Displays the signal for the top_level_testbench               |
| 1     | Enables ModelSim to display the signals for the tested design |

`-log_all_signals value`

Enables you to log all your signals during simulation; possible values are:

| Value | Description              |
|-------|--------------------------|
| TRUE  | Logs all signals         |
| FALSE | Does not log all signals |

`-do_file_args value`

Specifies \*.do file command parameters.

`-dump_vcd value`

Dumps the VCD file when simulation is complete; possible values are:

| Value | Description                |
|-------|----------------------------|
| TRUE  | Dumps the VCD file         |
| FALSE | Does not dump the VCD file |

`-vcd_file {value}`

Specifies the name of the dumped VCD file, where value is the name of the file.

## Example

Sets ModelSim options to use the automatic \*.do file, sets simulation runtime to 1000ns, sets the testbench module name to "testbench", sets the testbench top level to <top>\_0, sets simulation type to "max", resolution to 1ps, adds no vsim options, does not log signals, adds no additional DO file arguments, dumps the VCD file with a name power.vcd.

```
set modelsim_options -use_automatic_do_file 1 -sim_runtime {1000ns} -tb_module_name
{testbench} -tb_top_level_name {<top>_0} -include_do_file 0 -type {max} -resolution
{1ps} -add_vsim_options {} -display_dut_wave 0 -log_all_signals 0 -do_file_args {} -
dump_vcd 0 -vcd_file {power.vcd}
```

## set\_option

Tcl command; sets your synthesis and FPGA Hardware Breakpoint Auto Instantiation options on a module.

```
set_option [-synth "TRUE | FALSE"] [-fhw "TRUE | FALSE"] [-module "module_name"]
```

## Arguments

`-synth "TRUE | FALSE"`

Runs synthesis (for a value of TRUE).

`-fhb "TRUE | FALSE"`

Enable/disable FPGA Hardware Breakpoint Auto Instantiation.

`-module module_name`

Identifies the module on which you will run synthesis.

## Example

Run synthesis on the module test1.vhd:

```
set_option [-synth TRUE] [-module <module_name>]
```

## set\_root

Tcl command; sets the module you specify as the root.

```
set_root module_name
```

## Arguments

`set_root module_name`

Specifies the name the module you want to set as root.

## Example

Set the module mux8 as root:

```
set_root mux8
```

## set\_user\_lib\_options

Tcl command; sets your user library options during simulation. If you do not use a custom library these options are not available.

```
set_user_lib_options
-name {value}
-path {path}
-option {value}
```

## Arguments

`-name {value}`

Sets the name of your user library.

`-path {path}`

Sets the pathname of your user library.

`-option {value}`

Sets your default compile options on your user library; possible values are:

| Value          | Description                  |
|----------------|------------------------------|
| do_not_compile | User library is not compiled |
| refresh        | User library is refreshed    |
| compile        | User library is compiled     |

| Value               | Description                            |
|---------------------|----------------------------------------|
| recompile           | User library is recompiled             |
| refresh_and_compile | User library is refreshed and compiled |

## Example

The example below sets the name for the user library to "test1", the path to c:/msemi\_des\_files/libraries/test1, and the compile option to "do not compile".

```
set_user_lib_options -name {test1} -path {c:/msemi_des_files/libraries/test1} -option {do_not_compile}
```

## unlink

Tcl command; removes a link to a file in your project.

```
unlink -file filename [-local local_filename]
```

## Arguments

-file *filename*

Name of the linked (remote) file you want to unlink.

-local *local\_filename*

Name of the local file that you want to unlink.

## Example

Unlink the file hdl1.vhd from my local file test.vhd

```
unlink -file hdl1.vhd [-local test.vhd]
```

## unset\_as\_target

This Tcl command unsets a target file in the Constraints view.

```
unset_as_target -file {filename}
```

## Arguments

-file {*filename*}

Specifies the name of the file to be unset as a target.

## Example

This command unsets the PDC file <project\_folder> /constraints/user.pdc:

```
unset_as_target -file {c:/user/a_io.pdc}
```

## Return Value

This command returns 0 on success and 1 on failure.

## use\_source\_file

Tcl command; defines a module for your project.

```
use_source_file  
-file value  
-module value
```

## Arguments

-file *value*

Specifies the Verilog or VHDL file. Value is the name of the file you wish use (including the full pathname).

-module *value*

Specifies the module in which you want to use the file.

## Example

Specify file1.vhd in the ./project/hdl directory, in the module named top.

```
use_source_file -file "./project/hdl/file1.vhd" -module "top"
```

## See Also

[use\\_file](#)

---

# SmartDesign Tcl Commands

---

The SmartDesign Tcl commands can be used to create a design in the SmartDesign. You must either create or open a SmartDesign before you can use any of the SmartDesign commands - sd\_\*. .

All SmartDesign Tcl commands are supported by the PolarFire family.

## sd\_add\_pins\_to\_group

Tcl command; adds one or more pins to a pin group on an instance in a SmartDesign component.

```
sd_add_pins_to_group \  
-sd_name smartdesign_component_name \  
-instance_name instance_name \  
-group_name group_name \  
-pin_names pin_names
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance on which the pin group is present. It is mandatory.

-group\_name *group\_name*

Specifies the name of the group to add the pins to. It is mandatory.

-pin\_names *pin\_names*

Specifies the list of instance pins to be added to the pin group. It is mandatory.

### Examples

```
sd_add_pins_to_group -sd_name {TOP} -instance_name  
{COREAXI4INTERCONNECT_C0_0} -group_name {Group} -pin_names {ARESETN ACLK}
```

#### See Also

[Tcl Command Documentation Conventions](#)

## sd\_clear\_pin\_attributes

Tcl command; clears all attributes on one or more pins/ports in a SmartDesign. Pin attributes include pin inversion, mark as unused and constant value settings.

```
sd_clear_pin_attributes \  
-sd_name smartdesign_component_name \  
-pin_names port_or_pin_names
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_names *port\_or\_pin\_names*

Specifies the name of the port/pin for which all the attributes must be cleared. It is mandatory.

## Examples

```
sd_clear_pin_attributes -sd_name {sd1} -pin_names {RAM1K18_0:A_DOUT_CLK}
sd_clear_pin_attributes -sd_name {top} -pin_names {CARRY_OUT}
```

## Notes

This command will not work on multiple pins/ports in this release. Support for multiple pins/ports will be provided in the next Libero release. This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_configure\_core\_instance

Tcl command; configures the parameters of a core instance (Direct Instantiation) in a SmartDesign component. This command is typically used after instantiating a core from the catalog directly into a SmartDesign component (Direct Instantiation) without first creating a component for the core (using `sd_instantiate_core`). This command can configure multiple core parameters at a time.

```
sd_configure_core_instance \
-sd_name smartdesign_component_name \
-instance_name core_instance_name \
-params core_parameters \
[-validate_rules 0|1]
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-instance_name` *instance\_name*

Specifies the name of the core instance in the SmartDesign which needs to be configured. It is mandatory.

`-params` *core\_parameters*

Specifies the parameters that need to be configured for the core instance. It is mandatory.

`-validate_rules` *0|1*

Validates the rules of the updated configuration. It is optional.

## Examples

```
sd_configure_core_instance -sd_name {SD1} -instance_name {COREFIFO_0} -
params {"SYNC:0" "param2:value2" "param3:value3"} -validate_rules 0
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_connect\_instance\_pins\_to\_ports

Tcl command; connects all pins of an instance to new SmartDesign top level ports.

```
sd_connect_instance_pins_to_ports \
-sd_name smartdesign_component_name \
-instance_name instance_name
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-instance_name` *instance\_name*

Specifies the instance name for which all the pins must be connected to top level ports. It is mandatory. The instance pins are connected to new top level ports created with the same instance pin names. If a top level port with the same name already exists, then the tool automatically creates a new port with name `<port_name>_<index>` (index is an automatically generated integer starting at 0 such that the port name is unique in the SmartDesign).

## Examples

```
sd_connect_instance_pins_to_ports -sd_name {top} -instance_name
{CORESPI_C0_0}
sd_connect_instance_pins_to_ports -sd_name {top} -instance_name
{ddr_out_0}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_connect\_pins\_to\_constant

Tcl command; connects SmartDesign top level output ports or input instance pins to constant values.

```
sd_connect_pins_to_constant \
-sd_name smartdesign_component_name \
-pin_names port_or_pin_names \
-value constant_value
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-pin_names` *port\_or\_pin\_names*

Specifies the names of the top level output ports or the instance level input pins to be tied to constant values. It is mandatory. Bus pins/ports and pin/port slices can also be tied to constant values. This command will fail if the specified port/pin does not exist. The command will also fail if the assigned object is a port of direction IN/INOUT or a pin of direction OUT/INOUT.

`-value` *constant\_value*

Specifies the constant value to be assigned to the port/pin. It is mandatory. The acceptable values to this argument are GND/VCC/hexadecimal numbers.

## Examples

```
sd_connect_pins_to_constant -sd_name {top} -pin_name {bypass} -value
{GND}
sd_connect_pins_to_constant -sd_name {top} -pin_name {sle_0:en} -value
{VCC}
sd_connect_pins_to_constant -sd_name {top} -pin_name {ram64x12_0:w_data}
-value {0x7f}
```

## Notes

This command will not work on multiple pins/ports in this release. Support for multiple pins/ports will be provided in the next Libero release.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_connect\_pin\_to\_port

Tcl command; connects a SmartDesign instance pin to a new top level port. This command is equivalent to the 'Promote to Top Level' GUI action on an instance pin.

```
sd_connect_pin_to_port \
-sd_name smartdesign_component_name \
-pin_name pin_name \
[-port_name port_name]
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_name *pin\_name*

Specifies the name of the instance level pin that needs to be connected to a top level port. It is mandatory.

-port\_name *port\_name*

Specifies the name of the new top level port that the instance pin will be connected to. It is optional. If the port name is not specified, the new port takes the name of the instance pin. If the port name as defined by these rules already exists, the tool automatically creates a new port with name <port\_name>\_<index> (index is an automatically generated integer starting at 0 such that the port name is unique in the SmartDesign).

## Examples

```
sd_connect_pin_to_port -sd_name {top} -pin_name {DFN1_0:D}
sd_connect_pin_to_port -sd_name {top} -pin_name {DFN1_0:Q} -port_name
{Q_OUT}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_connect\_pins

Tcl command; connects a list of SmartDesign top level ports and/or instance pins together.

```
sd_connect_pins \
-sd_name smartdesign_component_name \
-pin_names port_or_pin_or_slice_names_
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_names *port\_or\_pin\_or\_slice\_names*

Specifies the port names, pin names and/or slice names to be connected together. It is mandatory. This command will fail if the ports, pins or slices do not exist. This command will also fail if the ports, pins and/or slices are not of the same size/range.

## Examples

```
sd_connect_pins -sd_name {top} -pin_names {CLK MACC_PA_0:CLK DFN1_0:CLK}
sd_connect_pins -sd_name {top} -pin_names {MACC_PA_0:A
RAM1K20_0:A_DIN[17:0]}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_create\_bif\_port

Tcl command; creates a SmartDesign Bus Interface port of a given type. This command is used to create top level Bus Interface ports in a SmartDesign component to connect to the instance level Bus Interface ports of the same type.

To use this command, it is recommended to first use the GUI to instantiate the core component or the HDL module with Bus Interface port to be promoted in the SmartDesign. Then use the UI action "Promote to Top Level" on the Bus Interface port of interest and export the Tcl script for the SmartDesign component by selecting "Export Component Description(Tcl)" on the right-click menu of the SmartDesign component in the Design Hierarchy. You can then use the Tcl command 'sd\_create\_bif\_port' from the exported Tcl script (note to change the SmartDesign name in the command) to create a bus interface port anywhere in a regular Libero script. Note that there can be different Bus Interface types and roles defined by the arguments -port\_bif\_vlnv and -port\_bif\_role.

```
sd_create_bif_port \
-sd_name smartdesign_component_name \
-port_name port_name \
-port_bif_vlnv vendor:library:name:version \
-port_bif_role port_bif_role \
-port_bif_mapping [bif_port_name:port_name]+
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-port\_name *port\_name*

Specifies the name of the Bus Interface port to be added in the SmartDesign. It is mandatory.

port\_bif\_vlnv {*vendor:library:name:version*}

Specifies the version identifier of the Bus Interface port to be added in the SmartDesign. It is mandatory.

-port\_bif\_role {*port\_bif\_role*}

Specifies the role of the Bus Interface port to be added in the SmartDesign. Role values depend on the type of Bus Interface (VLNv) that is being defined for the port. The figure below shows the roles for different Bus Interface ports supported by Libero.

| Name              | Vendor | Library       | Role           |
|-------------------|--------|---------------|----------------|
| AHB               | AMBA   | AMBA2         | master         |
| AHB               | AMBA   | AMBA2         | slave          |
| AHB               | AMBA   | AMBA2         | mirroredMaster |
| AHB               | AMBA   | AMBA2         | mirroredSlave  |
| APB               | AMBA   | AMBA2         | master         |
| APB               | AMBA   | AMBA2         | slave          |
| APB               | AMBA   | AMBA2         | mirroredMaster |
| APB               | AMBA   | AMBA2         | mirroredSlave  |
| AXI               | AMBA   | AMBA3         | master         |
| AXI               | AMBA   | AMBA3         | slave          |
| AXI               | AMBA   | AMBA3         | mirroredMaster |
| AXI               | AMBA   | AMBA3         | mirroredSlave  |
| AXI               | AMBA   | AMBA3         | system         |
| AXI4              | AMBA   | AMBA4         | master         |
| AXI4              | AMBA   | AMBA4         | slave          |
| AXI4              | AMBA   | AMBA4         | mirroredMaster |
| AXI4              | AMBA   | AMBA4         | mirroredSlave  |
| DDR3              | Actel  | busdef.memory | master         |
| DDR3              | Actel  | busdef.memory | slave          |
| PF_APB_LINK       | Actel  | busdef.link   | master         |
| PF_APB_LINK       | Actel  | busdef.link   | slave          |
| PF_CDR_CLK        | Actel  | busdef.clock  | master         |
| PF_CDR_CLK        | Actel  | busdef.clock  | slave          |
| PF_DRI            | Actel  | busdef.dri    | master         |
| PF_DRI            | Actel  | busdef.dri    | slave          |
| PF_DRI            | Actel  | busdef.dri    | mirroredMaster |
| PF_DRI            | Actel  | busdef.dri    | mirroredSlave  |
| PF_TXPLL_XCVR_CLK | Actel  | busdef.clock  | master         |
| PF_TXPLL_XCVR_CLK | Actel  | busdef.clock  | slave          |

```
-port_bif_mapping {[bif_port_name:port_name ]+}
```

Specifies the mapping between the bus interface formal names and the SmartDesign ports mapped onto that bus interface port. It is mandatory.

## Examples

```
sd_create_bif_port -sd_name {sd1} -port_name {BIF_1} -port_bif_vlnv
{AMBA:AMBA2:APB:r0p0} -port_bif_role {slave} -port_bif_mapping {\
  "PADDR:PADDR" \
  "PSELx:pselx" \
  "PENABLE:PENABLE" \
  "PWRITE:PWRITE" \
  "PRDATA:PRDATA" \
  "PWDATA:PWDATA" \
  "PREADY:PREADY" \
  "PSLVERR:PSLVERR" }
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_create\_bus\_port

Tcl command; creates a bus port of a given range in a SmartDesign component.

```
sd_create_bus_port \
-sd_name smartdesign_component_name \
-port_name port_name -port_direction IN|OUT|INOUT \
-port_range {[left_range_index:right_range_index]}
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-port\_name *port\_name*

Specifies the name of the bus port added to be SmartDesign component. It is mandatory.

-port\_direction *IN|OUT|INOUT*

Specifies the direction of the bus port added to the SmartDesign component. It is mandatory.

-port\_range {[*left\_range\_index:right\_range\_index*]}

Specifies the range of the bus port added to the SmartDesign component. The range is defined by the left and right indices. It is mandatory. The range must be specified inside the square brackets.

### Examples

```
sd_create_bus_port -sd_name {top} -port_name {test_port13} -port_direction {OUT} -
port_range {[9:36]}
sd_create_bus_port -sd_name {top} -port_name {test_port4} -port_direction {IN} -
port_range {[31:0]}
```

#### See Also

[Tcl Command Documentation Conventions](#)

## sd\_create\_pin\_group

Tcl command; creates a group of pins in a SmartDesign component. A pin group is only used to manage the complexity of the SmartDesign canvas. There is no actual netlist functionality related to pin group commands. Pin groups cannot be created for top level ports.

```
sd_create_pin_group \
-sd_name smartdesign_component_name \
-instance_name instance_name \
[-group_name group_name] \
[-pin_names pin_to_be_added_to_the_group]
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance on which the pin group is added. It is mandatory.

-group\_name *group\_name*

Specifies the name of the pin group. It is optional. If the group name is not specified, the default name will be 'Group'. If the name 'Group' is already taken, then the group name will be 'Group\_<index>' (index is auto-incremented).

-pin\_names *pins\_to\_be\_added\_to\_the\_group*

Specifies the list of instance pins to be added to the pin group. It is optional.

## Examples

```
sd_create_pin_group -sd_name {TOP} -instance_name
{COREAXI4INTERCONNECT_C0_0} -group_name {MyGroup} -pin_names {ACLK
ARESETN}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_create\_pin\_slices

Tcl command; creates slices for a SmartDesign top level bus port or an instance level bus pin.

```
sd_create_pin_slices \
-sd_name smartdesign_component_name \
-pin_name port_or_pin_name \
-pin_slices port_or_pin_slices
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_name *port\_or\_pin\_name*

Specifies the name of the bus port or bus pin to be sliced. It is mandatory. This command will fail if the port/pin is scalar or if the bus port/pin does not exist.

-pin\_slices *port\_or\_pin\_slices*

Specifies the port/pin slices as a list of bus ranges which must be contained within the port/pin bus range. It is mandatory. This command will fail if the sliced object is top level OUT/INOUT port and the slice ranges overlap. This command will also fail if the sliced object is an instance level IN/INOUT pin and the slice ranges overlap.

## Examples

```
sd_create_pin_slices -sd_name {sub} -pin_name {Rdata} -pin_slices {[4:3] [2:0]} # top
level port slicing
sd_create_pin_slices -sd_name {sub} -pin_name {DDR_memory_arbiter_C0_0:VIDEO_RDATA_4_O}
-pin_slices {[3:3] [2:0]} # instance level pin slicing
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_create\_scalar\_port

Tcl command; creates a scalar port in a SmartDesign component.

```
sd_create_scalar_port \
-sd_name smartdesign_component_name \
-port_name port_name \
-port_direction IN|OUT|INOUT
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-port\_name *port\_name*

Specifies the name of the port added to the SmartDesign component. It is mandatory.

-port\_direction *IN|OUT|INOUT*

Specifies the direction of the port added to the SmartDesign component. It is mandatory.

## Examples

```
sd_create_scalar_port -sd_name {main} -port_name {po2} -port_direction {INOUT}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_delete\_instances

Tcl command; deletes one or more instances from a SmartDesign component.

```
sd_delete_instances \  
-sd_name smartdesign_component_name \  
-instance_names instance_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_names *instance\_names*

Specifies the instance names to be deleted. It is mandatory.

## Examples

```
sd_delete_instances -sd_name {top} -instance_names {RAM64X12_0}  
sd_delete_instances -sd_name {SUB} -instance_names {coreahblite_c0_0  
coreriscv_axi4_c0_0 pf_ccc_c0_0}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_delete\_nets

Tcl command; deletes one or more nets from the SmartDesign component.

```
sd_delete_nets \  
-sd_name smartdesign_component_name \  
-net_names net_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-net\_names *net\_names*

Specifies the net names to be deleted. It is mandatory.

## Examples

```
sd_delete_nets -sd_name {topp} -net_names {B_REN_0}
```

## Notes

This command will not delete multiple nets in this release. Support for deleting multiple nets will be provided in the next Libero release. This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_delete\_pin\_group

Tcl command; deletes a pin group from an instance in a SmartDesign component.

```
sd_delete_pin_group \  
-sd_name smartdesign_component_name \  
-instance_name instance_name \  
-group_name group_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-group\_name *group\_name*

Specifies the name of the pin group to be deleted. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance from which the group pin needs to be deleted. It is mandatory.

## Examples

```
sd_delete_pin_group -sd_name {TOP} -instance_name  
{COREAXI4INTERCONNECT_C0_0} -group_name {Group}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_delete\_pin\_slices

Tcl command; deletes SmartDesign top level port slices or instance pin slices.

```
sd_create_pin_slices \  
-sd_name smartdesign_component_name \  
-pin_name port_or_pin_name \  
-pin_slices port_or_pin_slices
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_name *port\_or\_pin\_name*

Specifies the name of the bus port or bus pin for which the slices must be deleted. It is mandatory.

-pin\_slices *port\_or\_pin\_slices*

Specifies the ranges of the port and/or pin slices to be deleted. It is mandatory.

## Examples

```
sd_delete_pin_slices -sd_name {top} -pin_name {MACC_pa_0:p} -pin_slices  
{[21] [13] [28]} # deletes instance pin slices  
sd_delete_pin_slices -sd_name {top} -pin_name {A} -pin_slices {[17:16]  
[15:1] [0]} # deletes top level port slices
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_delete\_ports

Tcl command; deletes one or more ports from the SmartDesign component.

```
sd_delete_ports \  
-sd_name smartdesign_component_name \  
-port_names port_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-port\_names *port\_names*

Specifies the names of the ports to be deleted. It is mandatory.

## Examples

```
sd_delete_ports -sd_name {sd1} -port_names {REF_CLK_0}
```

## Notes

This command will not work on multiple ports in this release. Support for multiple ports will be provided in the next Libero release. This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_disconnect\_instance

Tcl command; clears all the connections on an instance in a SmartDesign component.

```
sd_disconnect_instance \  
-sd_name smartdesign_component_name \  
-instance_name instance_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-instance_name` *instance\_name*

Specifies the name of the instance for which all the connections must be cleared. It is mandatory.

## Examples

```
sd_disconnect_instance -sd_name {sd1} -instance_name {RAM1K18_1}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_disconnect\_pins

Tcl command; disconnects a list of SmartDesign top level ports and/or instance pins from the net they are connected to.

```
sd_disconnect_pins \  
-sd_name smartdesign_component_name \  
-pin_names port_or_pin_or_slice_names
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-pin_names` *port\_or\_pin\_or\_slice\_names*

Specifies the port, pin and/or slice names to be disconnected. It is mandatory. This command will fail if the ports, pins and/or slices do not exist.

## Examples

```
sd_disconnect_pins -sd_name {topp} -pin_names {B_ren  
RAM1K20_0:B_ADDR[12]}  
  
sd_disconnect_pins -sd_name {SD1} -pin_names {AND2_0:B AND3_0:B AND3_0:A  
PF_XCVR_ERM_C0_0:LANE0_RX_READY}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_duplicate\_instance

Tcl command; creates a new instance in a SmartDesign with the same module/component as the original instance.

```
sd_duplicate_instance \  
-sd_name smartdesign_component_name \  
-instance_name instance_name \[-duplicate_instance_name duplicate_instance_name]
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance to be duplicated. It is mandatory.

-duplicate\_instance\_name *duplicate\_instance\_name*

Specifies the name of the duplicate instance. It is optional. If the duplicate\_instance\_name is not specified, it will be automatically generated as <instance\_name><index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

## Examples

```
sd_duplicate_instance -sd_name {top} -instance_name {PF_CCC_C0_0}
sd_duplicate_instance -sd_name {top} -instance_name {SUB_0} -
duplicate_instance_name {T1}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_hide\_bif\_pins

Tcl command; hides one or more already exposed internal scalar or bus pins/ports of a Bus Interface pin/port.

```
sd_hide_bif_pins \
-sd_name smartdesign_component_name \
-bif_pin_name name_of_the_bif_pin_or_port \-pin_names pins_or_ports_to_be_exposed
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-bif\_pin\_name *name\_of\_the\_bif\_pin\_name*

Specifies the name of the Bus Interface pin for which the internal pins must be hidden. It is mandatory.

-pin\_name *pins\_to\_be\_exposed*

Specifies the bus interface internal pin/port names to be hidden. It is mandatory.

## Examples

```
sd_hide_bif_pins -sd_name {sd1} -bif_pin_name {COREAXI4INTERCONNECT_C0_0:AXI4mmaster0} -
pin_names {COREAXI4INTERCONNECT_C0_0:MASTER0_AWADDR}
```

```
sd_hide_bif_pins -sd_name {SD1} -bif_pin_name {CLKS_FROM_TXPLL_0} -pin_names
{TX_PLL_LOCK_0}
```

## Notes

This command will not hide multiple pins/ports in this release. Support to hide multiple pins/ports will be provided in the next Libero release. This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_instantiate\_component

Tcl command; instantiates a Libero SmartDesign component or a core component into another SmartDesign component.

```
sd_instantiate_component \
-sd_name smartdesign_component_name \
-component_name component_module_name \
[-instance_name instance_name]
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component in which other components will be instantiated. It is mandatory.

-component\_name *component\_module\_name*

Specifies the name of the component being instantiated in the SmartDesign component. It is mandatory. The components include SmartDesign components, core components created for different types of cores from the catalog and blocks.

-instance\_name *instance\_name*

Specifies the instance name of the Libero component being instantiated in the SmartDesign component. It is optional. By default, the instance name is <component\_module\_name>\_<index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

### Examples

```
sd_instantiate_component -sd_name {sub} -component_name {sd1} -
instance_name {sd1_0}
sd_instantiate_component -sd_name {top} -component_name {PF_CCC_C0}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_instantiate\_core

Tcl command; instantiates a core from the catalog directly into a SmartDesign component (Direct Instantiation) without first having to create a component for the core. The file-set related to the core is generated only when the SmartDesign in which the core is instantiated is generated. The GUI equivalent of this command is not currently supported in Libero. To instantiate a core in a SmartDesign component in the GUI, you have to first create a component for the core.

```
sd_instantiate_core \
-sd_name smartdesign_component_name \-core_vlnv vendor:library:name:version \[-instance_name
instance_name]
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-core\_vlnv *vendor:library:name:version*

Specifies the version identifier of the core being instantiated in the SmartDesign component. It is mandatory.

`-instance_name` *instance\_name*

Specifies the instance name of the core being instantiated in the SmartDesign. It is optional. By default, the instance name is <core\_name>\_<index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

## Examples

```
sd_instantiate_core -sd_name {top} -core_vlnv
{Actel:DirectCore:COREAXI4INTERCONNECT:2.5.100} -instance_name
{COREAXI4INTERCONNECT_C0_0}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_instantiate\_hdl\_core

Tcl command; instantiates a HDL+ core in a SmartDesign component. HDL+ core definition must be created on a HDL module before using this command.

```
sd_instantiate_hdl_core \
-sd_name smartdesign_component_name \
-hdl_core_name hdl_core_module_name \
[-instance_name instance_name]
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-hdl_core_name` *hdl\_core\_module\_name*

Specifies the name of the HDL+ core module being instantiated in the SmartDesign component. It is mandatory.

`-instance_name` *instance\_name*

Specifies the instance name of the HDL+ core being instantiated in the SmartDesign. It is optional. By default, the instance name is <hdl\_core\_module\_name>\_<index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

## Examples

```
sd_instantiate_hdl_core -sd_name {top} -hdl_core_name {temp} -instance_name {temp3}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_instantiate\_hdl\_module

Tcl command; instantiates a HDL module in a SmartDesign component. The HDL file in which the HDL module is defined must be imported/linked before running this command.

```
sd_instantiate_hdl_module \
-sd_name smartdesign_component_name \-hdl_module_name hdl_module_name \-hdl_file hdl_file \
[-instance_name instance_name]
```

## Arguments

`-sd_name` *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

`-hdl_module_name` *hdl\_module\_name*

Specifies the name of the HDL module being instantiated in the SmartDesign component. It is mandatory.

-hdl\_file *hdl\_file*

Specifies the path of the HDL file in which the HDL module is defined. The HDL file path can be relative to project folder for imported files but the path has to be complete for linked files. It is mandatory.

-instance\_name *instance\_name*

Specifies the instance name of the HDL module. It is optional. By default, the instance name is <hdl\_module\_name>\_<index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

## Examples

```
sd_instantiate_hdl_module -sd_name {top} -hdl_module_name {and1} -hdl_file {hdl\and1.v}
sd_instantiate_hdl_module -sd_name {top} -hdl_module_name {and_ex} -hdl_file
{hdl\and_ex.v} -instance_name {test_hdl_hdl_module_name_plus1_1}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_instantiate\_macro

Tcl command; instantiates a Microsemi primitive macro in a SmartDesign component.

```
sd_instantiate_macro \
-sd_name smartdesign_component_name \
-macro_name macro_module_name |
[-instance_name instance_name]
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-macro\_name *macro\_module\_name*

Specifies the name of the macro being instantiated in the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the instance name of the macro. It is optional. By default, the instance name is <macro name>\_<index> (index is an automatically generated integer starting at 0 such that the instance name is unique in the SmartDesign).

## Examples

```
sd_instantiate_macro -sd_name {TOP} -macro_name {MX2} -instance_name {MX2_0}
sd_instantiate_macro -sd_name {TOP} -macro_name {MACC_PA}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_invert\_pins

Tcl command; inverts one or more top level ports or instance level pins in a SmartDesign.

```
sd_invert_pins \
-sd_name smartdesign_component_name \
-pin_names port_or_pin_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_names *port\_or\_pin\_names*

Specifies the port or pin names to be inverted. It is mandatory. This parameter can take multiple values. This command will fail if the port/pin does not exist.

## Examples

```
sd_invert_pins -sd_name {main} -pin_names {A}
sd_invert_pins -sd_name {main} -pin_names {MX2_1:S MX2_1:Y A B}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_mark\_pins\_unused

Tcl command; marks one or more SmartDesign instance level output pins as unused. When an output pin is marked as unused, no Design Rule Check (DRC) warning will be printed for floating output pins while generating the SmartDesign.

```
sd_mark_pins_unused \
-sd_name smartdesign_component_name \
-pin_names port_or_pin_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-pin\_names *port\_or\_pin\_names*

Specifies the names of the instance pins to be marked as unused. It is mandatory.

## Examples

```
sd_mark_pins_unused -sd_name {top} -pin_names {PF_CCC_C0_0:PLL_LOCK_0}
```

## Notes

This command will not work on multiple pins in this release. Support for multiple pins will be provided in the next Libero release.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_remove\_pins\_from\_group

Tcl command; removes one or more pins from a pin group on an instance in a SmartDesign.

```
sd_remove_pins_from_group \
-sd_name smartdesign_component_name \
-instance_name instance_name \
-group_name group_name \
-pin_names pin_names
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance on which the pin group is present. It is mandatory.

-group\_name *group\_name*

Specifies the name of the pin group from which pins need to be removed. It is mandatory.

-pin\_names *pin\_names*

Specifies the list of pin names to be removed from the pin group. It is mandatory.

## Examples

```
sd_remove_pins_from_group -sd_name {TOP} -instance_name
{COREAXI4INTERCONNECT_CO_0} -group_name {Group} -pin_names {ARESETN ACLK}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_rename\_instance

Tcl command; renames an instance in a SmartDesign component. This command can be used to rename any type of instances (instances of other SmartDesigns components, core components, HDL modules, HDL+ cores and Microsemi macros) in a SmartDesign.

```
sd_rename_instance \
-sd_name component_name \
-current_instance_name instance_name \
-new_instance_name new_instance_name
```

## Arguments

-sd\_name *component\_name*

Specifies the name of the SmartDesign component in which the instance name has to be renamed. It is mandatory.

-current\_instance\_name *instance\_name*

Specifies the name of the instance to be renamed. It is mandatory.

-new\_instance\_name *new\_instance\_name*

Specifies the new instance name. It is mandatory.

## Examples

```
sd_rename_instance -sd_name {top} -current_instance_name {DFN1_0} -
new_instance_name {DFN1_new}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_rename\_pin\_group

Tcl command; renames a pin group on an instance in a SmartDesign component.

```
sd_rename_pin_group \  
-sd_name smartdesign_component_name \  
-instance_name instance_name \  
-current_group_name current_pin_group_name \  
-new_pin_group_name new_pin_group_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance on which the pin group is present. It is mandatory.

-current\_group\_name *current\_pin\_group\_name*

Specifies the name of the pin group to be renamed. It is mandatory.

-new\_group\_name *new\_group\_name*

Specifies the new name of the pin group. It is mandatory.

## Examples

```
sd_rename_pin_group -sd_name {TOP} -instance_name  
{COREAXI4INTERCONNECT_C0_0} -current_group_name {Group} -new_group_name  
{MyNewGroup}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_rename\_port

Tcl command; renames a SmartDesign port.

```
sd_rename_port \  
-sd_name smartdesign_component_name \  
-current_port_name port_name \  
-new_port_name new_port_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-current\_port\_name *port\_name*

Specifies the name of the port to be renamed in the SmartDesign component. It is mandatory. Note that only port names can be renamed, and not port types (scalar ports cannot be renamed as bus ports and vice versa).

-new\_port\_name *new\_port\_name*

Specifies the new name of the specified port. It is mandatory.

## Examples

```
sd_rename_port -sd_name {top} -library {work} -current_port_name {c1} -new_port_name  
{c2}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_save\_core\_instance\_config

Tcl command; this command is used to save the core instance configuration specified using one or more 'sd\_configure\_core\_instance' commands. This command is typically used after configuring a core instance in a SmartDesign, to save that core instance's configuration.

```
sd_save_core_instance_config \  
-sd_name smartdesign_component_name \  
-instance_name core_instance_name
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the core instance in the SmartDesign for which the configuration must be saved. It is mandatory.

### Examples

```
sd_save_core_instance_config -sd_name {SD1} -instance_name {COREFIFO_0}
```

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_show\_bif\_pins

Tcl command; exposes one or more internal scalar or bus pins/ports of a Bus Interface pin/port. A Bus Interface pin/port is usually a group of normal scalar or bus pins/ports grouped together and used to connect instances that have similar interfaces. The internal pins/ports underneath the Bus Interface pin/port may have to be exposed in some cases to connect to some logic in the design.

```
sd_show_bif_pins \  
-sd_name smartdesign_component_name \  
-bif_pin_name name_of_the_bif_pin_or_port \  
-pin_names pins_or_ports_to_be_exposed
```

### Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-bif\_pin\_name *name\_of\_the\_bif\_pin\_or\_port*

**Specifies the name of the Bus Interface pin/port for which the internal pins/ports need to be exposed. It is mandatory.**

-pin\_names *pins\_or\_ports\_to\_be\_exposed*

Specifies the names of the Bus Interface internal pins/ports to be exposed. It is mandatory.

### Examples

```
sd_show_bif_pins -sd_name {TOP} -bif_pin_name {COREAXI4INTERCONNECT_C0_0:AXI4mmaster0} -  
pin_names {COREAXI4INTERCONNECT_C0_0:MASTER0_AWADDR}
```

```
sd_show_bif_pins -sd_name {SD1} -bif_pin_name {CLKS_FROM_TXPLL_0} -pin_names  
{TX_PLL_LOCK_0}
```

## Notes

This command will not expose multiple pins/ports in this release. Support to expose multiple scalar or bus pins/ports will be provided in the next Libero release.

### See Also

[Tcl Command Documentation Conventions](#)

## sd\_update\_instance

Tcl command; updates an instance in a SmartDesign with its latest definition. This command is useful when the interface (port-list) of the component/module instantiated in a SmartDesign has changed. This command can be used to update any type of instance such as instances of other SmartDesign components, core components, HDL modules and HDL+ cores in a SmartDesign.

```
sd_update_instance \  
-sd_name smartdesign_component_name \  
-instance_name instance_name
```

## Arguments

-sd\_name *smartdesign\_component\_name*

Specifies the name of the SmartDesign component. It is mandatory.

-instance\_name *instance\_name*

Specifies the name of the instance to be updated. It is mandatory.

## Examples

```
sd_update_instance -sd_name {top} -instance_name {CORESMIP_C0_0}
```

## Notes

This command is not required to build a SmartDesign component. This command maps to an interactive user action in the SmartDesign Canvas and will not be present in the exported SmartDesign component Tcl description.

### See Also

[Tcl Command Documentation Conventions](#)

---

# HDL Tcl Commands

---

## create\_hdl\_core

This Tcl command is used to create a core component from an HDL core.

```
create_hdl_core \  
-module {module_name} \  
-file {file_path} \  
-library {library_name} \  
-package {package_name}
```

### Arguments

-module {*module\_name*}

Specify the module name for which you want to create a core component. This is a mandatory argument.

-file {*file\_path*}

Specify the file path of the module from which you create a core component. This is a mandatory argument.

-library {*library\_name*}

Specify the library name from which you want to create a HDL core. This is an optional argument.

-package {*package\_name*}

Specify the package name from which you want to create a core component. This is an optional argument.

### Example

```
create_hdl_core -file {./HDL_CORE_TEST/hdl/hdl_core.v} -module {test_hdl_core}
```

#### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_add\_bif

This Tcl command adds a bus interface to an HDL core.

```
hdl_core_add_bif \  
-hdl_core_name {hdl_core_name} \  
-bif_definition {Name:Vendor:Library:Role} \  
-bif_name {bus_interface_name} \  
[-signal_map {signal_map}]
```

### Arguments

-module {*module\_name*}

Specify the HDL core name to which the bus interface needs to be added. This is a mandatory argument.

-bif\_definition {*Name:Vendor:Library:Role*}

Specify the Bus Interface Definition Name, Vendor, Library and Bus Role of the core in the format {N:V:L:R}. This is a mandatory argument.

-bif\_name {*bus\_interface\_name*}

Specify the bus interface port name being added to the HDL core. This is a mandatory argument.

```
-signal_map {signal_map}
```

This argument is used to specify the signal map of the bus interface. This is an optional argument.

## Example

```
hdl_core_add_bif -hdl_core_name {test_hdl_core} -bif_definition {AHB:AMBA:AMBA2:master} -
bif_name {BIF_1}
```

### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_assign\_bif\_signal

Maps a bus interface signal definition name to an HDL core module port name.

```
hdl_core_assign_bif_signal
-hdl_core_name {hdl_core_name} \
-bif_name {bus_interface_name} \
-bif_signal_name {bif_signal_name} \
-core_signal_name {core_signal_name}
```

## Arguments

```
-hdl_core_name {hdl_core_name}
```

Specify the HDL core name to which the bus interface signal needs to be added. This is a mandatory argument.

```
-bif_name {bus_interface_name}
```

Specify the bus interface name for which you want to map a core signal. This is a mandatory argument.

```
-bif_signal_name {bus_interface_signal_name}
```

Specify the bus interface signal name that you want to map with the core signal name. This is a mandatory argument.

```
-core_signal_name {core_signal_name}
```

Specify the core signal name for which you want to map the bus interface signal name. This is a mandatory argument.

## Example

```
hdl_core_assign_bif_signal -hdl_core_name {test_hdl_core} -bif_name {BIF_1} -
bif_signal_name {HWRITE} -core_signal_name {myHRESULT}
```

### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_delete\_parameters

This Tcl command deletes parameters from a HDL core definition.

```
hdl_core_delete_parameters
-hdl_core_name {module_name} \
-parameters {parameter_list}
```

## Arguments

```
-hdl_core_name {hdl_core_name}
```

Specify the HDL core name from which you want to delete parameters. This is a mandatory argument.

```
-parameters {parameter_list}
```

Specify the list of parameters from a HDL core. This is typically done to remove parameters from the list of parameters that was automatically extracted using the `hdl_core_extract_ports_and_params` command. This is a mandatory argument.

## Example

```
hdl_core_delete_parameters -hdl_core_name {test_hdl_core} -parameters {WIDTH}
```

### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_extract\_ports\_and\_parameters

This Tcl command automatically extracts ports and generic parameters from an HDL core module description.

```
hdl_core_extract_ports_and_parameters \  
-hdl_core_name {hdl_core_name}
```

## Arguments

`-hdl_core_name` *hdl\_core\_name*

Specifies the HDL core name from which you want to extract signal names and generic parameters. This is a mandatory argument.

## Example

```
hdl_core_extract_ports_and_params -hdl_core_name {test_hdl_core}
```

### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_remove\_bif

Remove an existing bus interface from an HDL core.

```
hdl_core_remove_bif \  
-hdl_core_name {hdl_core_name} \  
-bif_name {bus_interface_name}
```

## Arguments

`-module` *{module\_name}*

Specify the HDL core name from which the bus interface needs to be removed. This is a mandatory argument.

`-bif_name` *{bus\_interface\_name}*

Specify the bus interface name that needs to be removed from the HDL core. This is a mandatory argument.

## Example

```
hdl_core_remove_bif -hdl_core_name {mod1} -bif_name {BIF_1}
```

### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_rename\_bif

Rename an existing bus interface port of a HDL core.

```
hdl_core_rename_bif
-hdl_core_name {hdl_core_name} \
-current_bif_name {current_bus_interface_name} \
-new_bif_name {new_bus_interface_name}
```

### Arguments

-hdl\_core\_name {hdl\_core\_name}

Specify the HDL core name for which the bus interface needs to be renamed. This is a mandatory argument.

-current\_bif\_name {current\_bus\_interface\_name}

Specify the bus old bus interface name that needs to be renamed for the HDL core. This is a mandatory argument.

-new\_bif\_name {new\_bus\_interface\_name}

Specify the new bus interface name that needs to be updated for the HDL core. This is a mandatory argument.

### Example

```
hdl_core_rename_bif -hdl_core_name {test_hdl_plus} -current_bif_name {BIF_2} -
new_bif_name {BIF_3}
```

#### See Also

[Tcl Command Documentation Conventions](#)

## hdl\_core\_unassign\_bif\_signal

Unmap an existing bus interface signal from a bus interface.

```
hdl_core_unassign_bif_signal
-hdl_core_name {hdl_core_name} \
-bif_name {bus_interface_name} \
-bif_signal_name {bif_signal_name}
```

### Arguments

-hdl\_core\_name {hdl\_core\_name}

Specify the HDL core name from which the bus interface signal needs to be deleted. This is a mandatory argument.

-bif\_name {bus\_interface\_name}

Specify the bus interface name for which you want to unassign a core signal. This is a mandatory argument.

-bif\_signal\_name {bus\_interface\_signal\_name}

Specify the bus interface signal name for which you want to unassign a core signal. This argument is mandatory.

### Example

```
hdl_core_unassign_bif_signal -hdl_core_name {test_hdl_plus} -bif_name {BIF_2} -
bif_signal_name {PENABLE}
```

#### See Also

[Tcl Command Documentation Conventions](#)

## remove\_hdl\_core

This Tcl command removes an HDL core component from the current project.

```
remove_hdl_core \  
-hdl_core_name {hdl_core_name}
```

### Arguments

-hdl\_core\_name {hdl\_core\_name}

Specify the module name from which you want to delete a core component. This is a mandatory argument.

### Example

```
remove_hdl_core -hdl_core_name {test_hdl_core}
```

#### See Also

[Tcl Command Documentation Conventions](#)

# Command Tools

## CONFIGURE\_CHAIN

CONFIGURE\_CHAIN is a command tool used in run\_tool. The command run\_tool -name {CONFIGURE\_CHAIN} takes a script file that contains specific Tcl commands and passes them to FlashPro Express for execution.

```
run_tool -name {CONFIGURE_CHAIN} -script {fpro_cmds.tcl}
```

*fpro\_cmds.tcl* is a Tcl script that contains specific Tcl commands to configure JTAG chain. For details on JTAG chain programming Tcl commands, refer to the Tcl commands section in the Libero SoC Online Help.

Do not include any project-management commands such as open\_project, save\_project, or close\_project in this *fpro\_cmds.tcl* script file. The run\_tool -name {CONFIGURE\_CHAIN} command generates these project-management commands for you.

**Note:** For a new Libero project without a JTAG chain, executing this command causes Libero to first add the existing design device to the JTAG chain and then execute the commands from the script. If, for example, the script *fpro\_cmds.tcl* contains commands to add four devices, executing the command run\_tool -name {CONFIGURE\_CHAIN} -script {*fpro\_cmds.tcl*} will create a JTAG chain of the Libero design device and the four devices. For existing Libero projects that already have a JTAG chain, the command is executed on the existing JTAG chain.

### Example

```
run_tool -name {CONFIGURE_CHAIN} -script {d:/fpro_cmds.tcl}
#Example fpro_cmds.tcl command file for the -script parameter
add_actel_device \
  -file {./sd_prj/sp_g3/designer/impl1/sdl.stp} \
  -name {dev1}
enable_device -name {MPF300TS_ES} -enable 0
add_non_actel_device \
  -ir 2 \
  -tck 1.00 \
  -name {Non-Microsemi Device}
add_non_actel_device \
  -ir 2 \
  -tck 1.00 \
  -name {Non-Microsemi Device (2)}
remove_device -name {Non-Microsemi Device}
set_device_to_highz -name {MPF300TS_ES} -highz 1
add_actel_device \
  -device {MPF300TS_ES} \
  -name {MPF300TS_ES (3)}
select_libero_design_device -name {MPF300TS_ES (3)}
```

### Return

Returns 0 on success and 1 on failure.

## CONFIGURE\_PROG\_OPTIONS

CONFIGURE\_PROG\_OPTIONS is a command tool used in configure\_tool. Configure\_tool -name {CONFIGURE\_PROG\_OPTIONS} sets the programming options.

```
configure_tool -name {CONFIGURE_PROG_OPTIONS}
-params {design_version:<value>}
-params {silicon_signature:<value>}
```

The following table lists the parameter names and values.

### configure\_tool -name {CONFIGURE\_PROG\_OPTIONS} parameter:value pair

| Name              | Value                               | Description                                                                                                                                               |
|-------------------|-------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------|
| design_version    | Integer {0 through 65535}           | Sets the design version. It must be greater than the Back level version in SPM Update Policy.                                                             |
| silicon_signature | Hex {<max length 8 Hex characters>} | 32-bit (8 hex characters) silicon signature to be programmed into the device. This field can be read from the device using the JTAG USERCODE instruction. |

### Example

```
configure_tool -name {CONFIGURE_PROG_OPTIONS}\
-params {design_version:255}
-params {silicon_signature:abcdef}
```

### Return

Returns 0 on success and 1 on failure.

## GENERATEPROGRAMMINGFILE

GENERATEPROGRAMMINGFILE is a command tool used in the configure\_tool and run\_tool commands. The configure\_tool -name {GENERATEPROGRAMMINGFILE} Tcl command configures tool options. The run\_tool Tcl command runs the specified tool with the options specified in configure\_tool.

```
configure_tool \
-name {GENERATEPROGRAMMINGFILE} \
-params {program_fabric:true|false} \
-params {program_security:true|false} \
-params {program_snvm:true|false}
run_tool -name {GENERATEPROGRAMMINGFILE}
```

The following tables list the parameter names and values.

### configure\_tool -name {GENERATEPROGRAMMINGFILE} parameter:value pair

| Name           | Value        | Description                                            |
|----------------|--------------|--------------------------------------------------------|
| program_fabric | true   false | Include fabric component in the programming bitstream. |

| Name             | Value        | Description                                                                                                  |
|------------------|--------------|--------------------------------------------------------------------------------------------------------------|
| program_security | true   false | Include custom security component in the programming bitstream ("true" only if custom security was defined). |
| program_snvm     | true   false | Include sNVM component in the programming bitstream ("true" only if sNVM available in the design).           |

## run\_tool -name {GENERATEPROGRAMMINGFILE}

This command takes no parameters.

## IO\_PROGRAMMING\_STATE

IO\_PROGRAMMING\_STATE is a command tool used in the configure\_tool Tcl command. The configure\_tool -name {IO\_PROGRAMMING\_STATE} Tcl command loads the I/O State information from a file during programming. The file used for loading the I/O State information during programming is specified in a parameter to the command. Refer to the [Specify I/O States During Programming Dialog Box](#) for details .

```
configure_tool -name {IO_PROGRAMMING_STATE} -params\
{ios_file:absolute_path_to_i/o_state_information_file}
```

### Example

```
configure_tool -name {IO_PROGRAMMING_STATE} -params\
{ios_file:d:\sd_prj\tony_sf2\designer\sd1\sd1.ios}
```

### Return

Returns 0 on success and 1 on failure.

## PLACEROUTE

To place and route a design in Libero SoC, you must first configure the PLACEROUTE tool with the configure\_tool command and then execute the PLACEROUTE tool with the run\_tool command.

### configure\_tool

```
configure_tool -name {PLACEROUTE} [-params {[name:value ]+}] +
```

#### Parameters

| Name | Value                | Description                                                                     |
|------|----------------------|---------------------------------------------------------------------------------|
| TDPR | true   false   1   0 | Set to true or 1 to enable Timing-Driven Place and Route. Default is 1.         |
| PDPR | true   false   1   0 | Set to true or 1 to enable Power-Driven Place and Route. Default is false or 0. |

| Name                | Value                                                        | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|---------------------|--------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| IOREG_COMBINING     | true   false   1   0                                         | Set to true or 1 to enable I/O Register Combining. Default is false or 0                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| GB_DEMOTION         | true   false   1   0                                         | Set to true or 1 to enable Global Pins Demotion. Default is true or 1                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| EFFORT_LEVEL        | true   false   1   0                                         | Set to true or 1 to enable High Effort Layout to optimize design performance. Default is false or 0.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
| INCRPLACEANDROUTE   | true   false   1   0                                         | Set to true or 1 to use previous placement data as the initial placement for the next run. Default is false or 0.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
| REPAIR_MIN_DELAY    | true   false   1   0                                         | Set to 1 to enable Repair Minimum Delay violations for the router when TDPR option is set to true or 1. Default is false.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              |
| NUM_MULTI_PASSES    | 1-25                                                         | Specifies the number of passes to run. The default is 5. Maximum is 25.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |
| START_SEED_INDEX    | 1-100                                                        | Indicates the random seed index which is the starting point for the passes. Its value should range from 1 to 100. If not specified, the default behavior is to continue from the last seed index which was used.                                                                                                                                                                                                                                                                                                                                                                                                       |
| MULTI_PASS_LAYOUT   | true   false   1   0                                         | Set to true or 1 to enable Multi-Pass Layout Mode for Place and Route. Default is false or 0.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| MULTI_PASS_CRITERIA | SLOWEST_CLOCK<br>SPECIFIC_CLOCK<br>VIOLATIONS<br>TOTAL_POWER | Specifies the criteria used to run multi-pass layout: <ul style="list-style-type: none"> <li>• SLOWEST_CLOCK: Use the slowest clock frequency in the design in a given pass as the performance reference for the layout pass.</li> <li>• SPECIFIC_CLOCK: Use a specific clock frequency as the performance reference for all layout passes.</li> <li>• VIOLATIONS: Use the pass that best meets the slack or timing-violations constraints. This is the default.</li> <li>• TOTAL POWER: Specifies the best pass to be the one that has the lowest total power (static + dynamic) out of all layout passes.</li> </ul> |
| SPECIFIC_CLOCK      | Clock_Name                                                   | Applies only when MULTI_PASS_CRITERIA is set to SPECIFIC_CLOCK. It specifies the                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |

| Name               | Value                               | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
|--------------------|-------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                    |                                     | name of the clock in the design used for Timing Violation Measurement.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| DELAY_ANALYSIS     | max   min                           | <p>Used only when MULTI_PASS_CRITERIA is set to "VIOLATIONS". Specifies the type of timing violations (slacks) to be examined. The default is 'max'.</p> <ul style="list-style-type: none"> <li>max: Use timing violations (slacks) obtained from maximum delay analysis</li> <li>min: Use timing violations (slacks) obtained from minimum delay analysis.</li> </ul>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| STOP_ON_FIRST_PASS | true   false   1   0                | <p>Applies only when MULTI_PASS_CRITERIA is set to "VIOLATIONS". It stops performing remaining passes if all timing constraints have been met (when there are no negative slacks reported in the timing violations report). Note: The type of timing violations (slacks) used is determined by the 'DELAY_ANALYSIS' parameter.</p>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      |
| SLACK_CRITERIA     | WORST_SLACK<br>TOTAL_NEGATIVE_SLACK | <p>Applies only when MULTI_PASS_CRITERIA is set to VIOLATIONS. Specifies how to evaluate the timing violations (slacks). The default is WORST_SLACK.</p> <ul style="list-style-type: none"> <li>WORST_SLACK: The largest amount of negative slack (or least amount of positive slack if all constraints are met) for each pass is identified and then the largest value out of all passes will determine the best pass. This is the default.</li> <li>TOTAL_NEGATIVE_SLACK: The sum of negative slacks from the first 100 paths for each pass in the Timing Violation report is identified. The largest value out of all passes will determine the best pass. If no negative slacks exist for a pass, then use the worst slack to evaluate that pass.<br/>Note: The type of timing violations (slacks) used is determined by the 'DELAY_ANALYSIS' parameter.</li> </ul> |

## Return Value

Returns 0 on success and 1 on failure.

## run\_tool

```
run_tool -name {PLACEROUTE}
```

### Parameters

None

### Return Value

Returns 0 on success and 1 on failure.

### Example

```
configure_tool -name {PLACEROUTE}\
  -params {EFFORT_LEVEL:true}\
  -params {GB_DEMOTION:true}\
  -params {INCRPLACEANDROUTE:false}\
  -params {IOREG_COMBINING:false}\
  -params {MULTI_PASS_CRITERIA:VIOLATIONS}\
  -params {MULTI_PASS_LAYOUT:false}\
  -params {NUM_MULTI_PASSES:5}\
  -params {PDPR:false}\
  -params {REPAIR_MIN_DELAY:true}\
  -params {SLACK_CRITERIA:WORST_SLACK}\
  -params {SPECIFIC_CLOCK:}\
  -params {START_SEED_INDEX:1}\
  -params {STOP_ON_FIRST_PASS:false}\
  -params {TDPR:true}\
  -params {USE_RAM_MATH_INTERFACE_LOGIC:false}
run_tool -name {PLACEROUTE}
```

## PROGRAMDEVICE

PROGRAMDEVICE is a command tool used in `configure_tool` and `run_tool`. `Configure_tool` allows you to configure the tool's parameters and values prior to executing the tool. `Run_tool` executes the tool with the configured parameters.

To program the design in Libero SoC, you must first configure the PROGRAMDEVICE tool with `configure_tool` command and then execute the PROGRAMDEVICE command with the `run_tool` command.

Use the commands to configure your programming action and the programming procedures associated with the program action.

```
configure_tool -name {PROGRAMDEVICE}
  -params {prog_action:params_value}
  -params {prog_optional_procedures:params_value}
  -params {skip_recommended_procedures:params_value}

run_tool -name {PROGRAMDEVICE}
```

### configure\_tool -name {PROGRAMDEVICE} parameter:value pair

| Name                        | Value                                                                                                     | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
|-----------------------------|-----------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| prog_action                 | String { PROGRAM   VERIFY   ERASE   DEVICE_INFO   READ_IDCODE   ENC_DATA_AUTHENTICATION   VERIFY_DIGEST } | <p>PROGRAM – Programs all selected family features: FPGA Array, targeted eNVM clients and security settings.</p> <p>VERIFY – Verifies all selected family features: FPGA Array, targeted eNVM clients and security settings.</p> <p>ERASE – Erases the selected family features: FPGA Array and security settings.</p> <p>DEVICE_INFO – Displays the IDCODE, the design name, the checksum, and device security settings and programming environment information programmed into the device.</p> <p>READ_IDCODE – Reads the device ID code from the device.</p> <p>ENC_DATA_AUTHENTICATION - Encrypted bitstream authentication data.</p> <p>VERIFY_DIGEST – Calculates the digests for the components included in the bitstream and compares them against the programmed values</p> |
| prog_optional_procedures    | Depends on the action from the prog_action parameter.                                                     | This parameter is optional. It is only required when the user wants to enable optional procedure.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| skip_recommended_procedures | Depends on the action from the prog_action parameter.                                                     | This parameter is optional. It is used to deselect recommended procedures.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |

### run\_tool -name {PROGRAMDEVICE} Parameter:value pair

| Name | Value | Description |
|------|-------|-------------|
| None |       |             |

### Example

```
configure_tool \
  -name {PROGRAMDEVICE} \
  -params {prog_action:VERIFY_DIGEST} \
  -params {prog_optional_procedures:DO_ENABLE_USER_PUBLIC_KEY } \
  -params {skip_recommended_procedures:DO_ENABLE_FABRIC DO_ENABLE_SNVM }
configure_tool -name {PROGRAMDEVICE} -params {prog_action:DEVICE_INFO}
run_tool -name {PROGRAMDEVICE} #Takes no parameters
```

### Return

configure\_tool -name {PROGRAMDEVICE} returns 0 on success and 1 on failure.

run\_tool -name {PROGRAMDEVICE} returns 0 on success and 1 on failure.

## PROGRAM\_SPI\_FLASH\_IMAGE

This Tcl command used in `configure_tool` and `run_tool` to program SPI Flash Image with configured parameters.

```
configure_tool \
  -name {PROGRAM_SPI_FLASH_IMAGE} \
  -params {spi_flash_prog_action: PROGRAM_SPI_FLASH}
run_tool \
  -name {PROGRAM_SPI_FLASH_IMAGE}
```

## PROGRAMMER\_INFO

PROGRAMMER\_INFO is a command tool used in `configure_tool`. `Configure_tool -name {PROGRAMMER_INFO}` sets the programmer settings, similar to the way FlashPro commands set the programmer settings. This command supports all five programmers: FlashPro3, FlashPro4, FlashPro5, FlashPro and FlashPro Lite.

```
configure_tool -name {PROGRAMMER_INFO}
-params [{name:value}]
```

The following tables list the parameter names and values.

### configure\_tool -name {PROGRAMMER\_INFO} Parameter:value (FlashPro5)

| Name                 | Value                                         | Description                    |
|----------------------|-----------------------------------------------|--------------------------------|
| flashpro5_clk_mode   | String {free_running_clk   discrete_clocking} | For FlashPro5 Programmer only. |
| flashpro5_force_freq | String {OFF   ON}                             | For FlashPro5 Programmer only. |
| flashpro5_freq       | Integer (Hertz)                               | For FlashPro5 Programmer only. |
| flashpro5_vpump      | String {ON   OFF}                             | For FlashPro5 Programmer only. |

### configure\_tool -name {PROGRAMMER\_INFO} Parameter:value (FlashPro4)

| Name                 | Value                                         | Description                    |
|----------------------|-----------------------------------------------|--------------------------------|
| flashpro4_clk_mode   | String {free_running_clk   discrete_clocking} | For FlashPro4 Programmer only. |
| flashpro4_force_freq | String {OFF   ON}                             | For FlashPro4 Programmer only. |
| flashpro4_freq       | Integer (Hertz)                               | For FlashPro4 Programmer only. |
| flashpro4_vpump      | String {ON   OFF}                             | For FlashPro4 Programmer only. |

### configure\_tool -name {PROGRAMMER\_INFO} parameter:value (FlashPro3)

| Name               | Value                                         | Description                    |
|--------------------|-----------------------------------------------|--------------------------------|
| flashpro3_clk_mode | String {free_running_clk   discrete_clocking} | For FlashPro3 Programmer only. |

| Name                 | Value             | Description                              |
|----------------------|-------------------|------------------------------------------|
| flashpro3_force_freq | String {OFF   ON} | For FlashPro3 Programmer only.           |
| flashpro3_freq       | Integer (Hertz)   | For FlashPro3 Programmer only.           |
| flashpro3_vpump      | String {ON   OFF} | For Flash For FlashPro3 Programmer only. |

### configure\_tool -name {PROGRAMMER\_INFO} Parameter:value (FlashPro)

| Name                | Value                | Description                   |
|---------------------|----------------------|-------------------------------|
| flashpro_drive_trst | String {OFF   ON}    | For FlashPro Programmer only. |
| flashpro_force_freq | String {OFF   ON}    | For FlashPro Programmer only. |
| flashpro_force_vddp | String {ON   OFF}    | For FlashPro Programmer only. |
| flashpro_freq       | Integer (Hertz)      | For FlashPro Programmer only. |
| flashpro_vddl       | String {ON  OFF}     | For FlashPro Programmer only. |
| flashpro_vddp       | String {2.5V   3.3V} | For FlashPro Programmer only. |
| flashpro_vpn        | String {ON   OFF}    | For FlashPro Programmer only. |
| flashpro_vpp        | String {ON   OFF}    | For FlashPro Programmer only. |

For a detailed description of the parameters and values, refer to [Programmer Settings](#) in the Libero Online Help.

## Examples

### For FlashPro3 programmer

```
configure_tool -name {PROGRAMMER_INFO}\
  -params {flashpro3_clk_mode:free_running_clk}\
  -params {flashpro3_force_freq:OFF}\
  -params {flashpro3_freq:400000}\
  -params {flashpro3_vpump:ON}
```

### For FlashPro4 programmer

```
configure_tool -name {PROGRAMMER_INFO}\
  -params {flashpro4_clk_mode:free_running_clk}\
  -params {flashpro4_force_freq:OFF}\
  -params {flashpro4_freq:400000}\
  -params {flashpro4_vpump:ON}
```

### For FlashPro5 programmer

```
configure_tool -name {PROGRAMMER_INFO}\
  -params {flashpro5_clk_mode:free_running_clk}\
  -params {flashpro5_force_freq:OFF}\
  -params {flashpro5_freq:400000}\
  -params {flashpro5_vpump:ON}
```

## For FlashPro programmer

```
configure_tool -name {PROGRAMMER_INFO}\
  -params {flashpro_drive_trst:OFF}\
  -params {flashpro_force_freq:ON}\
  -params {flashpro_force_vddp:ON}\
  -params {flashpro_freq:400000}\
  -params {flashpro_vddl:ON}\
  -params {flashpro_vddp:2.5}\
  -params {flashpro_vpn:ON}\
  -params {flashpro_vpp:ON}
```

## Return

Returns 0 on success and 1 on failure.

## SPM

To configure security using Tcl, you must use the `configure_tool` Tcl command to pass the SPM configuration parameters.

```
configure_tool -name {SPM}
  -params {name:value}
  [-params {name:value}] +
```

**configure\_tool -name {SPM} parameter:value pair**

**Note:** true | 1 will select the checkbox in the SPM UI

| Name                             | Type    | Value                | Description                                                      |
|----------------------------------|---------|----------------------|------------------------------------------------------------------|
| back_level_protection            | bool    | false   true   1   0 | If true, will set back level protection; Update Policy           |
| back_level_update_version        | Integer | 0 - 65535            | Set back level version; Update Policy                            |
| debug_passkey                    | hex     | 64 hex characters    | Value of DPK; Debug Policy                                       |
| disable_authenticate_action      | bool    | false   true   1   0 | Disables Authenticate action                                     |
| disable_autoprogramming_services | bool    | false   true   1   0 | Disables Auto Programming and IAP Services                       |
| disable_debug_jtag_boundary_scan | bool    | false   true   1   0 | Disables debug JTAG Boundary Scan                                |
| disable_debug_read_temp_volt     | bool    | false   true   1   0 | Disables reading temperature and voltage sensor (JTAG/SPI Slave) |
| disable_debug_ujtag              | bool    | false   true   1   0 | Disables debug UJTAG                                             |
| disable_ext_zeroization          | bool    | false   true   1   0 | Disables external zeroization through JTAG/SPI Slave             |

| Name                          | Type   | Value                | Description                                                                                                                                                                                                                                                                                                                    |
|-------------------------------|--------|----------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| disable_external_digest_check | bool   | false   true   1   0 | Disables external Fabric/sNVM digest requests through JTAG/SPI Slave                                                                                                                                                                                                                                                           |
| disable_jtag                  | bool   | false   true   1   0 | Disables JTAG                                                                                                                                                                                                                                                                                                                  |
| disable_program_action        | bool   | false   true   1   0 | Disables Program action                                                                                                                                                                                                                                                                                                        |
| disable_puf_emulation         | bool   | false   true   1   0 | Disables external access to PUF emulation through JTAG/SPI Slave                                                                                                                                                                                                                                                               |
| disable_smartdebug_debug      | bool   | false   true   1   0 | Disables user debug access and active probes                                                                                                                                                                                                                                                                                   |
| disable_smartdebug_live_probe | bool   | false   true   1   0 | Disables SmartDebug Live Probe                                                                                                                                                                                                                                                                                                 |
| disable_smartdebug_snvm       | bool   | false   true   1   0 | Disables SmartDebug sNVM                                                                                                                                                                                                                                                                                                       |
| disable_spi_slave             | bool   | false   true   1   0 | Disables SPI Slave interface                                                                                                                                                                                                                                                                                                   |
| disable_user_encryption_key_1 | bool   | false   true   1   0 | If true, disables UEK1; Key Mode Policy                                                                                                                                                                                                                                                                                        |
| disable_user_encryption_key_2 | bool   | false   true   1   0 | If true, disables UEK2; Key Mode Policy                                                                                                                                                                                                                                                                                        |
| disable_user_encryption_key_3 | bool   | false   true   1   0 | <p>If true, disables UEK3</p> <p>Note: UEK3 is only available for M2S060, M2GL060, M2S090, M2GL090, M2S150, and M2GL150 devices. All other devices will set this to false by default. See the <a href="#">SmartFusion2 SoC FPGA and IGLOO2 FPGA Security Best Practices User Guide</a> for details.</p> <p>Key Mode Policy</p> |
| disable_verify_action         | bool   | false   true   1   0 | Disables Verify action                                                                                                                                                                                                                                                                                                         |
| fabric_update_protection      | string | open   disabled      | Fabric update protection. Open – updates allowed using user defined encryption keys. Disabled – disables Erase/Write operations.                                                                                                                                                                                               |
| security_factory_access       | string | open   disabled      | Microsemi factory test mode access. Open – factory test mode access allowed. Disabled – disables factory test mode access.                                                                                                                                                                                                     |

| Name                   | Type   | Value             | Description                                                                                                              |
|------------------------|--------|-------------------|--------------------------------------------------------------------------------------------------------------------------|
| security_key_mode      | string | custom   default  | Default – bitstream encryption with default key. Custom – custom security options                                        |
| snvm_update_protection | string | open   disabled   | SNVM update protection. Open – updates allowed using user defined encryption keys. Disabled – disables Write operations. |
| user_encryption_key_1  | hex    | 64 hex characters | Value of UEK1                                                                                                            |
| user_encryption_key_2  | hex    | 64 hex characters | Value of UEK2                                                                                                            |
| user_passkey_1         | hex    | 64 hex characters | Value of Flashlock/UPK1                                                                                                  |
| user_passkey_2         | hex    | 64 hex characters | Value of UPK2                                                                                                            |

## Example

```
configure_tool \
  -name {SPM} \
  -params {back_level_protection:false} \
  -params {back_level_update_version: 32} \
  -params {disable_smartdebug_live_probe:false} \
  -params {disable_smartdebug_snvm:false} \
  -params {disable_user_encryption_key_1:false} \
  -params {disable_user_encryption_key_2:false} \
```

## Return

Returns 0 on success and 1 on failure.

# SYNTHESIZE

SYNTHESIZE is a command tool used in `configure_tool` and `run_tool`. `Configure_tool` is a general-purpose Tcl command that allows you to configure a tool's parameters and values prior to executing the tool. The `run_tool` Tcl command then executes the specified tool with the configured parameters.

To synthesize your design in Libero SoC, you first configure the synthesize tool with the `configure_tool` command and then execute the command with the `run_tool` command.

```
configure_tool -name {SYNTHESIZE}
  -params {name:value}
  [-params {name:value}]
run_tool -name {SYNTHESIZE}
```

The following tables list the parameter names and values.

### configure\_tool -name {SYNTHESIZE} parameter:value pair

| Name                      | Value                                   | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|---------------------------|-----------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| CLOCK_ASYNC               | Integer                                 | Specifies the threshold value for asynchronous pin promotion to a global net. The default is 12.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| CLOCK_GLOBAL              | Integer                                 | Specifies the threshold value for Clock pin promotion. The default is 2.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| CLOCK_DATA                | Integer value between 1000 and 200,000. | Specifies the threshold value for data pin promotion. The default is 5000.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             |
| RAM_OPTIMIZED_FOR_POWER   | Boolean {true   false   1   0}          | Set to true or 1 to optimize RAM for Low Power; RAMS are inferred and configured to ensure the lowest power consumption. Set to false or 0 to optimize RAM for High Speed at the expense of more FPGA resources.                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| RETIMING                  | Boolean {true   false   1   0}          | Set to true or 1 to enable Retiming during synthesis. Set to false or 0 to disable Retiming during synthesis.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| AUTO_COMPILE_POINT        | Boolean {true   false   1   0}          | Set to true or 1 to enable Automatic Compile Point during synthesis. Set to false or 0 to disable Automatic Compile Point during synthesis. The default is 0 or false.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| SYNPLIFY_OPTIONS          | String                                  | Specifies additional synthesis-specific options. Options specified by this parameter override the same options specified in the user Tcl file if there is a conflict.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |
| SYNPLIFY_TCL_FILE         | String                                  | Specifies the absolute or relative path name to the user Tcl file containing synthesis-specific options.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| BLOCK_MODE                | Boolean {true   false   1   0}          | Set to true or 1 when you have blocks in your design and you want to enable the Block mode. Set it to false or 0 if you don't have blocks in your design. Default is false or 0.                                                                                                                                                                                                                                                                                                                                                                                                                                                                       |
| BLOCK_PLACEMENT_CONFLICTS | String {ERROR KEEP LOCK DISCARD}        | <p>Instructs the COMPILE engine what to do when the software encounters a placement conflict. When set to: ERROR - Compile errors out if any instance from a Designer block becomes unplaced. This is the default.</p> <p>KEEP - If some instances get unplaced for any reason, the non-conflicting elements remaining are preserved but not locked. Therefore, the placer can move them into another location if necessary.</p> <p>LOCK - If some instances get unplaced for any reason, the non-conflicting elements remaining are preserved and locked.</p> <p>DISCARD - Discards any placement from the block, even if there are no conflicts.</p> |

| Name                                | Value                               | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
|-------------------------------------|-------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| BLOCK_ROUTING_CONFLICTS             | String<br>{ERROR KEEP LOCK DISCARD} | Instructs the COMPILE engine what to do when the software encounters a routing conflict. When set to: ERROR - Compile errors out if any route in any preserved net from a Designer block is deleted. This is the default.<br><br>KEEP – If a route is removed from a net for any reason, the routing for the non-conflicting nets is kept unlocked. The router can re-route these nets. LOCK – If routing is removed from a net for any reason, the routing for the non-conflicting nets is kept as locked, and the router will not change them.<br><br>DISCARD - Discards any routing from the block, even if there are no conflicts. |
| PA4_GB_COUNT                        | Integer                             | The number of available global nets is reported. Minimum for all dies is "0". Default and Maximum values are die-dependent:<br>005/010 die: Default = Max = 8<br>025/050/060/090/150 die: Default=Max=16<br>RT4G075/RT4G150: Default=24, Max=48.                                                                                                                                                                                                                                                                                                                                                                                       |
| PA4_GB_MAX_RCLKINT_INSERTION        | Integer                             | Specifies the maximum number of global nets that could be demoted to row-globals. Default is 16, Min is 0 and Max is 50.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |
| PA4_GB_MIN_GB_FANOUT_TO_USE_RCLKINT | Integer                             | Specifies the Minimum fanout of global nets that could be demoted to row-globals. Default is 300. Min is 25 and Max is 5000.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |
| SEQSHIFT_TO_URAM                    | Boolean {0,1}                       | Specifies whether the Sequential-Shift Registers are to be mapped to Registers or 64x12 RAMs. If set to 1 (the default), the logic mapping is to RAMs. If set to 0, the logic mapping is to Registers.                                                                                                                                                                                                                                                                                                                                                                                                                                 |
| LANGUAGE_SYSTEM_VLOG                | Boolean {true   false}              | Set to true if the Verilog files contain System Verilog constructs.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |
| LANGUAGE_VERILOG_2001               | Boolean {true   false}              | Set to true if Verilog files contain Verilog 2001 constructs.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |

## run\_tool -name {SYNTHESIZE}

### Example

```
configure_tool -name {SYNTHESIZE} -params {BLOCK_MODE:false}\
  -params {BLOCK_PLACEMENT_CONFLICTS:ERROR} -params\
  {BLOCK_ROUTING_CONFLICTS:ERROR} -params {CLOCK_ASYNC:12}\
  -params {CLOCK_DATA:5010} -params {CLOCK_GLOBAL:2} -params\
  -params {PA4_GB_MAX_RCLKINT_INSERTION:16} -params\
  {PA4_GB_MIN_GB_FANOUT_TO_USE_RCLKINT:299} -params\
  {RAM_OPTIMIZED_FOR_POWER:false} -params {RETIMING:false}\
  -params {AUTO_COMPILE_POINT:true} -params {SYNPLIFY_OPTIONS:
```

```

set_option -run_prop_extract 1;
set_option -maxfan 10000;
set_option -clock_globalthreshold 2;
set_option -async_globalthreshold 12;
set_option -globalthreshold 5000;
set_option -low_power_ram_decomp 0;}\
-params {SYNPLIFY_TCL_FILE:C:/Users/user1/Desktop/tclflow/synthesis/test.tcl}

run_tool -name {SYNTHESIZE} #Takes no parameters

```

## Return

```

configure_tool -name {SYNTHESIZE}
  Returns 0 on success and 1 on failure.
run_tool -name {SYNTHESIZE}
  Returns 0 on success and 1 on failure.

```

## VERIFYPOWER

VERIFYPOWER is a command tool used in run\_tool. The command run\_tool passes a script file that contains power-specific Tcl commands to the VERIFYPOWER command and executes it.

```
run_tool -name {VERIFYPOWER} -script {power_analysis.tcl}
```

where

<power\_analysis.tcl> is a script that contains power-specific Tcl commands. You can include power-specific Tcl commands to generate power reports. See the sample power\_analysis Tcl Script below for details.

## Return

Returns 0 on success and 1 on failure.

## Example

```
run_tool -name {VERIFYPOWER} -script {<power_analysis.tcl>}
```

## Sample power\_analysis Tcl Script <power\_analysis.tcl>

The following example changes SmartPower operating condition settings from the default to 40C junction temperature and 1.25V VDD.

It then creates a report called A4P5000\_uSRAM\_POWER\_64X18\_power\_report.txt.

# Change from pre-defined temperature and voltage mode (COM,IND,MIL) to SmartPower custom

```

smartpower_set_temperature_opcond -use "design"
smartpower_set_voltage_opcond -voltage "VDD" -use "design"

```

# Set the custom temperature to 40C ambient temperature.

```
smartpower_temperature_opcond_set_design_wide -typical 40 -best 40 -worst 40
```

# Set the custom voltage to 1.25V

```

smartpower_voltage_opcond_set_design_wide -voltage "VDD" -typical 1.25 -best 1.25 -worst
1.25

```

## VERIFYTIMING

VERIFYTIMING is a command tool used in run\_tool. Run\_tool passes a script file that contains timing-specific Tcl commands to the VERIFYTIMING command and executes it.

```
run_tool -name {VERIFYTIMING} -script {timing.tcl}
```

where

<timing.tcl> is a script that contains SmartTime-specific Tcl commands. You can include SmartTime-specific Tcl commands to create user path sets and to generate timing reports. See sample the Sample SmartTime Tcl Script below for details.

## Example

```
run_tool -name {VERIFYTIMING} -script {<timing.tcl>}
```

## Return

Returns 0 on success and 1 on failure.

## Sample SmartTime Tcl Script <timing.tcl>

```
# Create user path set -from B_reg
create_set -name from_B_reg \
  -source {B_reg[*]:CLK} \
  -sink {*}
# Create user set -from A, B, C
create_set -name from_in_ports \
  -source {A B C} \
  -sink {*}
# Generate Timing Reports
report \
  -type timing \
  -analysis min \
  -format text \
  -max_paths 10 \
  -print_paths yes \
  -max_expanded_paths 10 \
  -include_user_sets yes \
  min_timing.rpt
# Export SDC
write_sdc -scenario {Primary} exported.sdc
#save the changes
save
```

# SIMULATE

Use the run\_tool command to run simulation with your default simulation tool.

```
#Run Pre-synthesis simulation
run_tool -name {SIM_PRESYNTH}
#Run Post-synthesis simulation
run_tool -name {SIM_POSTSYNTH}
```

## Return Value

Returns 0 on success and 1 on failure.

# SmartTime Tcl Commands

## create\_set

Tcl command; creates a set of paths to be analyzed. Use the arguments to specify which paths to include. To create a set that is a subset of a clock domain, specify it with the `-clock` and `-type` arguments. To create a set that is a subset of an inter-clock domain set, specify it with the `-source_clock` and `-sink_clock` arguments. To create a set that is a subset (filter) of an existing named set, specify the set to be filtered with the `-parent_set` argument.

```
create_set\ -name <name>\ -parent_set <name>\ -type <set_type>\ -clock <clock_name>\ -
source_clock <clock_name>\ -sink_clock <clock_name>\ -in_to_out\ -source <port/pin pattern>\
-sink <port/pin pattern>
```

## Arguments

`-name <name>`

Specifies a unique name for the newly created path set.

`-parent_set <name>`

Specifies the name of the set to filter from.

`-clock <clock_name>`

Specifies that the set is to be a subset of the given clock domain. This argument is valid only if you also specify the `-type` argument.

`-type <value>`

Specifies the predefined set type on which to base the new path set. You can only use this argument with the `-clock` argument, not by itself.

| Value             | Description                                       |
|-------------------|---------------------------------------------------|
| reg_to_reg        | Paths between registers in the design             |
| async_to_reg      | Paths from asynchronous pins to registers         |
| reg_to_async      | Paths from registers to asynchronous pins         |
| external_recovery | The set of paths from inputs to asynchronous pins |
| external_removal  | The set of paths from inputs to asynchronous pins |
| external_setup    | Paths from input ports to registers               |
| external_hold     | Paths from input ports to registers               |
| clock_to_out      | Paths from registers to output ports              |

`-in_to_out`

Specifies that the set is based on the "Input to Output" set, which includes paths that start at input ports and end at output ports.

`-source_clock <clock_name>`

Specifies that the set will be a subset of an inter-clock domain set with the given source clock. You can only use this option with the `-sink_clock` argument.

`-sink_clock <clock_name>`

Specifies that the set will be a subset of an inter-clock domain set with the given sink clock. You can only use this option with the `-source_clock` argument.

`-source <port/pin_pattern>`

Specifies a filter on the source pins of the parent set. If you do not specify a parent set, this option filters all pins in the current design.

`-sink <port/pin_pattern>`

Specifies a filter on the sink pins of the parent set. If you do not specify a parent set, this option filters all pins in the current design.

## Examples

```
create_set -name { my_user_set } -source { C* } -sink { D* }
create_set -name { my_other_user_set } -parent_set { my_user_set } -source { CL* }
create_set -name { adder } -source { ALU_CLOCK } -type { REG_TO_REG } -sink { ADDER* }
create_set -name { another_set } -source_clock { EXTERN_CLOCK } -sink_clock {
MY_GEN_CLOCK }
```

## expand\_path

Tcl command; displays expanded path information (path details) for paths. The paths to be expanded are identified by the parameters required to display these paths with `list_paths`. For example, to expand the first path listed with `list_paths -clock {MYCLOCK} -type {register_to_register}`, use the command `expand_path -clock {MYCLOCK} -type {register_to_register}`. Path details contain the pin name, type, net name, cell name, operation, delay, total delay, and edge as well as the arrival time, required time, and slack. These details are the same as details available in the SmartTime Expanded Path window.

```
expand_path
-index value
-set name
-clock clock name
-type set_type
-analysis {max| min}
-format {csv | text}
-from_clock clock name
-to_clock clock name
```

## Arguments

`-index value`

Specify the index of the path to be expanded in the list of paths. Default is 1.

`-analysis {max | min}`

Specify whether the timing analysis is done is max-delay (setup check) or min-delay (hold check). Valid values: max or min.

`-format {csv | text}`

Specify the list format. It can be either text (default) or csv (comma separated values). The former is suited for display the latter for parsing.

`-set name`

Displays a list of paths from the named set. You can either use the `-set` option to specify a user set by its name or use both `-clock` and `-type` to specify a set.

`-clock clock name`

Displays the set of paths belonging to the specified clock domain. You can either use this option along with `-type` to specify a set or use the `-set` option to specify the name of the set to display.

**-type set\_type**

Specifies the type of paths in the clock domain to display in a list. You can only use this option with the -clock option. You can either use this option along with -clock to specify a set or use the -set option to specify a set name.

| Value             | Description                                   |
|-------------------|-----------------------------------------------|
| reg_to_reg        | Paths between registers in the design         |
| external_setup    | Path from input ports to registers            |
| external_hold     | Path from input ports to registers            |
| clock_to_out      | Path from registers to output ports           |
| reg_to_async      | Path from registers to asynchronous pins      |
| external_recovery | Set of paths from inputs to asynchronous pins |
| external_removal  | Set of paths from inputs to asynchronous pins |
| async_to_reg      | Path from asynchronous pins to registers      |

**-from\_clock clock\_name**

Displays a list of timing paths for an inter-clock domain set belonging to the source clock specified. You can only use this option with the -to\_clock option, not by itself.

**-to\_clock clock\_name**

Displays a list of timing paths for an inter-clock domain set belonging to the sink clock specified. You can only use this option with the -from\_clock option, not by itself.

**-analysis name**

Specifies the analysis for the paths to be listed. The following table shows the acceptable values for this argument.

| Value    | Description            |
|----------|------------------------|
| maxdelay | Maximum delay analysis |
| mindelay | Minimum delay analysis |

**-index list\_of\_indices**

Specifies which paths to display. The index starts at 1 and defaults to 1. Only values lower than the max\_paths option will be expanded.

**-format value**

Specifies the file format of the output. The following table shows the acceptable values for this argument:

| Value | Description                       |
|-------|-----------------------------------|
| text  | ASCII text format                 |
| csv   | Comma separated value file format |

## Examples

**Note:** The following example returns a list of five paths:

```
puts [expand_path -clock { myclock } -type {reg_to_reg }]
puts [expand_path -clock {myclock} -type {reg_to_reg} -index { 1 2 3 } -format text]
```

### See Also

[list\\_paths](#)

## list\_paths

Tcl command; returns a list of the *n* worst paths matching the arguments. The number of paths returned can be changed using the set\_options -limit\_max\_paths <value> command.

```
list_paths
-analysis <max | min>
-format <csv | text>
-set <name>
-clock <clock name>
-type <set_type>
-from_clock <clock name>
-to_clock <clock name>
-in_to_out
-from <port/pin pattern>
-to <port/pin pattern>
```

### Arguments

-analysis <max | min>

Specifies whether the timing analysis is done for max-delay (setup check) or min-delay (hold check). Valid values are: max or min.

-format < text | csv >

Specifies the list format. It can be either text (default) or csv (comma separated values). Text format is better for display and csv format is better for parsing.

-set <name>

Returns a list of paths from the named set. You can either use the -set option to specify a user set by its name or use both -clock and -type to specify a set.

-clock <clock name>

Returns a list of paths from the specified clock domain. This option requires the -type option.

-type <set\_type>

Specifies the type of paths to be included. It can only be used along with -clock. Valid values are:

reg\_to\_reg -- Paths between registers

external\_setup -- Path from input ports to data pins of registers

external\_hold -- Path from input ports to data pins of registers

clock\_to\_out -- Path from registers to output ports

reg\_to\_async -- Path from registers to asynchronous pins of registers

external\_recovery -- Path from input ports to asynchronous pins of registers

external\_removal -- Path from input ports to asynchronous pins of registers

async\_to\_reg -- Path from asynchronous pins to registers

-from\_clock <clock name>

Used along with -to\_clock to get the list of paths of the inter-clock domain between the two clocks.

-to\_clock <clock name>

Used along with -from\_clock to get the list of paths of the inter-clock domain between the two clocks.

-in\_to\_out

Used to get the list of path between input and output ports.

-from <port/pin pattern>

Filter the list of paths to those starting from ports or pins matching the pattern.

-to <*port/pin pattern*>

Filter the list of paths to those ending at ports or pins matching the pattern.

## Example

The following command displays the list of register to register paths of clock domain clk1:

```
puts [ list_paths -clock clk1 -type reg_to_reg ]
```

## See Also

[create\\_set](#)

[expand\\_path](#)

[set\\_options](#)

## read\_sdc

The read\_sdc Tcl command evaluate an SDC file, adding all constraints to the specified scenario (or the current/default one if none is specified). Existing constraints are removed if -add is not specified.

```
read_sdc
-add
-scenario scenario_name
-netlist (user | optimized)
-pin_separator (: | /)
file name
```

## Arguments

-add

Specifies that the constraints from the SDC file will be added on top of the existing ones, overriding them in case of a conflict. If not used, the existing constraints are removed before the SDC file is read.

-scenario *scenario\_name*

Specifies the scenario to add the constraints to. The scenario is created if none exists with this name.

-netlist (*user* | *optimized*)

Specifies whether the SDC file contains object defined at the post-synthesis netlist (user) level or physical (optimized) netlist (used for timing analysis).

-pin\_separator *sep*

Specify the pin separator used in the SDC file. It can be either ':' or '/'.

*file name*

Specify the SDC file name.

## Example

The following command removes all constraints from the current/default scenario and adds all constraints from design.sdc file to it:

```
read_sdc design.sdc
```

## See Also

[write\\_sdc](#)

## remove\_set

Tcl command; removes a set of paths from analysis. Only user-created sets can be deleted.

```
remove_set -name name
```

### Parameters

-name *name*

Specifies the name of the set to delete.

### Example

The following command removes the set named my\_set:

```
remove_set -name my_set
```

### See Also

[create\\_set](#)

## report

Tcl command; specifies the type of reports to generate and what to include in the reports.

```
report -type (timing | violations | datasheet | bottleneck | constraints_coverage |
combinational_loops) \
  -analysis <max|min> \
  -format (csv|text) \
  <filename>
  timing options
    -max_parallel_paths <number>
    -max_paths <number>
    -print_summary (yes|no)
    -use_slack_threshold (yes|no)
    -slack_threshold <double>
    -print_paths (yes|no)
    -max_expanded_paths <number>
    -include_user_sets (yes|no)
    -include_clock_domains (yes|no)
    -select_clock_domains <clock name list>
    -limit_max_paths (yes|no)
    -include_pin_to_pin (yes|no)
  bottleneck options
    -cost_type (path_count|path_cost)
    -max_instances <number>
    -from <port/pin pattern>
    -to <port/pin pattern>
    -set_type <set_type>
    -set_name <set name>
    -clock <clock name>
    -from_clock <clock name>
    -to_clock <clock name>
    -in_to_out
```

### Arguments

-type

Specifies the type of the report to be generated. It is mandatory.

| Value                | Description                 |
|----------------------|-----------------------------|
| timing               | Timing Report               |
| violations           | Timing Violation Report     |
| datasheet            | Datasheet Report            |
| bottleneck           | Bottleneck Report           |
| constraints_coverage | Constraints Coverage Report |
| combinational_loops  | Combinational Loops Report  |

**-analysis**

Specifies the type of Analysis(Max Delay or Min Delay) Performed to generate the reports. It is optional.

**Note:** This argument should not be used to generate datasheet reports. The command may fail if this argument is used to generate datasheet report.

| Value | Description                                         |
|-------|-----------------------------------------------------|
| max   | Timing report considers maximum analysis (default). |
| min   | Timing report considers minimum analysis.           |

**-format**

Specifies the format in which the report is generated. It is optional.

| Value | Description                                                                                     |
|-------|-------------------------------------------------------------------------------------------------|
| text  | Generates a text report (default).                                                              |
| csv   | Generates the report in a comma-separated value format which you can import into a spreadsheet. |

**-filename**

Specifies the file name of the generated report. It is mandatory.

## Timing Options and Values

| Parameter/Value               | Description                                                                                                                          |
|-------------------------------|--------------------------------------------------------------------------------------------------------------------------------------|
| -max_parallel_paths <number>  | Specifies the max number of parallel paths. Parallel paths are timing paths with the same start and end points.                      |
| -max_paths <number>           | Specifies the max number of paths to display for each set. This value is a positive integer value greater than zero. Default is 100. |
| -print_summary <yes no>       | Yes to include and No to exclude the summary section in the timing report.                                                           |
| -use_slack_threshold <yes no> | Yes to include slack threshold and no to exclude threshold in the timing report. The default is to exclude slack threshold.          |

| Parameter/Value                            | Description                                                                                                                                                                                                                                                                    |
|--------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| -slack_threshold <double>                  | Specifies the threshold value to consider when reporting path slacks. This value is in nanoseconds (ns). By default, there is no threshold (all slacks reported).                                                                                                              |
| -print_paths (yes no)                      | Specifies whether the path section (clock domains and in-to-out paths) will be printed in the timing report. Yes to include path sections (default) and no to exclude path sections from the timing report.                                                                    |
| -max_expanded_paths <number>               | Specifies the max number of paths to expand per set. This value is a positive integer value greater than zero. Default is 100.                                                                                                                                                 |
| -include_user_sets (yes no)                | If yes, the user set is included in the timing report. If no, the user set is excluded in the timing report.                                                                                                                                                                   |
| -include_clock_domains (yes no)            | Yes to include and no to exclude clock domains in the timing report.                                                                                                                                                                                                           |
| -select_clock_domains<br><clock_name_list> | Defines the clock domain to be considered in the clock domain section. The domain list is a series of strings with domain names separated by spaces. Both the summary and the path sections in the timing report display only the listed clock domains in the clock_name_list. |
| -limit_max_paths (yes no)                  | Yes to limit the number of paths to report. No to specify that there is no limit to the number of paths to report (the default).                                                                                                                                               |
| -include_pin_to_pin (yes no)               | Yes to include and no to exclude pin-to-pin paths in the timing report.                                                                                                                                                                                                        |

## Bottleneck Options and Values

| Parameter/Value                      | Description                                                                                                                                                                                                                                                                         |
|--------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| -cost_type<br><path_count path_cost> | Specifies the cost_type as either path_count or path_cost. For path_count, instances with the greatest number of path violations will have the highest bottleneck cost. For path_cost, instances with the largest combined timing violations will have the highest bottleneck cost. |
| -max_instances <number>              | Specifies the maximum number of instances to be reported. Default is 10.                                                                                                                                                                                                            |
| -from <port/pin pattern>             | Reports only instances that lie on violating paths that start at locations specified by this option.                                                                                                                                                                                |
| -to <port/pin pattern>               | Reports only instances that lie on violating paths that end at locations specified by this option.                                                                                                                                                                                  |
| -clock <clock name>                  | This option allows pruning based on a given clock domain. Only instances that lie on these violating paths are reported.                                                                                                                                                            |
| -set_name <set name>                 | Displays the bottleneck information for the named set. You can either use this option or use both -clock and -type. This option allows pruning based on a given set. Only paths that lie within the named set will be considered towards bottleneck.                                |

| Parameter/Value          | Description                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |
|--------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| -set_type <set_type>     | <p>This option can only be used in combination with the -clock option, and not by itself. The options allows you to filter which type of paths should be considered towards the bottleneck:</p> <ul style="list-style-type: none"> <li>• reg_to_reg - Paths between registers in the design</li> <li>• async_to_reg - Paths from asynchronous pins to registers</li> <li>• reg_to_async - Paths from registers to asynchronous pins</li> <li>• external_recovery - The set of paths from inputs to asynchronous pins</li> <li>• external_removal - The set of paths from inputs to asynchronous pins</li> <li>• external_setup - Paths from input ports to registers</li> <li>• external_hold - Paths from input ports to registers</li> <li>• clock_to_out - Paths from registers to output ports</li> </ul> |
| -from_clock <clock name> | Reports only bottleneck instances that lie on violating timing paths of the inter-clock domain that starts at the source clock specified by this option. This option can only be used in combination with -to_clock.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |
| -to_clock <clock name>   | Reports only instances that lie on violating paths that end at locations specified by this option.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            |
| -in_to_out               | Reports only instances that lie on violating paths that begin at input ports and end at output ports.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |

## Example

The following example generates a timing violation report named timing\_viol.txt. The report considers an analysis using maximum delays and does not filter paths based on slack threshold. It reports two paths per section and one expanded path per section.

```
report \
  -type violations \
  -analysis max \
  -use_slack_threshold no \
  -limit_max_paths yes \
  -max_paths 2 \
  -max_expanded_paths 1 \
  timing_viol.txt
```

The following example generates a datasheet report named datasheet.csv in CSV format.

```
report \
  -type datasheet \
  -format csv \
  datasheet.csv
```

## save

Tcl command; saves all changes made prior to this command. This includes changes made on constraints, options and sets.

```
save
```

## Arguments

None

## Example

The following script sets the maximum number of paths reported by list\_paths to 10, reads an SDC file, and save both the option and the constraints into the design project:

```
set_options -limit_max_paths 10
read_sdc somefile.sdc
save
```

## See Also

[set\\_options](#)

## set\_options

SmartTime-specific Tcl command; sets options for timing analysis. Some options will also affect timing-driven place-and-route. The same parameters can be changed in the SmartTime Options dialog box in the SmartTime GUI.

```
set_options
[-max_opcond value ]
[-min_opcond value]
[-interclockdomain_analysis value]
[-use_bibuf_loopbacks value]
[-enable_recovery_removal_checks value]
[-break_at_async value]
[-filter_when_slack_below value]
[-filter_when_slack_above value]
[-remove_slack_filters]
[-limit_max_paths value]
[-expand_clock_network value]
[-expand_parallel_paths value]
[-analysis_scenario value]
[-tdpr_scenario value]
[-reset]
```

## Arguments

-max\_opcond *value*

Sets the operating condition to use for Maximum Delay Analysis.

The acceptable Values for max\_opcode for PolarFire is shown in the below table. Default is slow\_lv\_lvt.

| Value       | Description                                           |
|-------------|-------------------------------------------------------|
| slow_lv_lvt | Use slow_lv_lvt conditions for Maximum Delay Analysis |
| slow_hv_lvt | Use slow_hv_lvt conditions for Maximum Delay Analysis |
| fast_hv_lvt | Use fast_hv_lvt conditions for Maximum Delay Analysis |

-min\_opcond *value*

Sets the operating condition to use for Minimum Delay Analysis.

The acceptable Values for min\_opcode for PolarFire is shown in the below table. Default is fast\_hv\_lt.

| Value      | Description                                          |
|------------|------------------------------------------------------|
| fast_hv_lt | Use fast_hv_lt conditions for Maximum Delay Analysis |
| slow_hv_lt | Use slow_hv_lt conditions for Maximum Delay Analysis |
| slow_lv_lt | Use slow_lv_lt conditions for Maximum Delay Analysis |

-interclockdomain\_analysis *value*

Enables or disables inter-clock domain analysis. Default is yes.

| Value | Description                          |
|-------|--------------------------------------|
| yes   | Enables inter-clock domain analysis  |
| no    | Disables inter-clock domain analysis |

-use\_bibuf\_loopbacks *value*

Instructs the timing analysis whether to consider loopback path in bidirectional buffers (D->Y, E->Y) as false-path {no}. Default is yes; i.e., loopback are false paths.

| Value | Description                 |
|-------|-----------------------------|
| yes   | Enables loopback in bibufs  |
| no    | Disables loopback in bibufs |

-enable\_recovery\_removal\_checks *value*

Enables recovery checks to be included in max-delay analysis and removal checks in min-delay analysis. Default is yes.

| Value | Description                          |
|-------|--------------------------------------|
| yes   | Enables recovery and removal checks  |
| no    | Disables recovery and removal checks |

-break\_at\_async *value*

Specifies whether or not timing analysis is allowed to cross asynchronous pins (clear, reset of sequential elements). Default is no.

| Value | Description                                   |
|-------|-----------------------------------------------|
| yes   | Enables breaking paths at asynchronous ports  |
| no    | Disables breaking paths at asynchronous ports |

-filter\_when\_slack\_below *value*

Specifies a minimum slack value for paths reported by list\_paths. Not set by default.

-filter\_when\_slack\_above *value*

Specifies a maximum slack value for paths reported by `list_paths`. Not set by default.

`-remove_slack_filters`

Removes the slack minimum and maximum set using `-filter_when_slack_below` and `filter_when_slack_above`.

`-limit_max_paths` *value*

Specifies the maximum number of paths reported by `list_paths`. Default is 100.

`-expand_clock_network` *value*

Specify whether or not clock network details are reported in `expand_path`. Default is yes.

| Value | Description                                          |
|-------|------------------------------------------------------|
| yes   | Enables expanded clock network information in paths  |
| no    | Disables expanded clock network information in paths |

`-expand_parallel_paths` *value*

Specify the number of parallel paths {paths with the same ends} to include in `expand_path`. Default is 1.

`-analysis_scenario` *value*

Specify the constraint scenario to be used for timing analysis. Default is *Primary*, the default scenario.

`-tdpr_scenario` *value*

Specify the constraint scenario to be used for timing-driven place-and-route. Default is *Primary*, the default scenario.

`-reset`

Reset all options to the default values, except those for analysis and TDPR scenarios, which remain unchanged.

## Examples

The following script commands the timing engine to use best operating conditions for both max-delay analysis and min-delay analysis:

```
set_options -max_opcond {best} -min_opcond {best}
```

The following script changes the scenario used by timing-driven place-and-route and saves the change in the Libero project for place-and-route tools to see the change.

```
set_options -tdpr_scenario {My_TDPR_Scenario}
```

## See Also

[save](#)

# SmartPower Tcl Commands

## smartpower\_add\_new\_scenario

Tcl command; creates a new scenario.

```
smartpower_add_new_scenario -name {value} -description {value} -mode {value}
```

### Arguments

-name {value}

Specifies the name of the new scenario.

-description {value}

Specifies the description of the new scenario.

-mode {<operating mode>:<duration>}+

Specifies the mode(s) and duration(s) for the specified scenario.

### Examples

This example creates a new scenario called myscenario:

```
smartpower_add_new_scenario -name "MyScenario" -mode "Custom_1:50.00"
"Custom_2:25.00" -mode "Active:25.00"
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_add\_pin\_in\_domain

Tcl command; adds a pin into a clock or set domain.

```
smartpower_add_pin_in_domain -pin_name {pin_name} -pin_type {value} -domain_name
{domain_name} -domain_type {value}
```

### Arguments

-pin\_name {pin\_name}

Specifies the name of the pin to add to the domain.

-pin\_type {value}

Specifies the type of the pin to add. The following table shows the acceptable values for this argument:

| Value | Description                   |
|-------|-------------------------------|
| clock | The pin to add is a clock pin |
| data  | The pin to add is a data pin  |

-domain\_name {domain\_name}

Specifies the name of the domain in which to add the specified pin.

-domain\_type {value}

Specifies the type of domain in which to add the specified pin. The following table shows the acceptable values for this argument:

| Value | Description                  |
|-------|------------------------------|
| clock | The domain is a clock domain |
| set   | The domain is a set domain   |

## Notes

- The `domain_name` must be a name of an existing domain.
- The `pin_name` must be a name of a pin that exists in the design.

## Examples

The following example adds a clock pin to an existing Clock domain:

```
smartpower_add_pin_in_domain -pin_name { XCMP3/U0/U1:Y } -pin_type {clock} -domain_name {clk1} -domain_type {clock}
```

The following example adds a data pin to an existing Set domain:

```
smartpower_add_pin_in_domain -pin_name {XCMP3/U0/U1:Y} -pin_type {data} -domain_name {myset} -domain_type {set}
```

## See Also

[Tcl documentation conventions](#)

[smartpower remove pin of domain](#)

# smartpower\_battery\_settings

This SmartPower Tcl command sets the battery capacity in SmartPower. The battery capacity is used to compute the battery life of your design.

```
smartpower_battery_settings -capacity {decimal value}
```

## Parameters

`-capacity {decimal value}`

Value must be a positive decimal.

This parameter is mandatory.

## Exceptions

None

## Returns

This command does not return a value.

## Usage

The following table lists the parameters for the command, their types, and the values they can be set to.

| smartpower_battery_settings | Type    | Value            | Description                              |
|-----------------------------|---------|------------------|------------------------------------------|
| capacity                    | Decimal | Positive decimal | Specify the battery capacity in mA*Hours |

## Example

This example sets the battery capacity to 1800 mA \* Hours.

```
smartpower_battery_settings -capacity {1800}
```

## smartpower\_change\_clock\_statistics

Tcl command; changes the default frequencies and probabilities for a specific domain.

```
smartpower_change_clock_statistics -domain_name {value} -clocks_freq {value} -
clocks_proba {value} -registers_freq {value} -registers_proba {value} -set_reset_freq
{value} -set_reset_proba {value} -primaryinputs_freq {value} -primaryinputs_proba {value} -
combinational_freq {value} -combinational_proba {value}
```

## Arguments

-domain\_name {value}

Specifies the domain name in which to initialize frequencies and probabilities.

-clocks\_freq {value}

Specifies the user input frequency in Hz, KHz, or MHz for all clocks.

-clocks\_proba {value}

Specifies the user input probability in % for all clocks.

-registers\_freq {value}

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

-registers\_proba {value}

Specifies the user input probability in % for all registers.

-set\_reset\_freq {value}

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

-set\_reset\_proba {value}

Specifies the user input probability in % for all set/reset nets.

-primaryinputs\_freq {value}

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

-primaryinputs\_proba {value}

Specifies the user input probability in % for all primary inputs.

-combinational\_freq {value}

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

-combinational\_proba {value}

Specifies the user input probability in % for all combinational combinational output.

**Note:** This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all clocks with:

```
smartpower_change_clock_statistics -domain_name {my_domain} -clocks_freq {10 MHz} -
clocks_proba {20} -registers_freq {10 MHz} -registers_proba {20} -set_reset_freq {10
MHz} -set_reset_proba {20} -primaryinputs_freq {10 MHz} -primaryinputs_proba {20} -
combinational_freq {10 MHz} -combinational_proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_change\_setofpin\_statistics

Tcl command; changes the default frequencies and probabilities for a specific set.

```
smartpower_change_setofpin_statistics -domain_name {value} -data_freq {value} -
data_proba {value}
```

### Arguments

-domain\_name {value}

Specifies the domain name in which to initialize data frequencies and probabilities.

-data\_freq {value}

Specifies the user input data frequency in Hz, KHz, or MHz for all sets of pins.

-data\_proba {value}

Specifies the user input data probability in % for all sets of pins.

### Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

### Examples

The following example initializes all clocks with:

```
smartpower_change_setofpin_statistics -domain_name {my_domain} -data_freq {10 MHz} -
data_proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_commit

Tcl command; saves the changes to the design file.

```
smartpower_commit
```

### Arguments

None

### Examples

```
smartpower_commit
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_compute\_vectorless

This Tcl command executes a vectorless analysis of the current operating mode.

## Arguments

None

## Example

```
smartpower_compute_vectorless
```

## See Also

[Tcl Command Documentation Conventions](#)

# smartpower\_create\_domain

Tcl command; creates a new clock or set domain.

```
smartpower_create_domain -domain_type {value} -domain_name {domain_name}
```

## Arguments

-domain\_type {value}

Specifies the type of domain to create. The following table shows the acceptable values for this argument:

| Value | Description                  |
|-------|------------------------------|
| clock | The domain is a clock domain |
| set   | The domain is a set domain   |

-domain\_name {domain\_name}

Specifies the name of the new domain.

## Notes

The domain name cannot be the name of an existing domain.

The domain type must be either clock or set.

## Examples

The following example creates a new clock domain named "clk2":

```
smartpower_create_domain -domain_type {clock} -domain_name {clk2}
```

The following example creates a new set domain named "myset":

```
smartpower_create_domain -domain_type {set} -domain_name {myset}
```

## See Also

[Tcl documentation conventions](#)

[smartpower\\_remove\\_domain](#)

# smartpower\_edit\_scenario

Tcl command; edits a scenario.

```
smartpower_edit_scenario -name {value} -description {value} -mode {value} -new_name {value}
```

## Arguments

-name {value}

Specifies the name of the scenario.

-description {*value*}

Specifies the description of the scenario.

-mode {<*operating mode*>:<*duration*>}

Specifies the mode(s) and duration(s) for the specified scenario.

-new\_name {*value*}

Specifies the new name for the scenario

## Examples

This example edits the name of myscenario to finalscenario:

```
smartpower_edit_scenario -name myscenario -new_name finalscenario
```

## See Also

[Tcl documentation conventions](#)

## smartpower\_import\_vcd

This SmartPower Tcl command imports into SmartPower a VCD file generated by a simulation tool. SmartPower extracts the frequency and probability information from the VCD.

```
import_vcd -file "VCD file" [-opmode "mode name"] [-with_vectorless "TRUE | FALSE"] [-
partial_parse\ "TRUE | FALSE"] [-start_time "decimal value"] [-end_time "decimal value"]
\
[-auto_detect_top_level_name "TRUE | FALSE"] [-top_level_name "top level name"] [-
glitch_filtering\ "false | auto | true"] [-glitch_threshold "integer value"] [-stop_time
"decimal value"]
```

## Parameters

-file "VCD file"

Value must be a file path. This parameter is mandatory.

[-opmode "mode name"]

Value must be a string. This parameter is optional.

[-with\_vectorless "TRUE | FALSE"]

Value must be a boolean. This parameter is optional.

[-partial\_parse "TRUE | FALSE"]

Value must be a boolean. This parameter is optional.

[-start\_time "decimal value"]

Value must be a positive decimal. This parameter is optional.

[-end\_time "decimal value"]

Value must be a positive decimal. This parameter is optional.

[-auto\_detect\_top\_level\_name "TRUE | FALSE"]

Value must be a boolean. This parameter is optional.

[-top\_level\_name "top level name"]

Value must be a string. This parameter is optional.

[-glitch\_filtering "false | auto | true"]

Value must be one of false | auto | true. This parameter is optional.

[-glitch\_threshold "integer value"]

Value must be a positive integer. This parameter is optional.

## Exceptions

None

## Returns

This command does not return a value.

### Usage

This section lists all the parameters for the command, their types, and the values they can be set to. The default value is always listed first.

| smartpower_import_vcd      | Type          | Values                                     | Description                                                                                                                                                                                |
|----------------------------|---------------|--------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| file                       | String        | Path to a VCD file                         | Path to a VCD file.                                                                                                                                                                        |
| opmode                     | String        | Operating mode name<br>"Active" by default | Operating mode in which the VCD will be imported. If the mode doesn't exist, it will be created.                                                                                           |
| with_vectorless            | Boolean       | TRUE FALSE                                 | Specify the method to set the frequency and probability information for signals not annotated by the VCD TRUE: use the vectorless analysis FALSE: use average value computed from the VCD. |
| partial_parse              | Boolean       | FALSE TRUE                                 | Enable partial parsing of the VCD. Start time and end time need to be specified when TRUE.                                                                                                 |
| start_time                 | Decimal value | positive decimal nanoseconds (ns)          | Specify the starting timestamp of the VCD extraction in ns. It must be lower than the specified end_time. It must be lower than the last timestamp in the VCD file.                        |
| end_time                   | Decimal value | positive decimal nanoseconds (ns)          | Specify the end timestamp of the VCD extraction in ns. It must be higher than the specified start_time.                                                                                    |
| auto_detect_top_level_name | Boolean       | TRUE FALSE                                 | Enable the auto detection of the top level name in the VCD file. Top_level_name needs to be specified when FALSE.                                                                          |
| top_level_name             | Boolean       | Full hierarchical name                     | Specify the full hierarchical name of the instance of the design in the VCD file.                                                                                                          |
| glitch_filtering           | Boolean       | Auto FALSE TRUE                            | AUTO: Enable glitch filtering with predefined threshold based on the family<br>TRUE: Enable glitch filtering, glitch_threshold must be specified<br>FALSE: Disable glitch filtering.       |

| smartpower_import_vcd | Type    | Values           | Description                                                        |
|-----------------------|---------|------------------|--------------------------------------------------------------------|
| glitch_threshold      | Integer | Positive integer | Specify the threshold in ps below which glitches are filtered out. |

## Examples

The Tcl command below imports the power.vcd file generated by the simulator into SmartPower:

```
smartpower_import_vcd -file "../../simulation/power.vcd"
```

The Tcl command below extracts information between 1ms and 2ms in the simulation, and stores the information into a custom mode:

```
smartpower_import_vcd -file "../../simulation/power.vcd" -partial_parse TRUE -start_time 1000000 -end_time 2000000 -opmode "power_1ms_to_2ms"
```

## smartpower\_init\_do

Tcl command; initializes the frequencies and probabilities for clocks, registers, set/reset nets, primary inputs, combinational outputs, enables and other sets of pins, and selects a mode for initialization.

```
smartpower_init_do -with {value} -opmode {value} -clocks {value} -registers {value} -
set_reset {value} -primaryinputs {value} -combinational {value} -enables {value} -othersets
{value}
```

## Arguments

-with{value}

This sets the option of initializing frequencies and probabilities with vectorless analysis or with fixed values. The following table shows the acceptable values for this argument:

| Value      | Description                                                        |
|------------|--------------------------------------------------------------------|
| vectorless | Initializes frequencies and probabilities with vectorless analysis |
| fixed      | Initializes frequencies and probabilities with fixed values        |

-opmode {value}

Optional; specifies the mode in which to initialize frequencies and probabilities. The value must be Active or Flash\*Freeze.

-clocks {value}

This sets the option of initializing frequencies and probabilities for all clocks. The following table shows the acceptable values for this argument:

| Value | Description                                                      |
|-------|------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all clocks         |
| false | Does not initialize frequencies and probabilities for all clocks |

-registers {value}

This sets the option of initializing frequencies and probabilities for all registers. The following table shows the acceptable values for this argument:

| Value | Description                                                         |
|-------|---------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all registers         |
| false | Does not initialize frequencies and probabilities for all registers |

```
-set_reset {value}
```

This sets the option of initializing frequencies and probabilities for all set/reset nets. The following table shows the acceptable values for this argument:

| Value | Description                                                              |
|-------|--------------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all set/reset nets         |
| false | Does not initialize frequencies and probabilities for all set/reset nets |

```
-primaryinputs{value}
```

This sets the option of initializing frequencies and probabilities for all primary inputs. The following table shows the acceptable values for this argument:

| Value | Description                                                              |
|-------|--------------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all primary inputs         |
| false | Does not initialize frequencies and probabilities for all primary inputs |

```
-combinational {value}
```

This sets the option of initializing frequencies and probabilities for all combinational outputs. The following table shows the acceptable values for this argument:

| Value | Description                                                                     |
|-------|---------------------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all combinational outputs         |
| false | Does not initialize frequencies and probabilities for all combinational outputs |

```
-enables {value}
```

This sets the option of initializing frequencies and probabilities for all enable sets of pins. The following table shows the acceptable values for this argument:

| Value | Description                                                                   |
|-------|-------------------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all enable sets of pins         |
| false | Does not initialize frequencies and probabilities for all enable sets of pins |

```
-othersets {value}
```

This sets the option of initializing frequencies and probabilities for all other sets of pins. The following table shows the acceptable values for this argument:

| Value | Description                                                                  |
|-------|------------------------------------------------------------------------------|
| true  | Initializes frequencies and probabilities for all other sets of pins         |
| false | Does not initialize frequencies and probabilities for all other sets of pins |

**Note:** This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all clocks with:

```
smartpower_init_do -with {vectorless} -opmode {my_mode} -clocks {true} -registers {true}
-asynchronous {true} -primaryinputs {true} -combinational {true} -enables {true} -
othersets {true}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_set\_clocks\_options

Tcl command; initializes the clock frequency options of all clock domains.

```
smartpower_init_set_clocks_options -with_clock_constraints {value} -
with_default_values {value} -freq {value} -duty_cycle {value}
```

## Arguments

-with\_clock\_constraints {value}

This sets the option of initializing the clock frequencies with frequency constraints from SmartTime. The following table shows the acceptable values for this argument:

| Value | Description                                                  |
|-------|--------------------------------------------------------------|
| true  | Sets initialize clock frequencies with clock constraints ON  |
| false | Sets initialize clock frequencies with clock constraints OFF |

-with\_default\_values {value}

This sets the option of initializing the clock frequencies with a user input default value. The following table shows the acceptable values for this argument:

| Value | Description                                               |
|-------|-----------------------------------------------------------|
| true  | Sets initialize clock frequencies with default values ON  |
| false | Sets initialize clock frequencies with default values OFF |

-freq {value}

Specifies the user input frequency in Hz, KHz, or MHz.

-duty\_cycle {value}

Specifies the user input duty cycles in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all clocks after executing `smartpower_init do` with `-clocks {true}`:

```
smartpower_init_set_clocks_options -with_clock_constraints {true} -with_default_values {true} -freq {10 MHz} -duty_cycle {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_set\_combinational\_options

Tcl commands; initializes the frequency and probability of all combinational outputs.

```
smartpower_init_set_combinational_options -freq {value} -proba {value}
```

## Arguments

`-freq {value}`

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

`-proba {value}`

Specifies the user input probability in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all combinational signals after executing `smartpower_init do` with `-combinational {true}`:

```
smartpower_init_set_combinational_options -freq {10 MHz} -proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_set\_enables\_options

Tcl command; initializes the clock frequency of all enable clocks with the initialization options.

```
smartpower_init_set_enables_options -freq {value} -proba {value}
```

## Arguments

`-freq {value}`

Specifies the user input frequency (in Hz, KHz, or MHz).

`-proba {value}`

Specifies the user input probability in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all clocks after executing `smartpower init do` with `-enables {true}`:

```
smartpower_init_set_enables_options -freq {10 MHz} -proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_set\_primaryinputs\_options

Tcl command; initializes the frequency and probability of all primary inputs.

```
smartpower_init_set_primaryinputs_options -freq {value} -proba {value}
```

## Arguments

`-freq {value}`

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

`-proba {value}`

Specifies the user input probability in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all primary inputs after executing `smartpower init do` with `-primaryinputs {true}`:

```
smartpower_init_set_primaryinputs_options -freq {10 MHz} -proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_set\_registers\_options

Tcl command; initializes the frequency and probability of all register outputs.

```
smartpower_init_set_registers_options -freq {value} -proba {value}
```

## Arguments

`-freq {value}`

Specifies the user input frequency (in Hz, KHz, or MHz) or the toggle rate (in %). If the unit is not provided and toggle rate is active, the value is handled as a toggle rate; if toggle rate is not active, the value is handled as a frequency.

`-proba {value}`

Specifies the user input probability in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Exceptions

None

## Examples

The following example initializes all register outputs after executing `smartpower init do` with `-registers {true}`:

```
smartpower_init_set_registers_options -freq {10 MHz} -proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_init\_setofpins\_values

Tcl command; initializes the frequency and probability of all sets of pins.

```
smartpower_init_setofpins_values -domain_name {name} -freq {value} -proba {value}
```

## Arguments

`-domain_name {name}`

Specifies the set of pins that will be initialized. The following table shows the acceptable values for this argument:

| Value             | Description                                                          |
|-------------------|----------------------------------------------------------------------|
| IOsEnableSet      | Specifies that the IOsEnableSet set of pins will be initialized      |
| MemoriesEnableSet | Specifies that the MemoriesEnableSet set of pins will be initialized |

`-freq {value}`

Specifies the user input frequency in Hz, MHz, or KHz.

`-proba {value}`

Specifies the user input probability in %.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all primary inputs after executing `smartpower init do` with `-othersets {true}`:

```
smartpower_init_setofpins_values -domain_name {IOsEnableSet} -freq {10 MHz} -proba {20}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_remove\_all\_annotations

Tcl command; removes all initialization annotations for the specified mode.

```
smartpower_remove_all_annotations -opmode {value}
```

## Arguments

`-opmode {value}`

Removes all initialization annotations for the specified mode, where value must be Active or Flash\*Freeze.

## Notes

This command is associated with the functionality of [Initialize frequencies and probabilities](#) dialog box.

## Examples

The following example initializes all clocks with opmode Active:

```
smartpower_remove_all_annotations -opmode {Active}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_remove\_file

Tcl command; removes a VCD file from the specified mode or all operating mode. Frequency and probability information of signals annotated by the VCD are set back to the default value.

```
remove_file
-file {value} \
-format {value} \
-opmode {value} \
```

## Arguments

`-file {value}`

Specifies the file to be removed. This is mandatory.

`-format VCD`

Specifies that the type to be removed is a VCD file. This is mandatory.

`[-opmode {value}]`

Specifies the operating mode. This is optional. The following table shows the acceptable values for this argument:

| Value              | Description                               |
|--------------------|-------------------------------------------|
| Active             | The operating mode is set to active       |
| Static (PolarFire) | The operating mode is set to Static       |
| Flash*Freeze       | The operating mode is set to Flash*Freeze |

## Examples

This example removes the file test.vcd from the Active mode.

```
smartpower_remove_file -file "test.vcd" -format VCD -opmode "Active"
```

This example removes the VCD file power1.vcd from all operating modes:

```
smartpower_remove_file -file "power1.vcd" -format VCD
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_remove\_scenario

Tcl command; removes a scenario from the current design.

```
smartpower_remove_scenario -name {value}
```

### Arguments

-name {value}

Specifies the name of the scenario.

### Examples

This example removes a scenario from the current design:

```
smartpower_remove_scenario -name myscenario
```

#### See Also

[Tcl documentation conventions](#)

## smartpower\_report\_power

Tcl command; creates a Power report, which enables you to determine if you have any power consumption problems in your design. It includes information about the global device and SmartPower preferences selection, and hierarchical detail (including gates, blocks, and nets), with a block-by-block, gate-by-gate, and net-by-net power summary SmartPower results.

```
smartpower_report_power\
[-powerunit {value}] \
[-frequnit {value}] \
[-opcond {value}] \
[-opmode {value}] \
[-toggle {value}] \
[-power_summary {value}] \
[-rail_breakdown{value}] \
[-type_breakdown{ value}] \
[-clock_breakdown{value}] \
[-thermal_summary {value}] \
[-battery_life {value}] \
[-opcond_summary {value}] \
[-clock_summary {value}] \
[-style {value}] \
[-sortorder {value}] \
[-sortby {value}] \
[-instance_breakdown {value}] \
[-power_threshold {value}] \
[-filter_instance {value}] \
[-min_power {number}] \
[-max_instance {integer >= 0}] \
[-activity_sortorder {value}] \
[-activity_sortby {value}] \
[-activity_summary {value}] \
[-frequency_threshold {value}] \
[-filter_pin {value}] \
[-min_frequency {value}] \
[-max_pin {value}] \
[-enablerates_sortorder {value}] \
[-enablerates_sortby {value}] \
[-enablerates_summary {value}] \
```

```
[-with_annotation_coverage {value}] \
{filename}
```

## Arguments

**-powerunit** {*value*}

Specifies the unit in which power is set. The following table shows the acceptable values for this argument:

| Value | Description                         |
|-------|-------------------------------------|
| W     | The power unit is set to watts      |
| mW    | The power unit is set to milliwatts |
| uW    | The power unit is set to microwatts |

**-frequnit** {*value*}

Specifies the unit in which frequency is set. The following table shows the acceptable values for this argument:

| Value | Description                            |
|-------|----------------------------------------|
| Hz    | The frequency unit is set to hertz     |
| kHz   | The frequency unit is set to kilohertz |
| MHz   | The frequency unit is set to megahertz |

**-opcond** {*value*}

Specifies the operating condition. The following table shows the acceptable values for this argument:

| Value   | Description                                    |
|---------|------------------------------------------------|
| worst   | The operating condition is set to worst case   |
| typical | The operating condition is set to typical case |
| best    | The operating condition is set to best case    |

**-opmode** {*value*}

Specifies the operating mode. The following table shows the acceptable values for this argument:

| Value        | Description                               |
|--------------|-------------------------------------------|
| Active       | The operating mode is set to Active       |
| Standby      | The operating mode is set to Standby      |
| Flash*Freeze | The operating mode is set to Flash*Freeze |

**-toggle** {*value*}

Specifies the toggle. The following table shows the acceptable values for this argument:

| Value | Description                |
|-------|----------------------------|
| true  | The toggle is set to true  |
| false | The toggle is set to false |

`-power_summary {value}`

Specifies whether to include the power summary, which shows the static and dynamic values in the report. The following table shows the acceptable values for this argument:

| Value | Description                                      |
|-------|--------------------------------------------------|
| true  | Includes the power summary in the report         |
| false | Does not include the power summary in the report |

`-rail_breakdown {value}`

Specifies whether to include the breakdown by rail summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                                  |
|-------|--------------------------------------------------------------|
| true  | Includes the breakdown by rail summary in the report         |
| false | Does not include the breakdown by rail summary in the report |

`-type_breakdown {value}`

Specifies whether to include the breakdown by type summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                                  |
|-------|--------------------------------------------------------------|
| true  | Includes the breakdown by type summary in the report         |
| false | Does not include the breakdown by type summary in the report |

`-clock_breakdown {value}`

Specifies whether to include the breakdown by clock domain in the report. The following table shows the acceptable values for this argument:

| Value | Description                                                          |
|-------|----------------------------------------------------------------------|
| true  | Includes the breakdown by clock domain summary in the report         |
| false | Does not include the breakdown by clock domain summary in the report |

`-thermal_summary {value}`

Specifies whether to include the thermal summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                        |
|-------|----------------------------------------------------|
| true  | Includes the thermal summary in the report         |
| false | Does not include the thermal summary in the report |

`-battery_life {value}`

Specifies whether to include the battery life summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                             |
|-------|---------------------------------------------------------|
| true  | Includes the battery life summary in the report         |
| false | Does not include the battery life summary in the report |

`-opcond_summary {value}`

Specifies whether to include the operating conditions summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                                     |
|-------|-----------------------------------------------------------------|
| true  | Includes the operating conditions summary in the report         |
| false | Does not include the operating conditions summary in the report |

`-clock_summary {value}`

Specifies whether to include the clock domains summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                      |
|-------|--------------------------------------------------|
| true  | Includes the clock summary in the report         |
| false | Does not include the clock summary in the report |

`-style {value}`

Specifies the format in which the report will be exported. The following table shows the acceptable values for this argument:

| Value | Description                              |
|-------|------------------------------------------|
| Text  | The report will be exported as Text file |
| CSV   | The report will be exported as CSV file  |

`-sortby {value}`

Specifies how to sort the values in the report. The following table shows the acceptable values for this argument:

| Value        | Description                     |
|--------------|---------------------------------|
| power values | Sorts based on the power values |
| alphabetical | Sorts in an alphabetical order  |

`-sortorder {value}`

Specifies the sort order of the values in the report. The following table shows the acceptable values for this argument:

| Value      | Description                          |
|------------|--------------------------------------|
| ascending  | Sorts the values in ascending order  |
| descending | Sorts the values in descending order |

`-instance_breakdown {value}`

Specifies whether to include the breakdown by instance in the report. The following table shows the acceptable values for this argument:

| Value | Description                                              |
|-------|----------------------------------------------------------|
| true  | Includes the breakdown by instance in the report         |
| false | Does not include the breakdown by instance in the report |

`-power_threshold {value}`

This specifies whether to include only the instances that consume power above a certain minimum value. When this command is set to true, the `-min_power` argument must also be used to specify that only the instances that consume power above this minimum power value are the ones that are included in the report. The following table shows the acceptable values for this argument:

| Value | Description                                        |
|-------|----------------------------------------------------|
| true  | Includes the power threshold in the report         |
| false | Does not include the power threshold in the report |

`-filter_instance {value}`

This specifies whether to have a limit on the number of instances to include in the Power report. When this command is set to true, the `-max_instance` argument must also be used to specify the maximum number of instances to be included into the Power report. The following table shows the acceptable values for this argument:

| Value | Description                                                                                              |
|-------|----------------------------------------------------------------------------------------------------------|
| true  | Indicates that you want to have a limit on the number of instances to include in the Power report        |
| false | Indicates that you do not want to have a limit on the number of instances to include in the Power report |

```
-min_power {number}
```

Specifies which block to expand based on the minimum power value of a block.

```
-max_instance {integer >= 0}
```

Sets the maximum number of instances to a specified integer greater than or equal to 0 (zero). This will limit the maximum number of instances to be included in the Power report.

```
-activity_sortorder {value}
```

Specifies the sort order for the activity summary. The following table shows the acceptable values for this argument:

| Value      | Description                          |
|------------|--------------------------------------|
| ascending  | Sorts the values in ascending order  |
| descending | Sorts the values in descending order |

```
-activity_sortby {value}
```

Specifies how to sort the values for the activity summary. The following table shows the acceptable values for this argument:

| Value     | Description                               |
|-----------|-------------------------------------------|
| pin name  | Sorts based on the pin name               |
| net name  | Sorts based on the net name               |
| domain    | Sorts based on the clock domain           |
| frequency | Sorts based on the clock frequency        |
| source    | Sorts based on the clock frequency source |

```
-activity_summary {value}
```

Specifies whether to include the activity summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                         |
|-------|-----------------------------------------------------|
| true  | Includes the activity summary in the report         |
| false | Does not include the activity summary in the report |

```
-frequency_threshold {value}
```

Specifies whether to add a frequency threshold. The following table shows the acceptable values for this argument:

| Value | Description                        |
|-------|------------------------------------|
| true  | Adds a frequency threshold         |
| false | Does not add a frequency threshold |

```
-filter_pin {value}
```

Specifies whether to filter by maximum number of pins. The following table shows the acceptable values for this argument:

| Value | Description                              |
|-------|------------------------------------------|
| true  | Filters by maximum number of pins        |
| false | Des not filter by maximum number of pins |

`-min_frequency {value}`

Sets the minimum frequency to {decimal value [unit { Hz | KHz | MHz}]}.

`-max_pin {value}`

Sets the maximum number of pins.

`-enablerates_sortorder {value}`

Specifies the sort order for the probabilities summary. The following table shows the acceptable values for this argument:

| Value      | Description                          |
|------------|--------------------------------------|
| ascending  | Sorts the values in ascending order  |
| descending | Sorts the values in descending order |

`-enablerates_sortby {value}`

Specifies how to sort the values for the probabilities summary. The following table shows the acceptable values for this argument:

| Value     | Description                               |
|-----------|-------------------------------------------|
| pin name  | Sorts based on the pin name               |
| net name  | Sorts based on the net name               |
| domain    | Sorts based on the clock domain           |
| frequency | Sorts based on the clock frequency        |
| source    | Sorts based on the clock frequency source |

`-enablerates_summary {value}`

Specifies whether to include the probabilities summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                         |
|-------|-----------------------------------------------------|
| true  | Includes the activity summary in the report         |
| false | Does not include the activity summary in the report |

`-with_annotation_coverage {value}`

Specifies whether to include the annotation coverage summary in the report. The following table shows the acceptable values for this argument:

| Value | Description                                            |
|-------|--------------------------------------------------------|
| true  | Includes the annotation coverage summary in the report |

| Value | Description                                                    |
|-------|----------------------------------------------------------------|
| false | Does not include the annotation coverage summary in the report |

```
{filename}
```

Specifies the name of the report.

## Notes

- The following arguments have been removed. Running the script will trigger a warning message: Warning: Invalid argument: -argname "argvalue" Ignored. Ignore the warning.
  - annotated\_pins {value}
  - stat\_pow {value}
  - dyn\_pow {value}
- Flash\*Freeze, Sleep, and Shutdown are available only for certain families and devices.
- Worst and Best are available only for certain families and devices.

## Examples

This example generates a Power report named report.rpt.

```
smartpower_report_power -powerunit "uW" -frequnit "MHz" -opcond "Typical" -opmode
"Active" -toggle "TRUE" -rail_breakdown "TRUE" -battery_life "TRUE" -style "Text" -
power_summary "TRUE" -activity_sortby "Source" text_report.txt
```

## smartpower\_set\_mode\_for\_analysis

Tcl command; sets the mode for cycle-accurate power analysis.

```
smartpower_set_mode_for_analysis -mode {value}
```

## Arguments

```
-mode {value}
```

Specifies the mode for cycle-accurate power analysis.

| Value        | Description                               |
|--------------|-------------------------------------------|
| Active       | The operating mode is set to Active       |
| Standby      | The operating mode is set to Standby      |
| Flash*Freeze | The operating mode is set to Flash*Freeze |

## Examples

The following example sets the mode for analysis to active:

```
smartpower_set_mode_for_analysis -mode {active}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_set\_mode\_for\_pdpr

This SmartPower Tcl command sets the operating mode used by the Power Driven Place and Route (PDPR) tool during power optimization.

```
smartpower_set_mode_for_pdpr -opmode {value}
```

### Parameters

-opmode {*value*}

Value must be a valid operating mode.

This parameter is mandatory.

Sets the operating mode for your power driven place and route.

### Exceptions

None

### Return Value

This command does not return a value.

### Examples

This example sets the Active mode as the operating mode for Power Driven Place and Route.

```
set_mode_for_pdpr -opmode "Active"
```

This example creates a custom mode and set it to be used by Power Driven Place and Route (PDPR).

```
smartpower_add_new_custom_mode -name "MyCustomMode" \  
-description "for PDPR" -base_mode "Active" \  
smartpower_set_mode_for_pdpr -opmode "MyCustomMode"
```

### See Also

[Tcl Command Documentation Conventions](#)

## smartpower\_set\_operating\_condition

Tcl command; sets the operating conditions used in SmartPower to one of the pre-defined types.

```
smartpower_set_operating_condition -opcond {value}
```

### Arguments

-opcond {*value*}

Specifies the value of the operating condition. The following table shows the acceptable values for this argument:

| Value   | Description                              |
|---------|------------------------------------------|
| best    | Sets the operating conditions to best    |
| typical | Sets the operating conditions to typical |
| worst   | Sets the operating conditions to worst   |

## Examples

This example sets the operating conditions to best:

```
smartpower_set_operating_condition -opcond {best}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_set\_operating\_conditions

Tcl command; sets the operating conditions used in SmartPower.

```
smartpower_set_operating_conditions "still_air | 1.0_mps | 2.5_mps | custom" -heatsink  
"None | custom | 10mm_Low_Profile | 15mm_Medium_Profile | 20mm_High_Profile" -boardmodel  
"None_Conservative | JEDEC_2s2p" [-teta_ja "decimal value"] [-teta_sa "decimal value"]
```

## Arguments

`-still_air {value}`

Specifies the value for the still air operating condition. The following table shows the acceptable values for this argument:

| Value   | Description                              |
|---------|------------------------------------------|
| 1.0_mps | Sets the operating conditions to best    |
| 2.5_mps | Sets the operating conditions to typical |
| custom  | Sets the operating conditions to worst   |

`-heatsink {value}`

Specifies the value of the operating condition. The following table shows the acceptable values for this argument:

| Value             | Description                  |
|-------------------|------------------------------|
| none              | No heat sink                 |
| custom            | Sets a custom heat sink size |
| 10mm_Low_Profile  | 10 mm heat sink              |
| 15mm_Low_Profile  | 15 mm heat sink              |
| 20mm_High_Profile | 20 mm heat sink              |

`-boardmodel {value}`

Specifies your board model. The following table shows the acceptable values for this argument:

| Value             | Description                          |
|-------------------|--------------------------------------|
| None_Conservative | No board model, conservative routing |
| JEDEC_2s2p        | JEDEC 2s2p board model               |

`-teta_ja {decimal_value}`

Optional; sets your teta ja value; must be a positive decimal

-teta\_sa {*decimal\_value*}

Optional; sets your teta sa value; must be a positive decimal.

## Examples

This example sets the operating conditions to best:

```
set_operating_conditions -airflow "still_air" -heatsink "None" -boardmodel
"None_Conservative "
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_set\_process

Tcl command; sets the process used in SmartPower to one of the pre-defined types.

```
smartpower_set_process -process {value}
```

## Arguments

-process {*value*}

Specifies the value of the operating condition. The following table shows the acceptable values for this argument:

| Value   | Description                                |
|---------|--------------------------------------------|
| Typical | Sets the process for SmartPower to typical |
| Maximum | Sets the process for SmartPower to maximum |

## Examples

This example sets the operating conditions to typical:

```
smartpower_set_process -process {Typical}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_set\_scenario\_for\_analysis

Tcl command; sets the scenario for cycle-accurate power analysis.

```
smartpower_set_scenario_for_analysis -scenario{value}
```

## Arguments

-scenario {*value*}

Specifies the mode for cycle-accurate power analysis.

## Examples

The following example sets the scenario for analysis to my\_scenario:

```
smartpower_set_scenario_for_analysis -scenario {my_scenario}
```

**See Also**
[Tcl documentation conventions](#)

## smartpower\_set\_temperature\_opcond

Tcl command; sets the temperature in the operating conditions to one of the pre-defined types.

```
smartpower_set_temperature_opcond -use{value}
```

**Arguments**

-use{value}

Specifies the temperature in the operating conditions. The following table shows the acceptable values for this argument:

| Value   | Description                                                                                                                                |
|---------|--------------------------------------------------------------------------------------------------------------------------------------------|
| oprange | Sets the temperature in the operating conditions as specified in your <a href="#">Project Settings</a> .                                   |
| design  | Sets the temperature in the operating conditions as specified in the SmartPower design-wide operating range. Applies to SmartPower only.   |
| mode    | Sets the temperature in the operating conditions as specified in the SmartPower mode-specific operating range. Applies to SmartPower only. |

**Examples**

This example sets the temperature in the operating conditions as specified in the custom mode-settings:

```
smartpower_set_temperature_opcond -use{mode}
```

**See Also**
[Tcl documentation conventions](#)

## smartpower\_set\_voltage\_opcond

Tcl command; sets the voltage in the operating conditions.

```
smartpower_set_voltage_opcond -voltage{value} -use{value}
```

**Arguments**

-voltage{value}

Specifies the voltage supply in the operating conditions. The following table shows the acceptable values for this argument:

| Value | Description                                     |
|-------|-------------------------------------------------|
| VDD   | Sets the voltage operating conditions for VDD   |
| VDD18 | Sets the voltage operating conditions for VDD18 |

| Value     | Description                                         |
|-----------|-----------------------------------------------------|
| VDDAUX    | Sets the voltage operating conditions for VDDAUX    |
| VDDI 1.1  | Sets the voltage operating conditions for VDD 1.1   |
| VDDI 1.2  | Sets the voltage operating conditions for VDDI 1.2  |
| VDDI 1.35 | Sets the voltage operating conditions for VDDI 1.35 |
| VDDI 1.5  | Sets the voltage operating conditions for VDDI 1.5  |
| VDDI 1.8  | Sets the voltage operating conditions for VDDI 1.8  |
| VDDI 2.5  | Sets the voltage operating conditions for VDDI 2.5  |
| VDDI 3.3  | Sets the voltage operating conditions for VDDI 3.3  |
| VDD25     | Sets the voltage operating conditions for VDD25     |
| VDDA      | Sets the voltage operating conditions for VDDA      |
| VDDA25    | Sets the voltage operating conditions for VDDA25    |

`-use{value}`

Specifies the voltage in the operating conditions for each voltage supply. The following table shows the acceptable values for this argument:

| Value   | Description                                                                                                                            |
|---------|----------------------------------------------------------------------------------------------------------------------------------------|
| oprange | Sets the voltage in the operating conditions as specified in your <a href="#">Project Settings</a> .                                   |
| design  | Sets the voltage in the operating conditions as specified in the SmartPower design-wide operating range. Applies to SmartPower only.   |
| mode    | Sets the voltage in the operating conditions as specified in the SmartPower mode-specific operating range. Applies to SmartPower only. |

## Examples

This example sets the VCCA as specified in the SmartPower mode-specific settings:

```
smartpower_set_voltage_opcond -voltage{vcca} -use{mode}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_temperature\_opcond\_set\_design\_wide

Tcl command; sets the temperature for SmartPower design-wide operating conditions.

```
smartpower_temperature_opcond_set_design_wide -best{value} -typical{value} -worst{value} -
thermal_mode{value}
```

## Arguments

-best{value}

Specifies the best temperature (in degrees Celsius) used for design-wide operating conditions.

-typical{value}

Specifies the typical temperature (in degrees Celsius) used for design-wide operating conditions.

-worst{value}

Specifies the worst temperature (in degrees Celsius) used for design-wide operating conditions.

-thermal\_mode{value}

Specifies the mode in which the junction temperature is computed. The following table shows the acceptable values for this argument:

| Value   | Description                                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------------------|
| ambient | The junction temperature will be iteratively computed with total static power                                           |
| opcond  | The junction temperature will be given as one of the operating condition range values specified in the device selection |

## Examples

This example sets the temperature for design-wide operating conditions to Best 20, Typical 30, and Worst 60:

```
smartpower_temperature_opcond_set_design_wide -best{20} -typical{30} -worst{60}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_temperature\_opcond\_set\_mode\_specific

Tcl command; sets the temperature for SmartPower mode-specific operating conditions.

```
smartpower_temperature_opcond_set_mode_specific -opmode{value} -thermal_mode{value} -
best{value} -typical{value} -worst{value} -thermal_mode{value}
```

## Arguments

-opmode {value}

Specifies the operating mode. The following table shows the acceptable values for this argument:

| Value        | Description                               |
|--------------|-------------------------------------------|
| Active       | The operating mode is set to Active       |
| Static       | The operating mode is set to Static       |
| Flash*Freeze | The operating mode is set to Flash*Freeze |

-thermal\_mode{value}

Specifies the mode in which the junction temperature is computed. The following table shows the acceptable values for this argument:

| Value   | Description                                                                                                             |
|---------|-------------------------------------------------------------------------------------------------------------------------|
| ambient | The junction temperature will be iteratively computed with total static power                                           |
| opcond  | The junction temperature will be given as one of the operating condition range values specified in the device selection |

`-best{value}`

Specifies the best temperature (in degrees Celsius) for the selected mode.

`-typical{value}`

Specifies the typical temperature (in degrees Celsius) for the selected mode.

`-worst{value}`

Specifies the worst temperature (in degrees Celsius) for the selected mode.

## Examples

This example sets the temperature for mode-specific operating conditions for mode1:

```
smartpower_temperature_opcond_set_mode_specific -mode{mode1} -best{20} -typical{30} -
worst{60}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_voltage\_opcond\_set\_design\_wide

Tcl command; sets the voltage settings for SmartPower design-wide operating conditions.

```
smartpower_voltage_opcond_set_design_wide -voltage{value} -best{value} -typical{value} -
worst{value}
```

## Arguments

`-voltage{value}`

Specifies the voltage supply in the operating conditions. The following table shows the acceptable values for this argument:

| Value    | Description                                        |
|----------|----------------------------------------------------|
| VDD      | Sets the voltage operating conditions for VDD      |
| VDDI 2.5 | Sets the voltage operating conditions for VDDI 2.5 |
| VPP      | Sets the voltage operating conditions for VPP      |
| VCCA     | Sets the voltage operating conditions for VCCA     |
| VCCI 3.3 | Sets the voltage operating conditions for VCCI 3.3 |
| VCCI 2.5 | Sets the voltage operating conditions for VCCI 2.5 |
| VCCI 1.8 | Sets the voltage operating conditions for VCCI 1.8 |

| Value    | Description                                        |
|----------|----------------------------------------------------|
| VCCI 1.5 | Sets the voltage operating conditions for VCCI 1.5 |
| VCC33A   | Sets the voltage operating conditions for VCC33A   |
| VCCDA    | Sets the voltage operating conditions for VCCDA    |

`-best{value}`

Specifies the best voltage used for design-wide operating conditions.

`-typical{value}`

Specifies the typical voltage used for design-wide operating conditions.

`-worst{value}`

Specifies the worst voltage used for design-wide operating conditions.

## Examples

This example sets VCCA for design-wide to best 20, typical 30 and worst 40:

```
smartpower_voltage_opcond_set_design_wide -voltage{VCCA} -best{20} -typical{30} -
worst{40}
```

### See Also

[Tcl documentation conventions](#)

## smartpower\_voltage\_opcond\_set\_mode\_specific

Tcl command; sets the voltage settings for SmartPower mode-specific use operating conditions.

```
smartpower_voltage_opcond_set_mode_specific -opmode{value} -voltage{value} -best{value} -
typical{value} -worst{value}
```

## Arguments

`-opmode {value}`

Use this option to specify the mode from which the operating conditions are extracted to generate the report.

| Value        | Description                               |
|--------------|-------------------------------------------|
| Active       | The operating mode is set to Active       |
| Static       | The operating mode is set to Static       |
| Flash*Freeze | The operating mode is set to Flash*Freeze |

`-voltage{value}`

Specifies the voltage in the operating conditions. The following table shows the acceptable values for this argument:

| Value | Description                                   |
|-------|-----------------------------------------------|
| VDD   | Sets the voltage operating conditions for VDD |

| Value     | Description                                         |
|-----------|-----------------------------------------------------|
| VDD18     | Sets the voltage operating conditions for VDD18     |
| VDDAUX    | Sets the voltage operating conditions for VDDAUX    |
| VDDI 1.1  | Sets the voltage operating conditions for VDD 1.1   |
| VDDI 1.2  | Sets the voltage operating conditions for VDDI 1.2  |
| VDDI 1.35 | Sets the voltage operating conditions for VDDI 1.35 |
| VDDI 1.5  | Sets the voltage operating conditions for VDDI 1.5  |
| VDDI 1.8  | Sets the voltage operating conditions for VDDI 1.8  |
| VDDI 2.5  | Sets the voltage operating conditions for VDDI 2.5  |
| VDDI 3.3  | Sets the voltage operating conditions for VDDI 3.3  |
| VDD25     | Sets the voltage operating conditions for VDD25     |
| VDDA      | Sets the voltage operating conditions for VDDA      |
| VDDA25    | Sets the voltage operating conditions for VDDA25    |

`-best{value}`

Specifies the best voltage used for mode-specific operating conditions.

`-typical{value}`

Specifies the typical voltage used for mode-specific operating conditions.

`-worst{value}`

Specifies the worst voltage used for mode-specific operating conditions.

## Examples

This example sets the voltage for the static mode and sets best to 20, typical to 30 and worst to 40:

```
smartpower_voltage_opcond_set_mode_specific -opmode{active} -voltage{VCCA} -best{20} -
typical{30} -worst{40}
```

## See Also

[Tcl documentation conventions](#)

# Programming and Configuration

## Tcl Commands

### configure\_design\_initialization\_data

This Tcl command sets the parameter values needed for generating initialization data.

```
configure_design_initialization_data
-second_stage_start_address {<valid_snvm_address>} \
-third_stage_start_address {<valid_address_for_third_stage_memory_type>} \
-third_stage_memory_type {<UPROM | SNVM | SPIFLASH_NONAUTH >}\
-third_stage_spi_clock_divider { 1 | 2 | 4 | 6} \
-init_timeout {<int_between_1_and_128_seconds>}
```

### Arguments

-second\_stage\_start\_address

String parameter for the start address of the second stage initialization client.

Specified as a 32-bit hexadecimal string.

The first stage client is always placed in sNVM, so it must be a valid sNVM address aligned on a page boundary.

There are 221 sNVM pages and each page is 256 bytes long, so the address will be between 0 and DC00.

#### Notes:

Although the actual size of each page is 256 bytes, only 252 bytes are available to the user.

The first stage initialization client is always added to SNVM at 0xDC00 (page 220). So the valid addresses for the second stage initialization client are 0x0 (page 0) to 0xDB00 (page 219).

-third\_stage\_start\_address

String parameter for the start address of the third stage initialization client.

Specified as a 32-bit hexadecimal string, and must be one of the following:

- valid sNVM address aligned on a page boundary
- valid UPROM address aligned on a block boundary
- valid SPIFLASH address

-third\_stage\_memory\_type

The memory where the third stage initialization client will be placed.

The value can be UPROM, SNVM, or SPIFLASH\_NONAUTH. The default is UPROM.

This parameter determines the valid value for parameter 'third\_stage\_start\_address'.

-third\_stage\_spi\_clock\_divider

The value can be 1, 2, 4, or 6. The default value is 1.

-init\_timeout

Timeout value in seconds. Initialization is aborted if it does not complete before timeout expires.

The value can be between 1 and 128. The default value is 128.

### Example

```
configure_design_initialization_data
-second_stage_start_address 200 \
-third_stage_start_address 400 \
```

```
-third_stage_memory_type UPROM \
-third_stage_spi_clock_divider 4 \
-init_timeout 120
```

### See Also

[generate design initialization data](#)

## configure\_ram

This Tcl command uses the RAM configuration file to configure RAM.

```
configure_ram
-cfg file <RAM configuration file>
```

### Arguments

-cfg\_file *file*  
*file* is a valid configuration file to configure RAM.

## set\_client (for RAM)

```
set_client \
-logical_instance_name {} \
-content_type {MEMORY_FILE | INITIALIZE_WITH_ZERO} \
-memory_file_format {} \
-memory_file {} \
-content_type_changed {1}
```

### Arguments

-logical\_instance\_name

Hierarchical instance name of the logical RAM that the client will initialize.

-content\_type

The -content\_type can be MEMORY\_FILE or INITIALIZE\_WITH\_ZERO.

MEMORY\_FILE – Client will be initialized with content from the memory file.

INITIALIZE\_WITH\_ZERO – Client will be initialized with zeros.

-memory\_file\_format

For RAM blocks from PF\_SRAM\_AHBL\_AXI core, the supported file format is “INTEL\_HEX”. For all others, the supported file formats are “INTEL\_HEX” and “MOTOROLA\_S”.

-memory\_file

Path of the imported memory file. This can be absolute, or relative to the project.

-content\_type\_changed {1}

If client information is modified by the user in Fabric RAMs, the value must be “1”.

### Example

The following example shows the set\_client Tcl command for RAM.

```
set_client \
-logical_instance_name {TOP/SD1_0/dplsramp1_0} \
-content_type {MEMORY_FILE} \
-memory_file_format {} \
-memory_file
{D:/local_z_folder/work/libero_projects/g5/mint_gfad_spi_done/ram_client_1.hex} \
-content_type_changed {1}
```

## configure\_snvm

Tcl command; configures sNVM from the specified configuration file.

```
configure_snvm -cfg_file file
```

### Arguments

-cfg\_file *file*

*file* is a valid configuration file to configure sNVM.

### See Also

Configure sNVM

### Sample sNVM Configuration File

```
set_plain_text_client \
  -client_name {pt_A} \
  -number_of_bytes 64 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {C:/local_z_folder/work/memory files/binary8x16.mem} \
  -start_page 0 \
  -use_for_simulation 0 \
  -reprogram 1 \
  -use_as_rom 0
set_plain_text_client \
  -client_name {pt_client} \
  -number_of_bytes 64 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {C:/local_z_folder/work/memory files/binary32X16.mem} \
  -start_page 2 \
  -use_for_simulation 0 \
  -reprogram 1 \
  -use_as_rom 0
set_plain_text_client \
  -client_name {pt_client_16bit} \
  -number_of_bytes 32 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {C:/local_z_folder/work/memory files/binary16X16.mem} \
  -start_page 1 \
  -use_for_simulation 0 \
  -reprogram 1 \
  -use_as_rom 0
set_plain_text_client \
  -client_name {INIT_STAGE_1_SNVM_CLIENT} \
  -number_of_bytes 504 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {designer\top\top_init_stage_1_snvm.mem} \
  -start_page 219 \
```

```

    -use_for_simulation 0 \
    -reprogram 1 \
    -use_as_rom 0
set_plain_text_client \
    -client_name {pt_B} \
    -number_of_bytes 1 \
    -content_type {STATIC_FILL} \
    -content_file_format {Microsemi-Binary 8/16/32 bit} \
    -content_file {} \
    -start_page 3 \
    -use_for_simulation 0 \
    -reprogram 1 \
    -use_as_rom 0

```

### See Also

[set\\_plain\\_text\\_client](#)

[set\\_plain\\_text\\_auth\\_client](#)

[set\\_cipher\\_text\\_auth\\_client](#)

[set\\_usk\\_client](#)

## configure\_spiflash

This Tcl command configures SPI Flash Memory from the specified SPI Flash Memory configuration file.

```
configure_spiflash -cfg_file file
```

### Arguments

`-cfg_file file`

Specify a valid configuration file to configure SPI Flash.

*file* is the SPI Flash Memory configuration file. *file* can be an absolute path to the SPI Flash Memory configuration file or it can be a path relative to a Tcl file that includes the command. After running this command, the new configuration is saved as a project `spiflash.cfg` file.

### See Also

[Configure SPI Flash](#)

### Sample SPI Flash Configuration File

```

set_auto_update_mode {0}
set_manufacturer {Macronix}
set_client \
    -client_name {vzcx} \
    -client_type {FILE_SPI} \
    -content_type {MEMORY_FILE} \
    -content_file {..\..\..\memory files\spi_bitstream.spi} \
    -start_address {2561} \
    -client_size {388} \
    -program {1}
set_client \
    -client_name {golden} \
    -client_type {FILE_SPI_GOLDEN} \
    -content_type {MEMORY_FILE} \

```

```

-content_file {C:\local_z_folder\work\memory_files\spi_bitstream.spi} \
-start_address {1042} \
-client_size {389} \
-program {1}

set_client \
-client_name {INIT_STAGE_3_SPI_CLIENT} \
-client_type {INIT} \
-content_type {MEMORY_FILE} \
-content_file {C:\local_z_folder\work\libero_projects\g5\SNVM_TEST_top_uic.bin} \
-start_address {4096} \
-client_size {4124} \
-program {1}

```

## SPM\_OTP

Configures the parameters for SPM\_OTP.

```

configure_tool \
[-name SPM_OTP] \
[-params permanently_disable_debugging 0 | 1] \
[-params permanently_disable_dpk 0 | 1] \
[-params permanently_disable_factory_access 0 | 1] \
[-params permanently_disable_prog_interfaces 0 | 1] \
[-params permanently_disable_upk1 0 | 1] \
[-params permanently_disable_upk2 0 | 1] \
[-params permanently_write_protect_fabric 0 | 1]

```

The following tables list the parameter names and values.

### configure\_tool -name {SPM\_OTP} parameter:value pair

| Name                                | Type | Value                | Description                                                                                                                                                                                                                   |
|-------------------------------------|------|----------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| permanently_disable_debugging       | bool | false   true   0   1 | Specifies that the SmartDebug access control and reading temperature and voltage sensor settings is either permanently enabled or disabled. A value of true/1 will permanently disable debugging. The default value is false. |
| permanently_disable_dpk             | bool | false   true   0   1 | Specifies that the Debug Pass Key is either permanently enabled or disabled. A value of true/1 will permanently disable FlashLock DPK unlocking. The default value is false.                                                  |
| permanently_disable_factory_access  | bool | false   true   0   1 | Specifies that the access policy for Microsemi factory test mode is either permanently enabled or disabled. A value of true/1 will permanently disable Microsemi factory test mode. The default value is false.               |
| permanently_disable_prog_interfaces | bool | false   true   0   1 | Specifies that the Programming interfaces such as Auto Programming, JTAG, SPI Slave are either permanently enabled or                                                                                                         |

| Name                             | Type | Value                | Description                                                                                                                                                                             |
|----------------------------------|------|----------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
|                                  |      |                      | disabled. A value of true/1 will permanently disable all of the programming interfaces. The default value is false.                                                                     |
| permanently_disable_upk1         | bool | false   true   0   1 | Specifies that the User Key UPK1 is either permanently enabled or disabled. A value of true/1 will permanently disable FlashLock UPK1 unlocking. The default value is false.            |
| permanently_disable_upk2         | bool | false   true   0   1 | Specifies that the User Key UPK2 is either permanently enabled or disabled. A value of true/1 will permanently disable FlashLock UPK2 unlocking. The default value is false.            |
| permanently_write_protect_fabric | bool | false   true   0   1 | Specifies that the write protection for fabric is either permanently enabled or disabled. A value of the true/1 will make the fabric one-time programmable. The default value is false. |

## Examples

The following example specifies that SPM\_OTP tool is configured to permanently disable user keys UPK1 and UPK2.

```
configure_tool \
  -name {SPM_OTP} \
  -params {permanently_disable_debugging:false} \
  -params {permanently_disable_dpk:false} \
  -params {permanently_disable_factory_access:false} \
  -params {permanently_disable_prog_interfaces:false} \
  -params {permanently_disable_upk1:true} \
  -params {permanently_disable_upk2:true} \
  -params {permanently_write_protect_fabric:false}
```

The following example specifies that SPM\_OTP tool is configured to permanently disable programming interfaces.

```
configure_tool \
  -name {SPM_OTP} \
  -params {permanently_disable_debugging:false} \
  -params {permanently_disable_dpk:false} \
  -params {permanently_disable_factory_access:false} \
  -params {permanently_disable_prog_interfaces:true} \
  -params {permanently_disable_upk1:false} \
  -params {permanently_disable_upk2:false} \
  -params {permanently_write_protect_fabric:false}
```

### See Also

[remove permanent locks](#)

## configure\_uprom

Tcl command; configures uPROM from the specified configuration file.

```
configure_uprom -cfg_file file
```

### Arguments

-cfg\_file *file*

*file* is a valid configuration file to configure uPROM.

### See Also

[Configure uPROM](#)

### Sample uPROM Configuration File

```
set_data_storage_client \
  -client_name {client1_from_elsewhere} \
  -number_of_words 37 \
  -use_for_simulation {0} \
  -content_type {MEMORY_FILE} \
  -memory_file_format {Microsemi-Binary} \
  -memory_file {C:/local_z_folder/work/memory_files/sar_86586_uprom.mem} \
  -base_address 1500
set_data_storage_client \
  -client_name {large_1} \
  -number_of_words 100 \
  -use_for_simulation {0} \
  -content_type {STATIC_FILL} \
  -base_address 5000
```

## export\_spiflash\_image

This Tcl command exports a SPI Flash image file to a specified directory.

```
export_spiflash_image -file_name {name of file} -export_dir {absolute path to folder location}
```

### Arguments

-file\_name *name of file*

The name of the image file.

-export\_dir *absolute path to folder location*

Folder/directory location.

### See Also

[Export Flash Image](#)

## generate\_design\_initialization\_data

This Tcl command creates the memory files on disk, adds the initialization clients to the target memories, and writes the configuration files to disk.

This command also runs validation on the saved configuration files and writes out errors (if any) in the log. This command causes the UI of the Configure Design Initialization Data and Memories tool to refresh and show the latest configuration and validation errors (if any) in the tables.

This command takes no parameters.

```
generate_design_initialization_data
```

### See Also

[configure\\_design\\_initialization\\_data](#)

## generate\_initialization\_mem\_files

This Tcl command sets the parameter values needed for generating memory files to be used with design initialization clients.

```
generate_initialization_mem_files
-second_stage_start_address {<valid_snvm_address>} \
-third_stage_start_address {<valid_address_for_third_stage_memory_type>} \
-third_stage_memory_type {<UPROM | SNVM | SPIFLASH_NONAUTH >}\
-third_stage_spi_clock_divider{ 1 | 2 | 4 | 6} \
-init_timeout { <int_between_1_and_128_seconds>}\
-custom_cfg_file {<valid_user_specified_configuration_file>}
```

### Arguments

`-second_stage_start_address`

String parameter for the start address of the second stage sNVM initialization client.

Specified as a 32-bit hexadecimal string.

The second stage client is always placed in sNVM, so it must be a valid sNVM address aligned on a page boundary.

This address will be between 0 and DB00. There are 221 sNVM pages and each page is 256 bytes long. The last two pages are reserved for the first stage initialization client so they are not available for the second stage initialization client.

`-third_stage_memory_type`

The memory where the third stage initialization client will be placed.

The value can be UPROM, SNVM, or SPIFLASH\_NONAUTH. The default is SNVM.

This parameter determines the valid value for parameter 'third\_stage\_start\_address'.

`-third_stage_start_address`

String parameter for the start address of the third stage initialization client.

Specified as a 32-bit hexadecimal string, and must be one of the following:

- valid sNVM address aligned on a page boundary
- valid UPROM address aligned on a block boundary
- valid SPIFLASH address

`-third_stage_spi_clock_divider`

The value can be 1, 2, 4, or 6. The default value is 1.

`-init_timeout`

Timeout value in seconds. Initialization is aborted if it does not complete before timeout expires.

The value can be between 1 and 128. The default value is 128.

`-custom_cfg_file`

Specifies the user\_specified configuration file to be loaded in.

## Example

```
generate_initialization_mem_files \
  -second_stage_start_address 200 \
  -third_stage_memory_type UPROM \
  -third_stage_start_address 400 \
  -third_stage_spi_clock_divider 6 \
  -init_timeout 120 \
  -custom_cfg_file {D:\test\my.txt}
```

### See Also

#### Design and Memory Initialization

## remove\_permanent\_locks

Removes all the locks configured in SPM\_OTP. This command can only be used when at least one lock is disabled using SPM\_OTP.

```
remove_permanent_locks
```

## Example

```
remove_permanent_locks
```

### See Also

#### [SPM\\_OTP](#)

## select\_programmer

This Tcl command enables the specified programmer and disables all other connected programmers. This command is useful when multiple programmers are connected.

```
select_programmer -programmer_id {programmer_id} -host_name {host_name} -host_port  
{host_port}
```

## Arguments

-programmer\_id <*programmer\_id*>

The programmer to be enabled. See [Select Programmer](#).

-host\_name <*host\_name*>

The host name or IP address. This argument is required for a remote programmer and optional for a local programmer. For local programmer, if specified it must be "localhost".

-host\_port <*host\_port*>

This argument is required for a remote programmer and optional for a local programmer. If omitted, the default port is used (currently, the default is 80).

For a local host, both "localhost" and its port should be specified or omitted.

**Note:** The def variable "LOCAL\_PROGRAM\_DEBUG\_SERVER\_PORT" is used to set a different default local host port.

## Examples

```
select_programmer -programmer_id {00557}
select_programmer -programmer_id {00557} \
  -host_name {localhost} \
  -host_port {80}
```

## See Also

### [Select Programmer](#)

## set\_auto\_update\_mode

This command enables or disables auto update.

```
set_auto_update_mode {0|1}
```

If `set_auto_update_mode` is 0, auto update is disabled. If `set_auto_update_mode` is 1, auto update is enabled.

## set\_cipher\_text\_auth\_client

This Tcl command is added to the sNVM .cfg file that is given as the parameter to the `configure_snvm` command.

Cipher-text Authenticated clients have 236 bytes available for user data in each page of sNVM.

```
set_cipher_text_auth_client
  -client_name {<name>}
  -number_of_bytes <number>
  -content_type {MEMORY_FILE | STATIC_FILL}
  -content_file_format {Microsemi-Binary 8/16/32 bit}
  -content_file {<path>}
  -start_page <number>
  -use_for_simulation 0
  -reprogram 0 | 1
  -use_as_rom 0 | 1
```

## Arguments

`-client_name`

The name of the client. Needs to start with an alphabetic letter. Underscores and numerals are allowed at all positions other than the first.

`-number_of_bytes`

The size of the client specified in bytes.

`-content_type`

Source of data for the client. This can either be a memory file, or all zeros. Allowed values are `MEMORY_FILE` or `STATIC_FILL`.

`-content_file_format`

Only 'Microsemi-Binary 8/16/32 bit' is supported at this time.

`-content_file`

Path of the memory file. This can be absolute, or relative to the project.

`-start_page`

The page number in sNVM where data for this client will be placed.

`-use_for_simulation`

Only value 0 is allowed.

`-reprogram`

Boolean field; specifies whether the client will be programmed into the final design or not. Possible values are 0 or 1.

`-use_as_rom` 0

Boolean field; specifies whether the client will allow only reads, or both read and writes. Possible values are 0 or 1.

## Example

```
set_cipher_text_auth_client \
  -client_name {c} \
  -number_of_bytes 12 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {D:/local_z_folder/work/memory_files/binary8x12.mem} \
  -start_page 3 \
  -use_for_simulation 0 \
  -reprogram 1 \
```

### See Also

[set\\_plain\\_text\\_client](#)

[set\\_plain\\_text\\_auth\\_client](#)

[set\\_usk\\_client](#)

## set\_client

This Tcl command specifies the client that will be added to SPI Flash Memory. This command is added to the SPI Flash Memory configuration file that is given as the parameter to the `configure_spiflash` command.

```
set_client \
  -client_name {} \
  -client_type {FILE_SPI | FILE_SPI_GOLDEN | FILE_SPI_UPDATE | FILE_DATA_STORAGE_INTELHEX \
  -content_type {MEMORY_FILE | STATIC_FILL} \
  -content_file {} \
  -start_address {} \
  -client_size {} \
  -program {0|1}
```

## Arguments

`-client_name`

The name of the client. Maximum of 32 characters, letters or numbers or “-” or “\_”.

`-client_type`

The `-client_type` can be `FILE_SPI`, `FILE_SPI_GOLDEN`, `FILE_SPI_UPDATE` or `FILE_DATA_STORAGE_INTELHEX`.

`FILE_SPI` – SPI Bitstream

`FILE_SPI_GOLDEN` – Recovery/Golden SPI Bitstream

`FILE_SPI_UPDATE` – Auto Update SPI Bitstream; available only if Auto Update is enabled. See [set\\_auto\\_update\\_mode](#).

`FILE_DATA_STORAGE_INTELHEX` - Data Storage client

`-content_type`

The `-content_type` can be `MEMORY_FILE` or `STATIC_FILL`.

`MEMORY_FILE` – `content_file` parameter must be specified. See below.

`STATIC_FILL` – client memory will be filled with 1s; no content memory file

`-content_file`

Absolute or relative path to the content memory file.

`-start_address`

The client start address. Note that some space is reserved for the SPI Flash Memory directory. Note: This is a decimal value of bytes.

`-client_size`

Client's size in bytes. If a content file is specified, the size must be equal to or larger than the file size. Note: this is a decimal value.

```
-program {1}
```

Note: Only program | 1 is supported in this release.

## Examples

The following examples show the `set_client` Tcl command for SPI Flash.

### Absolute path

```
set_client \
  -client_name {golden} \
  -client_type {FILE_SPI_GOLDEN} \
  -content_type {MEMORY_FILE} \
  -content_file {E:\top_design_ver_1.spi} \
  -start_address {1024} \
  -client_size {9508587} \
  -program {1}

set_client \
  -client_name {ds} \
  -client_type {FILE_DATA_STORAGE_INTELHEX} \
  -content_type {MEMORY_FILE} \
  -content_file {E:\intel_hex.hex} \
  -start_address {9509611} \
  -client_size {128} \
  -program {1}
```

### Relative path

```
set_client \
  -client_name {golden} \
  -client_type {FILE_SPI_GOLDEN} \
  -content_type {MEMORY_FILE} \
  -content_file {.\..\..\top_design_ver_1.spi} \
  -start_address {1024} \
  -client_size {9508587} \
  -program {1}

set_client \
  -client_name {ds} \
  -client_type {FILE_DATA_STORAGE_INTELHEX} \
  -content_type {MEMORY_FILE} \
  -content_file {.\..\..\intel_hex.hex} \
  -start_address {9509611} \
  -client_size {128} \
  -program {1}
```

## set\_data\_storage\_client

This Tcl command is added to the .cfg file, which will then be given as the parameter to the `configure_uprom` command.

```
set_data_storage_client \
  -client_name {<name>} \
  -number_of_words {<number>} \
  -content_type {MEMORY_FILE | STATIC_FILL} \
  -memory_file_format {Microsemi-Binary} \
  -memory_file {<path>} \
  -base_address {<hexadecimal_string>} \
  -use_for_simulation {0} \
```

## Arguments

`-client_name`

The name of the client. Must start with an alphabetic letter. Underscores and numerals are allowed at all positions other than the first.

`-number_of_bytes`

The size of the client specified in number of words.

-content\_type

Source of data for the client. This can either be a memory file, or all zeros. Allowed values are MEMORY\_FILE or STATIC\_FILL.

MEMORY\_FILE – content memory file must be specified

STATIC\_FILL – client memory will be filled with 1s, no content memory file

-memory\_file\_format

Only 'Microsemi-Binary' is supported at this time.

-content\_file

Path of the memory file. This can be absolute, or relative to the project.

-base\_address

Hexadecimal address where the first byte of user data will be placed.

-use\_for\_simulation

Only value 0 is allowed.

## Example

```
set_data_storage_client \
  -client_name {client1_from_elsewhere_new_MMMMMM} \
  -number_of_words 57 \
  -use_for_simulation {0} \
  -content_type {MEMORY_FILE} \
  -memory_file_format {Microsemi-Binary} \
  -memory_file {D:/local_z_folder/work/memory_files/sar_86586_uprom.mem} \
  -base_address 0
```

## set\_manufacturer

This command specifies the manufacturer for the SPI Flash device.

```
set_manufacturer {MICRON | SPANSION | Macronix | Winbond }
```

The value for the set\_manufacturer command must be one of the following:

- MICRON
- SPANSION
- Macronix
- Winbond

See the following table for details about the supported SPI Flash devices.

| Mfg Part Number                                                   | Memory Capacity | Manufacturer | Sector Size |
|-------------------------------------------------------------------|-----------------|--------------|-------------|
| MT25QL01GBBB8ESF-0SIT                                             | 1 GB            | MICRON       | 4 KB        |
| S25FL512SAGMFI011                                                 | 512 MB          | SPANSION     | 256 KB      |
| MX66L51235FMI-10G                                                 | 512 MB          | Macronix     | 4 KB        |
| W25Q256FVFIG                                                      | 256 MB          | Winbond      | 4 KB        |
| Note: Microsemi currently supports only the devices listed above. |                 |              |             |

**Note:** This version of the programmer does not support SPI Flash security. Device security options such as "Hardware Write Protect" should be disabled for the External SPI Flash device.

## See Also

Microsemi Factory Access Policy

## set\_plain\_text\_auth\_client

This Tcl command is added to the sNVM .cfg file that is given as the parameter to the configure\_snmv command.

Plain-text Authenticated clients have 236 bytes available for user data in each page of sNVM.

```
set_plain_text_auth_client
  -client_name {<name>}
  -number_of_bytes <number>
  -content_type {MEMORY_FILE | STATIC_FILL}
  -content_file_format {Microsemi-Binary 8/16/32 bit}
  -content_file {<path>}
  -start_page <number>
  -use_for_simulation 0
  -reprogram 0 | 1
  -use_as_rom 0 | 1
```

## Arguments

-client\_name

The name of the client. Needs to start with an alphabetic letter. Underscores and numerals are allowed at all positions other than the first.

-number\_of\_bytes

The size of the client specified in bytes.

-content\_type

Source of data for the client. This can either be a memory file, or all zeros. Allowed values are MEMORY\_FILE or STATIC\_FILL

-content\_file\_format

Only 'Microsemi-Binary 8/16/32 bit' is supported at this time.

-content\_file

Path of the memory file. This can be absolute, or relative to the project.

-start\_page

The page number in sNVM where data for this client will be placed.

-use\_for\_simulation

Only value 0 is allowed.

-reprogram

Boolean field; specifies whether the client will be programmed into the final design or not. Possible values are 0 or 1.

-use\_as\_rom 0

Boolean field; specifies whether the client will allow only reads, or both read and writes. Possible values are 0 or 1.

## Example

```
set_plain_text_auth_client \
  -client_name {b} \
  -number_of_bytes 12 \
  -content_type {MEMORY_FILE} \
  -content_file_format {Microsemi-Binary 8/16/32 bit} \
  -content_file {D:/local_z_folder/work/memory_files/binary8x12.mem} \
  -start_page 2 \
  -use_for_simulation 0 \
```

```
-reprogram 1 \
-use_as_rom 0
```

### See Also

[set\\_plain\\_text\\_client](#)

[set\\_cipher\\_text\\_auth\\_client](#)

[set\\_usk\\_client](#)

## set\_plain\_text\_client

This Tcl command is added to the sNVM .cfg file that is given as the parameter to the configure\_snmv command. Plain-text Non-Authenticated clients have 252 bytes available for user data in each page of sNVM.

```
set_plain_text_client
  -client_name {<name>}
  -number_of_bytes <number>
  -content_type {MEMORY_FILE | STATIC_FILL}
  -content_file_format {Microsemi-Binary 8/16/32 bit}
  -content_file {<path>}
  -start_page <number>
  -use_for_simulation 0
  -reprogram 0 | 1
  -use_as_rom 0 | 1
```

### Arguments

-client\_name

The name of the client. Needs to start with an alphabetic letter. Underscores and numerals are allowed at all positions other than the first.

-number\_of\_bytes

The size of the client specified in bytes.

-content\_type

Source of data for the client. This can either be a memory file, or all zeros. Allowed values are MEMORY\_FILE or STATIC\_FILL

-content\_file\_format

Only 'Microsemi-Binary 8/16/32 bit' is supported at this time.

-content\_file

Path of the memory file. This can be absolute, or relative to the project.

-start\_page

The page number in sNVM where data for this client will be placed.

-use\_for\_simulation

Only value 0 is allowed.

-reprogram

Boolean field; specifies whether the client will be programmed into the final design or not. Possible values are 0 or 1.

-use\_as\_rom 0

Boolean field; specifies whether the client will allow only reads, or both read and writes. Possible values are 0 or 1.

### Example

```
set_plain_text_client \
  -client_name {a} \
  -number_of_bytes 12 \
  -content_type {MEMORY_FILE} \
```

```
-content_file_format {Microsemi-Binary 8/16/32 bit} \
-content_file {D:/local_z_folder/work/memory_files/binary8x12.mem} \
-start_page 1 \
-use_for_simulation 0 \
-reprogram 1 \
-use_as_rom 0
```

#### See Also

[set\\_plain\\_text\\_auth\\_client](#)

[set\\_cipher\\_text\\_auth\\_client](#)

[set\\_usk\\_client](#)

## set\_programming\_interface

This Tcl command sets the programming interface.

```
set_programming_interface -interface {JTAG | SPI_SLAVE}
```

### Arguments

```
set_programming_interface -interface {JTAG | SPI_SLAVE}
```

Specify the programming interface as JTAG or SPI\_SLAVE. The default is JTAG.

#### See Also

[Programming Connectivity and Interface](#)

## set\_usk\_client

This Tcl command is added to the sNVM .cfg file that is given as the parameter to the configure\_snvm command.

The USK client is required if sNVM has one or more clients of type 'Authenticated'.

```
set_cipher_text_auth_client
-start_page <number>
-key <Hexadecimal string of size 24>
-use_for_simulation 0 | 1
-reprogram 0 | 1
```

### Arguments

-start\_page

The page number in sNVM where data for this client will be placed.

-key

A string of 24 hexadecimal characters.

-use\_for\_simulation

Boolean field specifies whether the client will be used for simulation or not. Possible values are 0 or 1.

-reprogram

Boolean field; specifies whether the client will be programmed into the final design or not. Possible values are 0 or 1.

### Example

```
set_usk_client \
-start_page 4 \
-key {D8C8831F3A2F72EDC569503F} \
-use_for_simulation 0 \
-reprogram 1
```

### See Also

[set\\_plain\\_text\\_client](#)

[set\\_plain\\_text\\_auth\\_client](#)

[set\\_cipher\\_text\\_auth\\_client](#)

# FlashPro Express Tcl Commands

## close\_project

Closes the FlashPro or FlashPro Express project.

```
close_project
```

### Arguments

None

### Exceptions

None

### Example

```
close_project
```

## configure\_flashpro3\_prg

Changes FlashPro3 programmer settings.

```
configure_flashpro3_prg [-vpump {ON|OFF}] [-clk_mode {discrete_clk|free_running_clk}] [-force_freq {ON|OFF}] [-freq {freq}]
```

### Arguments

-vpump {ON|OFF}

Enables FlashPro programmer to drive VPUMP. Set to ON to drive VPUMP.

-clk\_mode {discrete\_clk|free\_running\_clk}

Specifies free running or discrete TCK.

-force\_freq {ON|OFF}

Forces the FlashPro software to use the TCK frequency specified by the software rather than the TCK frequency specified in the programmer file.

-freq {freq}

Specifies the TCK frequency in MHz.

### Exceptions

None

### Example

The following example sets the VPUMP option to ON, TCK to free running, and uses the TCK frequency specified in the programmer file (force\_freq is set to OFF):

```
configure_flashpro3_prg -vpump {ON} -clk_mode {free_running_clk} -force_freq {OFF} -freq {4}
```

The following example sets VPUMP to ON, TCK to discrete, forces the FlashPro software to use the TCK frequency specified in the software (-force\_freq is set to ON) at a frequency of 2 MHz.

```
configure_flashpro3_prg -vpump {ON} -clk_mode {discrete_clk} -force_freq {ON} -freq {2}
```

## configure\_flashpro4\_prg

Changes FlashPro4 programmer settings.

```
configure_flashpro4_prg [-vpump {ON|OFF}] [-clk_mode {discrete_clk|free_running_clk}] [-force_freq {ON|OFF}] [-freq {freq}]
```

### Arguments

-vpump {ON|OFF}

Enables FlashPro4 programmer to drive VPUMP. Set to ON to drive VPUMP.

-clk\_mode {discrete\_clk|free\_running\_clk}

Specifies free running or discrete TCK.

-force\_freq {ON|OFF}

Forces the FlashPro software to use the TCK frequency specified by the software rather than the TCK frequency specified in the programmer file.

-freq {freq}

Specifies the TCK frequency in MHz.

### Exceptions

None

### Example

The following example sets the VPUMP option to ON and uses a free running TCK at a frequency of 4 MHz (force\_freq is set to OFF).

```
configure_flashpro4_prg -vpump {ON} -clk_mode {free_running_clk} -force_freq {OFF} -freq {4}
```

The following example sets the VPUMP option to ON, uses a discrete TCK and sets force\_freq to ON at 2 MHz.

```
configure_flashpro4_prg -vpump {ON} -clk_mode {discrete_clk} -force_freq {ON} -freq {2}
```

## configure\_flashpro5\_prg

Tcl command; changes FlashPro5 programmer settings.

```
configure_flashpro5_prg [-vpump {ON|OFF}] [-clk_mode {free_running_clk}] [-programming_method {jtag | spi_slave}] [-force_freq {ON|OFF}] [-freq {freq}]
```

### Arguments

-vpump {ON|OFF}

Enables FlashPro5 programmer to drive VPUMP. Set to ON to drive VPUMP. Default is ON.

-clk\_mode {free\_running\_clk}

Specifies free running TCK. Default is free\_running\_clk.

-programming\_method {jtag | spi\_slave}

Specifies the programming method to use. Default is jtag.

**Note:** spi\_slave works only with SmartFusion2 and IGLOO2.

-force\_freq {ON|OFF}

Forces the FlashPro software to use the TCK frequency specified by the software rather than the TCK frequency specified in the programmer file. Default is OFF.

-freq {freq}

Specifies the TCK frequency in MHz. Default is 4.

## Exceptions

None

## Example

The following example sets the VPUMP option to ON and uses a free running TCK at a frequency of 4 MHz (force\_freq is set to OFF).

```
configure_flashpro5_prg -vpump {ON} -clk_mode {free_running_clk} -force_freq {OFF} -freq {4}
```

The following example sets the VPUMP option to ON, uses a free running TCK and sets force\_freq to ON at 2 MHz.

```
configure_flashpro5_prg -vpump {ON} -clk_mode {free_running_clk} -force_freq {ON} -freq {2}
```

## create\_job\_project

Tcl command; creates a Flashpro Express job using the programming job exported from Libero.

```
create_job_project -job_project_location location -job_file path -overwrite 0|1
```

## Arguments

-job\_project\_location *location*

Specifies the location for your FlashPro Express job project.

-job\_file *path*

Path to the Libero job file that is used as input to create the Flashpro Express job project.

-overwrite *0|1*

Set value to 1 to overwrite your existing job project. .

## Exceptions

None

## Example

The following example creates a job project named test.job in the \fpexpress directory. It does not overwrite the existing job project.

```
create_job_project \  
-job_project_location {D:\fpexpress} \  
-job_file {D:\test\designer\test\export\test.job} -overwrite 0\
```

## dump\_tcl\_support

Unloads the list of supported FlashPro or FlashPro Express Tcl commands.

```
dump_tcl_support -file {file}
```

## Arguments

-file {*file*}

## Exceptions

None

## Example

The following example dumps your Tcl commands into the file 'tcldump.tcl'

```
dump_tcl_support -file {tcldump.tcl}
```

## open\_project

Opens a FlashPro or FlashPro Express project.

```
open_project -project {project}
```

## Arguments

-project {*project*}

Specifies the location and name of the project you wish to open.

## Exceptions

None

## Example

Opens the 'FPPrj1.pro' project from the FPPProject1 directory

```
open_project -project {./FPPProject1/FPPrj1.pro}
```

## ping\_prg

Pings one or more programmers.

```
ping_prg (-name {name}) *
```

## Arguments

-name {*name*}

Specifies the programmer to be pinged. Repeat this argument for multiple programmers.

## Exceptions

None

## Example

The following example pings the programmers 'FP300085' and 'FP30086'.

```
ping_prg -name {FP300085} -name {FP300086}
```

## refresh\_prg\_list

Refreshes the programmer list. This is most often used to have FlashPro or FlashPro Express detect a programmer that you have just connected.

```
refresh_prg_list
```

## Arguments

None

## Exceptions

None

## Example

```
refresh_prg_list
```

## remove\_prg

Removes the programmer from the programmer list.

```
remove_prg (-name {name}) *
```

## Arguments

-name {*name*} \*

Specifies the programmer to be removed. You can repeat this argument for multiple programmers.

## Exceptions

None

## Example

The following example removes the programmer '03178' from the programmer list:

```
remove_prg (name {03178}) *
```

## run\_selected\_actions

Runs the selected action on the specified programmer and returns the exit code from the action. If no programmer name is specified, the action is run on all connected programmers. Only one exit code is returned, so return code cannot be used when action is run on more than one programmer. A programming file must be loaded.

```
run_selected_actions [(-name {name}) *]
```

## Arguments

-name {*name*}

Optional argument that specifies the programmer name. You can repeat this argument for multiple programmers.

## Exceptions

None

## Example

The following example runs the selected actionS on the programmers 'FP30085' and 'FP30086'.

```
run_selected_actions -name {FP300085} -name {FP300086}
```

Example using return code:

```
if {[catch {run_selected_actions} return_val]} {puts "Error running Action"} else {puts "exit code $return_val"}
```

Example returning exit code to the command line (returns exit 99 on script failure, otherwise returns exit code from selected action):

```
if {[catch {run_selected_actions} return_val]}{exit 99} else {exit $return_val}
```

## save\_log

Saves the log file.

```
save_log -file {file}
```

### Arguments

-file {file}

Specifies the log filename.

### Exceptions

None

### Example

The following example saves the log file with the name 'my\_logfile1.log':

```
save_log -file {my_logfile1.log}
```

## save\_project

Saves the FlashPro or FlashPro Express project.

```
save_project
```

### Arguments

None

### Exceptions

None

### Example

```
save_project
```

## scan\_chain\_prg

In single mode, this command runs scan chain on a programmer.

In chain mode, this command runs scan and check chain on a programmer if devices have been added in the grid.

```
scan_chain_prg [(-name {name})+]
```

### Arguments

-name {name}

Specifies the programmer name.

### Exceptions

None

### Example

The following example runs scan chain on a single programmer (single mode) named '21428':

```
scan_chain_prg -name {21428}
```

## self\_test\_prg

Runs Self-Test on a programmer.

```
self_test_prg (-name {name}) *
```

### Arguments

-name {*name*}

Specifies the programmer name. You can repeat this argument for multiple programmers.

### Exceptions

None

### Example

The following examples runs the self test on the programmer '30175':

```
self_test_prg (-name {30175}) *
```

## set\_prg\_name

Changes the user name of a programmer.

```
set_prg_name -name {name} -new_name {new_name}
```

### Arguments

-name {*name*}

Identifies the old programmer name.

-new\_name {*new\_name*}

Specifies the new programmer name.

### Exceptions

None

### Example

The following example changes the name of the programmer 'FP300086' to 'FP3Prg2':

```
set_prg_name -name {FP300086} -new_name {FP3Prg2}
```

## set\_programming\_action

Selects the action for a device. The device name parameter must be specified only in chain programming mode. A programming file must be loaded. The device must be a Microsemi device.

```
set_programming_action [-name {name}] -action {action}
```

### Arguments

-name {*name*}

Specifies the device name.

-action {*action*}

Specifies the action.

## Exceptions

Must be a Microsemi device

## Example

The following example sets the programming action in single programming mode:

```
set_programming_action -action {PROGRAM}
```

And in chain programming mode:

```
set_programming_action -name {MyDevice1} -action {ERASE}
```

## set\_programming\_file

Sets the programming file for a device. Either the *file* or the *no\_file* flag must be specified. A programming file must be loaded. The device must be a Microsemi device .

```
set_programming_file [-name {name}] [-file {file}] [-no_file { }]
```

## Arguments

-name {*name*}

Specifies the device name. This argument must be specified only in chain programming mode.

-file {*file*}

Specifies the programming file.

-no\_file

Specifies to unload the current programming file.

## Exceptions

Must be a Microsemi device.

## Examples

In single programming mode:

```
set_programming_file -file {e:/design/pdb/TopA3P250.pdb}
```

In chain programming mode:

```
set_programming_file -name {MyDevice2} -file {e:/design/pdb/TopA3P250.pdb}
```

```
set_programming_file -name {MyDevice1} -no_file
```

# SmartDebug Tcl Support

The following table lists the Tcl commands related to SmartDebug for PolarFire. Click the command to view more information.

Table 1 · SmartDebug Tcl Commands

| Command                                      | Action                                                                                           |
|----------------------------------------------|--------------------------------------------------------------------------------------------------|
| <b>Probe</b>                                 |                                                                                                  |
| <a href="#">add_probe_insertion_point</a>    | Adds probe points to be connected to user-specified I/Os for probe insertion flow.               |
| <a href="#">add_to_probe_group</a>           | Adds the specified probe points to the specified probe group                                     |
| <a href="#">create_probe_group</a>           | Creates a new probe group.                                                                       |
| <a href="#">delete_active_probe</a>          | Deletes either all or the selected active probes.                                                |
| <a href="#">load_active_probe_list</a>       | Loads the list of probes from the file.                                                          |
| <a href="#">move_to_probe_group</a>          | Moves the specified probe points to the specified probe group.                                   |
| <a href="#">program_probe_insertion</a>      | Runs the probe insertion flow on the selected nets.                                              |
| <a href="#">remove_probe_insertion_point</a> | Deletes an added probe from the probe insertion UI.                                              |
| <a href="#">set_live_probe</a>               | Set Live probe channels A and/or B to the specified probe point (or points).                     |
| <a href="#">select_active_probe</a>          | Manages the current selection of active probe points to be used by active probe READ operations. |
| <a href="#">read_active_probe</a>            | Reads active probe values from the device.                                                       |
| <a href="#">remove_from_probe_group</a>      | Move out the specified probe points from the group.                                              |
| <a href="#">save_active_probe_list</a>       | Saves the list of active probes to a file.                                                       |
| <a href="#">select_active_probe</a>          | Manages the current selection of active probe points to be used by active probe READ operations. |
| <a href="#">ungroup</a>                      | Disassociates the probes as group.                                                               |

| Command                                 | Action                                                                                           |
|-----------------------------------------|--------------------------------------------------------------------------------------------------|
| <b>Probe</b>                            |                                                                                                  |
| <a href="#">unset_live_probe</a>        | Discontinues the debug function and clears live probe channels.                                  |
| <a href="#">write_active_probe</a>      | Sets the target probe point on the device to the specified value.                                |
| <b>LSRAM</b>                            |                                                                                                  |
| <a href="#">read_lsram</a>              | Reads a specified block of large SRAM from the device.                                           |
| <a href="#">write_lsram</a>             | Writes a seven bit word into the specified large SRAM location.                                  |
| <b>uSRAM</b>                            |                                                                                                  |
| <a href="#">read_usram</a>              | Reads a uSRAM block from the device.                                                             |
| <a href="#">write_usram</a>             | Writes a seven bit word into the specified uSRAM location.                                       |
| <b>Transceiver</b>                      |                                                                                                  |
| <a href="#">loopback_mode</a>           | Applies loopback to a specified lane.                                                            |
| <a href="#">smartbert_test</a>          | Starts and stops a Smart BERT test and resets error counter.                                     |
| <a href="#">static_pattern_transmit</a> | Starts and stops a Static Pattern Transmit.                                                      |
| <a href="#">plot_eye</a>                | Plots eye and exports eye plots.                                                                 |
| <a href="#">xcvr_read_register</a>      | Reads SCB registers and their field values.                                                      |
| <a href="#">xcvr_write_register</a>     | Writes SCB registers and their field values.                                                     |
| <b>Additional Commands</b>              |                                                                                                  |
| <a href="#">event_counter</a>           | Runs on signals that are assigned to channel A on the live probe, and displays the total events. |
| <a href="#">export_smart_debug_data</a> | Exports debug data for the SmartDebug application.                                               |
| <a href="#">fhb_control</a>             | Provides FPGA Hardware Breakpoint (FHB) feature capability for SmartDebug.                       |
| <a href="#">frequency_monitor</a>       | Calculates the frequency of a signal that is assigned to live probe A.                           |
| <a href="#">get_programmer_info</a>     | Lists the IDs of all FlashPRO programmers connected to the machine.                              |
| <a href="#">uprom_read_memory</a>       | Reads uPROM memory block from the device.                                                        |

| Command                                       | Action                                                                                                                                                                              |
|-----------------------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <b>Probe</b>                                  |                                                                                                                                                                                     |
| <b>Standalone SmartDebug Commands</b>         |                                                                                                                                                                                     |
| <a href="#">construct_chain_automatically</a> | Automatically starts chain construction for the specified programmer.                                                                                                               |
| <a href="#">scan_chain_prg</a>                | In single mode, this Tcl command runs scan chain on a programmer. In chain mode, this Tcl command runs scan and check chain on a programmer if devices have been added in the grid. |
| <a href="#">enable_device</a>                 | Enables or disables a device in the chain.                                                                                                                                          |
| <a href="#">set_debug_programmer</a>          | Sets the debug programmer.                                                                                                                                                          |
| <a href="#">set_device_name</a>               | Sets the device name.                                                                                                                                                               |
| <a href="#">set_programming_file</a>          | Sets the programming file for a device.                                                                                                                                             |
| <a href="#">set_programming_action</a>        | Selects the action for a device.                                                                                                                                                    |
| <a href="#">run_selected_actions</a>          | Runs the selected action for a device.                                                                                                                                              |

## add\_probe\_insertion\_point

This Tcl command adds probe points to be connected to user-specified I/Os for probe insertion flow.

```
add_probe_insertion_point -net net_name -driver driver -pin package_pin_name -port port_name
```

### Arguments

-net *net\_name*

Name of the net used for probe insertion.

-driver *driver*

Driver of the net.

-pin *package\_pin\_name*

Package pin name (i.e. I/O to which the net will be routed during probe insertion).

-port *port\_name*

User-specified name for the probe insertion point.

### Example

```
add_probe_insertion_point -net {count_out_c[0]} -driver {Counter_8bit_0_count_out[0]:Q} -pin {H5} -port {Probe_Insert0}
```

## add\_to\_probe\_group

Tcl command; adds the specified probe points to the specified probe group.

```
add_to_probe_group -name probe_name -group group_name
```

### Arguments

-name *probe\_name*

Specifies one or more probes to add.

-group *group\_name*

Specifies name of the probe group.

### Example

```
add_to_probe_group -name out[5]:out[5]:Q \  
                  -name grp1.out[3]:out[3]:Q \  
                  -name out.out[1].out[1]:Q \  
                  -group my_new_grp
```

## construct\_chain\_automatically

This Tcl command automatically starts chain construction for the specified programmer.

```
construct_chain_automatically -name {programmer_name}
```

### Arguments

-name

Specify the device (programmer) name. This argument is mandatory.

### Example

*For a single programmer:*

```
construct_chain_automatically -name {21428}
```

#### See Also

[scan\\_chain\\_prq](#)

[enable\\_device](#)

[set\\_debug\\_programmer](#)

[set\\_device\\_name](#)

[set\\_programming\\_file](#)

[set\\_programming\\_action](#)

[run\\_selected\\_actions](#)

## create\_probe\_group

Tcl command; creates a new probe group.

```
create_probe_group -name group_name
```

### Arguments

-name *group\_name*

Specifies the name of the new probe group.

## Example

```
create_probe_group -name my_new_grp
```

## delete\_active\_probe

Tcl command; deletes either all or the selected active probes.

**Note:** You cannot delete an individual probe from the Probe Bus.

```
delete_active_probe -all | -name probe_name
```

## Arguments

-all

Deletes all active probe names.

-name *probe\_name*

Deletes the selected probe names.

## Example

```
delete -all      <- deletes all active probe names
delete -name out[5]:out[5]:Q \
        -name my_grp1.out[1]:out[1]:Q      #deletes the selected probe names
delete -name my_grp1 \
        -name my_bus      #deletes the group, bus and their members.
```

## enable\_device

This Tcl command enables or disables a device in the chain. When the device is disabled, it is bypassed. The device must be a Microsemi device.

```
enable_device -name {device_name} -enable {1 | 0}
```

## Arguments

-name

Specify the device name. This argument is mandatory.

-enable

Specify the enable device. This argument is mandatory.

## Example

```
enable_device -name {MPF300 (T_ES|TS_ES)} -enable 1
```

### See Also

[construct\\_chain\\_automatically](#)

[scan\\_chain\\_prq](#)

[set\\_debug\\_programmer](#)

[set\\_device\\_name](#)

[set\\_programming\\_file](#)

[set\\_programming\\_action](#)

[run\\_selected\\_actions](#)

## event\_counter

The `event_counter` Tcl command runs on signals that are assigned to channel A on the live probe, and displays the total events. It can be run before or after setting the live probe signal to channel A. The user specifies the duration to run the `event_counter` command.

```
event_counter -run -stop -after duration_in_seconds
```

### Arguments

`-run`

Run `event_counter`.

`-stop`

Stop `event_counter`.

`-after` *duration\_in\_seconds*

Duration to stop `event_counter`. Specified by the user. This argument is required when `-stop` is specified.

### Example

```
set_live_probe -probeA {count_out_c[0]:Counter_8bit_0_count_out[0]:Q} -probeB {}
event_counter -run
event_counter -stop -after 10
```

#### Output

```
Device ID Code = 2F8071CF
The 'read_id_code' command succeeded.
Live probes have been assigned.
Channel A: count_out_c[0]:Counter_8bit_0_count_out[0]:Q
Channel B: Not specified

The 'set_live_probe' command succeeded.

Event Counter = Activated
The 'event_counter' command succeeded.

Event Counter = Stopped
Total Events = 1603561
The 'event_counter' command succeeded.
The Execute Script command succeeded.
```

## export\_smart\_debug\_data

Tcl command; exports debug data for the SmartDebug application.

```
export_smart_debug_data [device_components] [bitstream_components] [-file_name {file}] [-
export_dir {dir}] [-force_rtg4_otp 0 | 1]
```

The command corresponds to the Export SmartDebug Data tool in Libero. The command creates a file with the extension “ddc” that contains data based on selected options. This file is used by SmartDebug (standalone application) to create a new SmartDebug project, or it can be imported into a device in SmartDebug (standalone application).

- If you do not specify any design components, all components available in the design will be included by default except the bitstream components.
- The `generate_bitstream` parameter is required if you want to generate bitstream file and include it in the exported file.
  - You must specify the bitstream components you want to include in the generated bitstream file or all available components will be included.

- o If you choose to include bitstream, and the design has custom security, the custom security bitstream component must be included.

## Arguments

### *device\_components*

The following device components can be selected. Specify "1" to include the component, and "0" if you do not want to include the component.

```
-probes <1|0>
-package_pins <1|0>
-memory_blocks <1|0>
-envm_data <1|0>
-security_data <1|0>
-chain <1|0>
-programmer_settings <1|0>
-ios_states <1|0>
```

### *bitstream\_components*

The following bitstream components can be selected. Specify "1" to include the component, and "0" if you do not want to include the component.

```
-generate_bitstream <1|0>
-bitstream_security <1|0>
-bitstream_fabric <1|0>
-bitstream_snvm <1|0>
-file_name file
```

Name of exported file with extension "ddc".

```
-export_dir dir
```

Location where DDC file will be exported. If omitted, design export folder will be used.

## Example

The following examples shows the `export_smart_debug_data` command with all parameters.

```
export_smart_debug_data \
-file_name "top" \
-export_dir "./" \
-probes 1 \
-package_pins 0 \
-memory_blocks 1 \
-security_data 1 \
-chain 1 \
-programmer_settings 1 \
-ios_states 1 \
-generate_bitstream 1 \
-bitstream_security 0 \
-bitstream_fabric 1 \
-bitstream_snvm 1
```

The following example shows the command with no parameters:

```
export_smart_debug_data
```

## fhb\_control

This Tcl command provides FPGA Hardware Breakpoint (FHB) feature capability for SmartDebug.

```
fhb_control
-halt -clock_domain clkDomName(s)/all
-run -clock_domain clkDomName(s)
-step number_of_steps -clock_domain clkDomName(s)
-reset -clock_domain clkDomName(s)
```

```
-arm_trigger -trigger_signal liveProbePoint -trigger_edge_select rising -delay value -
clock_domain clkDomName(s)
-disarm_trigger -clock_domain clkDomName(s)/all
-capture_waveform number_of_steps -vcd_file target_file_name
-clock_domain_status -clock_domain clkDomName(s)/all
```

## Arguments

**-halt**

Specifies to halt the clock.

**-clock\_domain** *clkDomName(s)/all*

Specifies clock domain names to halt. Can be single or multiple clock domains, halted in order specified by user.

**-run**

Specifies to run the clock.

**-clock\_domain** *clkDomName(s)*

Specifies clock domain names to run. Can be single or multiple clock domains, releasing the user clock based on order specified.

**-step** *number\_of\_steps*

Specifies to step the clock “number\_of\_steps” times. Minimum value is 1.

**-clock\_domain** *clkDomName(s)*

Specifies clock domain names to step. Can be single or multiple clock domains.

**-reset**

Specifies to reset FHB configuration for the specified clock domain.

**-clock\_domain** *clkDomName(s)*

Specifies clock domain names to reset. Can be single or multiple clock domains.

**-arm\_trigger**

Specifies to arm FHB configuration for the specified clock domain.

**-trigger\_signal** *liveProbePoint*

Set the trigger signal to arm the FHBs.

**-trigger\_edge\_select** *rising*

Specifies the trigger signal edge to arm the FHBs. FHBs will be armed on rising edge of trigger signal.

**-delay** *value*

**-clock\_domain** *clkDomName(s)*

Specifies clock domain names to be armed by the trigger signal. Can be single or multiple clock domains.

**-disarm\_trigger**

Specifies to disarm FHB configuration for the specified clock domain.

**-clock\_domain** *clkDomName(s)*

Specifies clock domain names to be reset by the trigger signal. Can be single or multiple clock domains.

**-capture\_waveform** *number\_of\_steps*

Specifies to capture waveform of all the added signals to active probes in the specified clock domain for number\_of\_steps.

**-vcd\_file** *target\_file\_name*

Target file to save the data and see the waveform.

**-clock\_domain\_status** *clkDomName(s)/all*

Specifies to read and display status of specified clock domain(s). Can be single or multiple clock domains.

## Examples

```
fhb_control -halt -clock_domain {"FCCC_0/GL0_INST " "FCCC_0/GL1_INST" }
fhb_control -run -clock_domain {"FCCC_0/GL0_INST " "FCCC_0/GL1_INST" }
```

```
fhb_control -step -clock_domain {"FCCC_0/GL0_INST" "FCCC_0/GL1_INST" }
fhb_control -reset -clock_domain {"FCCC_0/GL0_INST" "FCCC_0/GL1_INST" }
fhb_control -arm_trigger -trigger_signal {q_0_c[14]:count_1_q[14]:Q}
-trigger_edge_select {rising} - delay 0 - clock_domain {"FCCC_0/GL0_INST"}
fhb_control -disarm_trigger -trigger_signal {q_0_c[14]:count_1_q[14]:Q}
-trigger_edge_select {rising} - delay 0 - clock_domain {"FCCC_0/GL0_INST"}
fhb_control -capture_waveform {10} -vcd_file {D:/wvf_location/waveform.vcd}
fhb_control - clock_domain_status - clock_domain { "FCCC_0/GL0_INST" "FCCC_0/GL1_INST"
"FCCC_0/GL2_INST" }
```

## frequency\_monitor

The frequency\_monitor Tcl command calculates the frequency of a signal that is assigned to live probe A.

```
run_frequency_monitor -signal signal_name -time duration
```

### Arguments

-signal *signal\_name*

Specifies the signal name.

-time *duration*

Specifies the duration to run the command. The value can be 0.1, 1, 5, 8, or 10.

### Example

```
run_frequency_monitor -signal {count_out_c[7]:Counter_8bit_0_count_out[7]:Q} -time {5}
```

#### Output

Device ID Code = 2F8071CF

The 'read\_id\_code' command succeeded.

Frequency = 0.192716 MHz

The 'run\_frequency\_monitor' command succeeded.

The Execute Script command succeeded.

## get\_programmer\_info

This Tcl command lists the IDs of all FlashPRO programmers connected to the machine.

```
get_programmer_info
```

This command takes no arguments.

### Example

```
set a [get_programmer_info]
```

## load\_active\_probe\_list

Tcl command; loads the list of probes from the file.

```
load_active_probe_list -file file_path
```

### Arguments

-file *file\_path*

The input file location.

## Example

```
load_active_probe_list -file "./my_probes.txt"
```

## loopback\_mode

This Tcl command applies loopback to a specified lane.

```
loopback_mode -lane {Physical_Location} -apply -type {loopback_type}
```

## Arguments

-lane {Physical\_Location}

Specify the physical location of the lane.

-apply

Apply specified loopback to specified lane.

-type {loopback\_type}

Specify the loopback type to apply.

## Examples

```
loopback_mode -lane {Q3_LANE2} -apply -type {EQ-NearEnd}
loopback_mode -lane {Q3_LANE0} -apply -type {EQ-FarEnd}
loopback_mode -lane {Q0_LANE0} -apply -type {CDRFarEnd}
loopback_mode -lane {Q0_LANE1} -apply -type {NoLpbk}
loopback_mode -lane {Q1_LANE2} -apply -type {EQ-FarEnd}
loopback_mode -lane {Q1_LANE0} -apply -type {NoLpbk}
loopback_mode -lane {Q2_LANE2} -apply -type {EQ-NearEnd}
loopback_mode -lane {Q2_LANE3} -apply -type {CDRFarEnd}
```

## move\_to\_probe\_group

Tcl command; moves the specified probe points to the specified probe group.

**Note:** Probe points related to a bus cannot be moved to another group.

```
move_to_probe_group -name probe_name -group group_name
```

## Arguments

-name probe\_name

Specifies one or more probes to move.

-group group\_name

Specifies name of the probe group.

## Example

```
move_to_probe_group -name out[5]:out[5]:Q \
                    -name grp1.out[3]:out[3]:Q \
                    -group my_grp2
```

## optimize\_dfe

This Tcl command supports the Optimize DFE feature in SmartDebug.

```
optimize_dfe -dfe_algorithm <type of dfe algorithm> -lane <lane(s) configured in the design>
```

## Arguments

`-dfe_algorithm`

This command executes Dfe Algorithm with type of dfe algorithm and lanes as input. Algorithm selection has two options:

`software_based` – executes DfeSs.tcl script

`xcvr_based` –executes internal Dfe Auto Calibration.

This argument is mandatory.

`-lane`

List of lane(s) configured in the design.

This argument is mandatory.

## Examples

```
optimize_dfe -lane {"Q2_LANE0"} -dfe_algorithm {software_based}
optimize_dfe -lane {"Q2_LANE0"} -dfe_algorithm {xcvr_based}
optimize_dfe -lane {"Q2_LANE0" "Q0_LANE0"} -dfe_algorithm {xcvr_based}
```

## pcie\_config\_space

This Tcl command displays the value of the entered parameter in the SmartDebug log window and return the `register:field` value to the Tcl.

```
pcie_config_space -pcie_block_name {pcie_block_name} -param_name {param name}
```

## Arguments

`-pcie_block_name` {*pcie\_block\_name*}

Complete logical hierarchy of the PCIE block whose status is to be read from the device. This parameter is mandatory.

`-param_name` {*param name*}

Parameter name to read from the device. This parameter is mandatory.

## Example

```
pcie_config_space -pcie_block_name {sb_0/CM1_Subsystem/my_pcie_0} -param_name
{neg_max_payload}
```

*Output Display in SmartDebug window:* 512 bytes

*Return value to the tcl script:* 0x2

## pcie\_ltssm\_status

This Tcl command displays the current LTSSM state from the PLDA core in the SmartDebug log window and returns the `register:field` value to the Tcl.

```
pcie_ltssm_status -pcie_block_name {pcie_block_name}
```

## Arguments

`-pcie_block_name` {*pcie\_block\_name*}

Complete logical hierarchy of the PCIE block whose status is to be read from the device. This parameter is mandatory.

## Example

```
pcie_ltssm_status -pcie_block_name {sb_0/CM1_Subsystem/my_pcie_0}
```

*Output Display in SmartDebug window:* Configuration.Linkwidth.start

*Return value to the tcl script:* 0x2

## plot\_eye

This Tcl command is used to plot eye and export eye plots.

```
plot_eye -lane {lane_instance_name} -export_dir {location_path}
```

### Arguments

-lane

Specify the lane instance name.

-export\_dir

Specify the path to the location where the file is to be exported.

### Example

```
plot_eye -lane {Q2_LANE0} - export_dir {E:\designs\G5\SERDES\ export.txt}
```

## program\_probe\_insertion

This Tcl command runs the probe insertion flow on the selected nets.

```
program_probe_insertion
```

This command takes no arguments.

## read\_active\_probe

Tcl command; reads active probe values from the device. The target probe points are selected by the [select\\_active\\_probe](#) command.

```
read_active_probe [-deviceName device_name] [-name probe_name] [-group_name bus_name|group_name] [-value_type b|h] [-file file_path]
```

### Arguments

-deviceName device\_name

Parameter is optional if only one device is available in the current configuration.

-name probe\_name

Instead of all probes, read only the probes specified. The probe name should be prefixed with bus or group name if the probe is in the bus or group.

-group\_name bus\_name | group\_name

Instead of all probes, reads only the specified buses or groups specified here.

-value\_type b | h

Optional parameter, used when the read value is stored into a variable as a string.

b = binary

h = hex

-file file\_path

Optional. If specified, redirects output with probe point values read from the device to the specified file.

**Note:** When the user tries to read at least one signal from the bus/group, the complete bus or group is read. The user is presented with the latest value for all the signals in the bus/group.

## Example

```
read_active_probe -group_name {bus1}
read_active_probe -group_name {group1}
```

To save into variable:

```
set a [read_active_probe -group_name {bus_name} -value_type h]      #save read data in hex string
```

If read values are stored into a variable without specifying value\_type parameter, it saves values as a binary string by default.

### Example

```
set a [read_active_probe ]      #sets variable a as binary string of read values after read_active_probe
command.
```

## read\_lsram

Tcl command; reads a specified block of large SRAM from the device.

### Physical block

```
read_lsram -name block_name -fileName file_name
```

### Arguments

-name *block\_name*

Specifies the name for the target block.

-fileName *file\_name*

Optional; specifies the output file name for the data read from the device.

### Exceptions

- Array must be programmed and active
- Security locks may disable this function

### Example

Reads the LSRAM Block Fabric\_Logic\_0/U2/F\_0\_F0\_U1/ramtmp\_ramtmp\_0\_0/INST\_RAM1K20\_IP from the PolarFire device and writes it to the file output.txt.

```
read_lsram -name {Fabric_Logic_0/U2/F_0_F0_U1/ramtmp_ramtmp_0_0/INST_RAM1K20_IP} -
fileName {output.txt}
```

### Logical block

```
read_lsram -logicalBlockName block_name -port port_name
```

### Arguments

-logicalBlockName *block\_name*

Specifies the name for the user defined memory block.

-port *port\_name*

Specifies the port for the memory block selected. Can be either Port A or Port B.

### Example

```
read_lsram -logicalBlockName {Fabric_Logic_0/U2/F_0_F0_U1} -port {Port A}
```

## read\_usram

Tcl command; reads a uSRAM block from the device.

### Physical block

```
read_usram [-name block_name] -fileName file_name
```

### Arguments

-name *block\_name*

Specifies the name for the target block.

-fileName *file\_name*

Optional; specifies the output file name for the data read from the device.

### Exceptions

- Array must be programmed and active
- Security locks may disable this function

### Example

Reads the uSRAM Block Fabric\_Logic\_0/U3/F\_0\_F0\_U1/ramtmp\_ramtmp\_0\_0/INST\_RAM64x12\_IP from the PolarFire device and writes it to the file sram\_block\_output.txt.

```
read_usram -name {Fabric_Logic_0/U3/F_0_F0_U1/ramtmp_ramtmp_0_0/INST_RAM64x12_IP} -  
fileName {output.txt}
```

### Logical block

```
read_usram -logicalBlockName block_name -port port_name
```

### Arguments

-logicalBlockName *block\_name*

Specifies the name of the user defined memory block.

-port *port\_name*

Specifies the port of the memory block selected. Can be either Port A or Port B.

### Example

```
read_usram -logicalBlockName {Fabric_Logic_0/U3/F_0_F0_U1} -port {Port A}
```

## remove\_from\_probe\_group

Tcl command; removes the specified probe points from the group. That is, the removed probe points won't be associated with any probe group.

**Note:** Probes cannot be removed from the bus.

```
remove_from_probe_group -name probe_name
```

### Arguments

-name *probe\_name*

Specifies one or more probe points to remove from the probe group.

## Example

The following command removes two probes from my\_grp2.

```
Move_out_of_probe_group -name my_grp2.out[3]:out[3]:Q \  
                        -name my_grp2.out[3]:out[3]:Q
```

## remove\_probe\_insertion\_point

This Tcl command deletes an added probe from the probe insertion UI.

```
remove_probe_insertion_point -net net_name -driver driver
```

## Arguments

-net *net\_name*

Name of the existing net which is added using the add\_probe\_insertion\_point command.

-driver *driver*

Driver of the net.

## Example

```
remove_probe_insertion_point -net {count_out_c[0]} -driver  
{Counter_8bit_0_count_out[0]:Q}
```

## run\_selected\_actions

This Tcl command is used to run the selected action for a device.

```
run_selected_actions
```

This command takes no arguments.

## Example

```
set_programming_action -name {MPF300(T_ES|TS_ES)} -action {DEVICE_INFO}  
set_programming_action -name {M2S/M2GL090(T|TS|TV)} -action {ERASE}
```

### See Also

[construct\\_chain\\_automatically](#)

[scan\\_chain\\_prq](#)

[enable\\_device](#)

[set\\_debug\\_programmer](#)

[set\\_device\\_name](#)

[set\\_programming\\_file](#)

[set\\_programming\\_action](#)

## save\_active\_probe\_list

Tcl command; saves the list of active probes to a file.

```
save_active_probe_list -file file_path
```

## Arguments

-file *file\_path*

The output file location.

## Example

```
save_active_probe_list -file "./my_probes.txt"
```

## scan\_chain\_prg

In single mode, this Tcl command runs scan chain on a programmer. In chain mode, this Tcl command runs scan and check chain on a programmer if devices have been added in the grid.

```
scan_chain_prg -name {programmer_name}
```

## Arguments

-name

Specify the device (programmer) name. This argument is mandatory.

## Example

```
scan_chain_prg -name {21428}
```

### See Also

[construct\\_chain\\_automatically](#)

[enable\\_device](#)

[set\\_debug\\_programmer](#)

[set\\_device\\_name.htm](#)

[set\\_programming\\_file](#)

[set\\_programming\\_action](#)

[run\\_selected\\_actions](#)

## select\_active\_probe

Tcl command; manages the current selection of active probe points to be used by active probe READ operations. This command extends or replaces your current selection with the probe points found using the search pattern.

```
select_active_probe [-deviceName device_name] [-name probe_name_pattern] [-reset true|false]
```

## Arguments

-deviceName *device\_name*

Parameter is optional if only one device is available in the current configuration..

-name *probe\_name\_pattern*

Specifies the name of the probe. Optionally, search pattern string can specify one or multiple probe points. The pattern search characters "\*" and "?" also can be specified to filter out the probe names.

-reset *true | false*

Optional parameter; resets all previously selected probe points. If name is not specified, empties out current selection.

## Example

The following command selects three probes. In the below example, "grp1" is a group and "out" is a bus..

```
Select_active_probe -name out[5]:out[5]:Q
Select_active_probe -name out.out[1]:out[1]:Q \
    -name out.out[3]:out[3]:Q \
    -name out.out[5]:out[5]:Q
```

## set\_live\_probe

Tcl command; set\_live\_probe channels A and/or B to the specified probe point(s). At least one probe point must be specified. Only exact probe name is allowed (i.e. no search pattern that may return multiple points).

```
set_live_probe [-deviceName device_name] [-probeA probe_name] [-probeB probe_name]
```

### Arguments

-deviceName *device\_name*

Parameter is optional if only one device is available in the current configuration or set for debug (see SmartDebug user guide for details).

-probeA *probe\_name*

Specifies target probe point for the probe channel A.

-probeB *probe\_name*

Specifies target probe point for the probe channel B.

### Exceptions

- The array must be programmed and active
- Active probe read or write operation will affect current settings of Live probe since they use same probe circuitry inside the device
- Setting only one Live probe channel affects the other one, so if both channels need to be set, they must be set from the same call to set\_live\_probe
- Security locks may disable this function
- In order to be available for Live probe, ProbeA and ProbeB I/O's must be reserved for Live probe respectively

### Example

Sets the Live probe channel A to the probe point A12 on device MPF300TS\_ES.

```
set_live_probe [-deviceName MPF300TS_ES] [-probeA A12]
```

## set\_debug\_programmer

This Tcl command is used to set the debug programmer.

```
set_debug_programmer -name {programmer_name}
```

### Arguments

-name

Specify the programmer. This argument is mandatory.

### Example

```
set_debug_programmer -name {S201YQST1V}
```

#### See Also

[construct\\_chain\\_automatically](#)

[scan\\_chain\\_prq](#)

[enable\\_device](#)

[set\\_device\\_name](#)

[set\\_programming\\_file](#)

[set\\_programming\\_action](#)

[run\\_selected\\_actions](#)

## set\_programming\_action

This Tcl command is used to select the action for a device.

```
set_programming_action [-name {device_name}] -action {procedure_action}
```

### Arguments

-name

Specify the device name. This argument is mandatory.

-action

Specify the programming action. This argument is mandatory.

### Example

```
set_programming_action -name {MPF300(T_ES|TS_ES)} -action {DEVICE_INFO}  
set_programming_action -name {M2S/M2GL090(T|TS|TV)} -action {ERASE}
```

#### See Also

[construct\\_chain\\_automatically](#)[scan\\_chain\\_prq](#)[enable\\_device](#)[set\\_debug\\_programmer](#)[set\\_device\\_name](#)[set\\_programming\\_file](#)[run\\_selected\\_actions](#)

## set\_programming\_file

This Tcl command is used to set the programming file for a device. Either the file or the no\_file flag must be specified. A programming file must be loaded. The device must be a Microsemi device.

```
set_programming_file -name {device_name} -file {stapl_file_name_with_path}
```

### Arguments

-name

Specify the device name. This argument is mandatory.

-file

Specify the *file* path. This argument is mandatory.

### Example

```
set_programming_file -name {MPF300(T_ES|TS_ES)} -file  
{D:/export/CM1_PCIE_TOP_default_uic_l2_200_0_12.stp}
```

#### See Also

[construct\\_chain\\_automatically](#)[scan\\_chain\\_prq](#)[enable\\_device](#)[set\\_debug\\_programmer](#)

[set\\_device\\_name](#)  
[set\\_programming\\_action](#)  
[run\\_selected\\_actions](#)

## smartbert\_test

This Tcl command is used for the following:

- Start a Smart BERT test
- Stop a Smart BERT test
- Reset error count

### smartbert\_test -start

This Tcl command starts a Smart BERT test with a specified pattern on a specified lane.

```
smartbert_test -start -pattern {pattern_type} -lane {Physical_Location}
```

### Arguments

-start  
 Start the Smart BERT test.  
 pattern {pattern\_type}  
 Specify the pattern type of the Smart BERT test.  
 -lane {Physical\_Location}  
 Specify the physical location of the lane.  
 -EQ-NearEndLoopback  
 Enable EQ-Near End Loopback on specified lane.

### Examples

```

smartbert_test -start -pattern {prbs9} -lane {Q0_LANE3}
smartbert_test -start -pattern {prbs23} -lane {Q3_LANE2}
smartbert_test -start -pattern {prbs7} -lane {Q3_LANE1}
smartbert_test -start -pattern {prbs31} -lane {Q1_LANE2} -EQ-NearEndLoopback
smartbert_test -start -pattern {prbs9} -lane {Q2_LANE2} -EQ-NearEndLoopback
smartbert_test -start -pattern {prbs15} -lane {Q2_LANE3} -EQ-NearEndLoopback
  
```

### smartbert\_test -stop

This Tcl command stops a Smart BERT test on a specified lane.

```
smartbert_test -stop -lane {Physical_Location}
```

### Arguments

-stop  
 Stop the smart BERT test.  
 -lane {Physical\_Location}  
 Specify the physical location of the lane.

### Examples

```

smartbert_test -stop -lane {Q0_LANE0}
smartbert_test -stop -lane {Q0_LANE3}
smartbert_test -stop -lane {Q3_LANE2}
  
```

```
smartbert_test -stop -lane {Q3_LANE1}
smartbert_test -stop -lane {Q1_LANE2}
smartbert_test -stop -lane {Q2_LANE2}
smartbert_test -stop -lane {Q2_LANE3}
```

## smartbert\_test -reset\_counter

This Tcl command resets a lane error counter.

```
smartbert_test -reset_counter -lane {Physical_Location}
```

## Arguments

-reset\_counter

Reset lane error counter on hardware and cumulative error count on the UI.

-lane {Physical\_Location}

Specify the physical location of the lane.

## Examples

```
smartbert_test -reset_counter -lane {Q0_LANE0}
smartbert_test -reset_counter -lane {Q3_LANE2}
smartbert_test -reset_counter -lane {Q2_LANE3}
smartbert_test -reset_counter -lane {Q2_LANE2}
smartbert_test -reset_counter -lane {Q1_LANE2}
smartbert_test -reset_counter -lane {Q3_LANE1}
```

## static\_pattern\_transmit

This Tcl command starts and stops a Static Pattern Transmit.

### static\_pattern\_transmit -start

```
static_pattern_transmit -start -lane {Physical_Location} -pattern {pattern_type} -value {user_pattern_value}
```

## Parameters

-start

Start the Static Pattern Transmit.

-lane {Physical\_Location}

Specify physical location of lane.

-pattern {pattern\_type}

Specify pattern\_type of Static Pattern Transmit.

-value {user\_pattern\_value}

Specify user\_pattern\_value in hex if pattern\_type selected is custom.

## Examples

```
static_pattern_transmit -start -lane {Q0_LANE0} -pattern {fixed}
static_pattern_transmit -start -lane {Q0_LANE2} -pattern {maxrunlength} -value {}
static_pattern_transmit -start -lane {Q3_LANE2} -pattern {custom} -value {df}
static_pattern_transmit -start -lane {Q3_LANE0} -pattern {fixed} -value {}
static_pattern_transmit -start -lane {Q1_LANE1} -pattern {custom} -value {4578}
static_pattern_transmit -start -lane {Q1_LANE2} -pattern {fixed} -value {}
```

```
static_pattern_transmit -start -lane {Q2_LANE2} -pattern {maxrunlength} -value {}
static_pattern_transmit -start -lane {Q2_LANE1} -pattern {custom} -value {abcdef56}
```

## static\_pattern\_transmit -stop

```
static_pattern_transmit -stop -lane {Physical_Location}
```

### Parameters

-stop  
Stop the Static Pattern Transmit.

-lane {Physical\_Location}  
Specify physical location of lane.

### Examples

```
static_pattern_transmit -stop -lane {Q0_LANE0}
static_pattern_transmit -stop -lane {Q0_LANE2}
static_pattern_transmit -stop -lane {Q3_LANE2}
static_pattern_transmit -stop -lane {Q3_LANE0}
static_pattern_transmit -stop -lane {Q1_LANE1}
static_pattern_transmit -stop -lane {Q1_LANE2}
static_pattern_transmit -stop -lane {Q2_LANE2}
static_pattern_transmit -stop -lane {Q2_LANE1}
```

## ungroup

Tcl command; disassociates the probes as a group.

```
nngroup -name group_name
```

### Arguments

-name group\_name  
Name of the group.

### Example

```
ungroup -name my_grp4
```

## unset\_live\_probe

Tcl command; discontinues the debug function and clears live probe A, live probe B, or both probes (Channel A/Channel B). An all zeros value is shown in the oscilloscope.

```
unset_live_probe -probeA 1 -probeB 1 [-deviceName device_name]
```

### Arguments

-probeA  
Live probe Channel A.

-probeB  
Live probe Channel B.

-deviceName device\_name

Parameter is optional if only one device is available in the current configuration or set for debug (see the [SmartDebug User Guide for Libero](#) or the [SmartDebug User Guide for PolarFire](#) for details).

## Exceptions

- The array must be programmed and active.
- Active probe read or write operation affects current of Live Probe settings, because they use the same probe circuitry inside the device.
- Security locks may disable this function.

## Example

The following example unsets live probe Channel A from the device MPF300TS\_ES.

```
unset_live_probe -probeA 1[-deviceName MPF300TS_ES]
```

## uprom\_read\_memory

This Tcl command reads a uPROM memory block from the device.

```
read_uprom_memory -startAddress {hex_value} -words {integer_value}
```

## Arguments

-startAddress *hex\_value*

Specifies the start address of the uPROM memory block.

-words *integer\_value*

Specifies the number of 9-bit words.

## Example

```
read_uprom_memory -startAddress {0xA} -words {100}
```

## write\_active\_probe

Tcl command; sets the target probe point on the device to the specified value. The target probe point name must be specified.

```
write_active_probe [-deviceName device_name] -name probe_name -value true|false  
-group_name group_bus_name -group_value "hex-value" | "binary-value"
```

## Arguments

-deviceName *device\_name*

Parameter is optional if only one device is available in the current configuration.

-name *probe\_name*

Specifies the name for the target probe point. Cannot be a search pattern.

-value *true | false hex-value | binary-value*

Specifies values to be written.

True = High

False = Low

-group\_name *group\_bus\_name*

Specify the group or bus name to write to complete group or bus.

-group\_value *"hex-value" | "binary-value"*

Specify the value for the complete group or bus.

Hex-value format : “ <size>’h<value>”

Binary-value format: “ <size>’b<value>”

## Example

```
write_active_probe -name out[5]:out[5]:Q -value true <-- write to a single probe
write_active_probe -name grp1.out[3]:out[3]:Q -value low <-- write to a probe in the group
write_active_probe -group_name grp1 -group_value "8'hF0" <-- write the value to complete group
write_active_probe -group_name out -group_value "8'b11110000" \
    -name out[2]:out[2]:Q -value true <-- write multiple probes at the same time.
```

## write\_lsram

Tcl command; writes a word into the specified large SRAM location.

## Physical block

```
write_lsram -name block_name -offset offset_value -value integer_value
```

## Arguments

-name *block\_name*

Specifies the name for the target block.

-offset *offset\_value*

Offset (address) of the target word within the memory block.

-value *integer\_value*

Word to be written to the target location. Depending on the configuration of memory blocks, the width can be 1, 2, 5, 10, or 20 bits.

## Exceptions

- Array must be programmed and active
- The maximum value that can be written depends on the configuration of memory blocks
- Security locks may disable this function

## Example

```
write_lsram -name {Fabric_Logic_0/U2/F_0_F0_U1/ramtmp_ramtmp_0_0/INST_RAM1K20_IP} -offset
0 -value 291
```

## Logical block

```
write_lsram -logicalBlockName block_name -port port_name -offset 1 offset_value -logicalValue
hexadecimal_value
```

## Arguments

-logicalBlockName *block\_name*

Specifies the name of the user defined memory block.

-port *port\_name*

Specifies the port of the memory block selected. Can be either Port A or Port B.

-offset *offset\_value*

Offset (address) of the target word within the memory block.

`-logicalValue hexadecimal_value`

Specifies the hexadecimal value to be written to the memory block. Size of the value is equal to the width of the output port selected.

## Example

```
write_lsram -logicalBlockName {Fabric_Logic_0/U2/F_0_F0_U1} -port {Port A} -offset 1 -
logicalValue {00FFF}
```

## write\_usram

Tcl command; writes a 12-bit word into the specified uSRAM location.

## Physical block

```
write_usram -name block_name -offset offset_value -value integer_value
```

## Arguments

`-name block_name`

Specifies the name for the target block.

`-offset offset_value`

Offset (address) of the target word within the memory block.

`-value integer_value`

12-bit value to be written.

## Exceptions

- Array must be programmed and active
- The maximum value that can be written is 0x1FF
- Security locks may disable this function

## Example

Writes a value of 0x291 to the device PolarFire in the Fabric\_Logic\_0/U3/F\_0\_F0\_U1/ramtmp\_ramtmp\_0\_0/INST\_RAM64x12\_IP with an offset of 0.

```
write_lsram -name {Fabric_Logic_0/U3/F_0_F0_U1/ramtmp_ramtmp_0_0/INST_RAM64x12_IP} -
offset 0 -value 291
```

## Logical block

```
write_usram -logicalBlockName block_name -port port_name -offset offset_value -logicalValue
hexadecimal_value
```

## Arguments

`-logicalBlockName block_name`

Specifies the name of the user defined memory block.

`-port port_name`

Specifies the port of the memory block selected. Can be either Port A or Port B.

`-offset offset_value`

Offset (address) of the target word within the memory block.

`-logicalValue hexadecimal_value`

Specifies the hexadecimal value to be written to the memory block. Size of the value is equal to the width of the output port selected.

## Example

```
write_usram -logicalBlockName {Fabric_Logic_0/U3/F_0_F0_U1} -port {Port A} -offset 1 -
logicalValue {00FFF}
```

## xcvr\_read\_register

This Tcl command reads SCB registers and their field values. Read value is in hex format. This command is used in SmartDebug Signal Integrity.

```
xcvr_read_register -inst_name <inst_name> -reg_name [<reg_name> | <reg_name:field_name>]
```

## Arguments

-inst\_name <inst\_name>

Specify the lane instance name used in the design.

-reg\_name <reg\_name> or <reg\_name:field\_name>

Specify the <reg\_name> for register name or <reg\_name>:<field\_name> for the register's field.

## Examples

### Reading pcslane's 32-bit register LNTV\_R0:

```
xcvr_read_register -inst_name {CM1_PCIE_SS_0/PF_PCIE_0/LANE1} -reg_name {LNTV_R0}
```

#### Output:

Register Name: LNTV\_R0 value: 0x12

The 'xcvr\_write\_register' command succeeded.

### Reading Register LNTV\_R0 field LNTV\_RX\_GEAR (i.e. 0th bit of 32-bit register):

```
xcvr_read_register -inst_name {CM1_PCIE_SS_0/PF_PCIE_0/LANE1} -reg_name
{LNTV_R0:LNTV_RX_GEAR}
```

#### Output:

Register Name: LNTV\_R0:LNTV\_RX\_GEAR, Value: 0x0

The 'xcvr\_read\_register' command succeeded.

## Exception:

## SOFT\_RESET Register

The SOFT\_RESET register is an SCB read/write register containing information such as block ID and Map IDs. It is also used to provide a pulsed reset to the SCB registers. It is a group-specific register.

The SOFT\_RESET register is available with the four groups (pma\_lane, pma\_cmnn, pcslane, and pcscmn). To read or write this register or its field value, "group name" must be added before "SOFT\_RESET".

-reg\_name <group name>\_<SOFT\_RESET> for register name

or

[<group name>\_<SOFT\_RESET>:field\_name] for register field name

where <group name> can be PCS, PCSCMN, PMA, or PMA\_CMN.

## Examples

### Reading all four groups' SOFT\_RESET register and its field BLOCKID

#### ***Reading the PCS SOFT\_RESET register and its field BLOCKID (i.e. 16th to 31st bit):***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PCS_SOFT_RESET}
```

##### **Output:**

Register Name: PCS\_SOFT\_RESET, Value: 0x300100

The 'xcvr\_read\_register' command succeeded.

#### ***Reading field BLOCKID:***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PCS_SOFT_RESET:BLOCKID}
```

##### **Output:**

Register Name: PCS\_SOFT\_RESET:BLOCKID, Value: 0x30

The 'xcvr\_read\_register' command succeeded.

#### ***Reading PCSCMN's SOFT\_RESET register and its field BLOCKID (i.e. 16th to 31st bit):***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PCSCMN_SOFT_RESET}
```

Register Name: PCSCMN\_SOFT\_RESET, Value: 0x340100

The 'xcvr\_read\_register' command succeeded.

#### ***Reading field BLOCKID:***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PCSCMN_SOFT_RESET:BLOCKID}
```

##### **Output:**

Register Name: PCSCMN\_SOFT\_RESET:BLOCKID, Value: 0x34

The 'xcvr\_read\_register' command succeeded.

#### ***Reading PMA's SOFT\_RESET register and its field BLOCKID (i.e. 16th to 31st bit):***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PMA_SOFT_RESET}
```

##### **Output:**

Register Name: PMA\_SOFT\_RESET, Value: 0x1300100

The 'xcvr\_read\_register' command succeeded.

#### ***Reading field BLOCKID:***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PMA_SOFT_RESET:BLOCKID}
```

##### **Output:**

Register Name: PMA\_SOFT\_RESET:BLOCKID, Value: 0x130

The 'xcvr\_read\_register' command succeeded.

#### ***Reading PMA\_CMN's SOFT\_RESET register and it's field BLOCKID (i.e. 16th to 31st bit):***

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PMA_CMN_SOFT_RESET}
```

##### **Output:**

Register Name: PMA\_CMN\_SOFT\_RESET, Value: 0x1340100

The 'xcvr\_read\_register' command succeeded.

**Reading field BLOCKID:**

```
xcvr_read_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name
{PMA_CMN_SOFT_RESET:BLOCKID}
```

**Output:**

Register Name: PMA\_CMN\_SOFT\_RESET:BLOCKID, Value: 0x134  
 The 'xcvr\_read\_register' command succeeded.

**See Also**

[xcvr\\_write\\_register](#)

## xcvr\_write\_register

This Tcl command writes SCB registers and their field values. Write value is in hex format. This command is used in SmartDebug Signal Integrity.

```
xcvr_write_register -inst_name <inst_name> -reg_name [<reg_name> | <reg_name:field_name>] -
value {write_value}
```

### Arguments

-inst\_name <inst\_name>

Specify the lane instance name used in the design.

-reg\_name <reg\_name> or <reg\_name:field\_name>

Specify the <reg\_name> for register name or <reg\_name>:<field\_name> for the register's field.

-value <write\_value>

Specify the value in hex format.

### Examples

#### Writing pscmn's 32-bit register GSSCLK\_CTRL

```
xcvr_write_register -inst_name {CM1_PCIE_SS_0/PF_PCIE_0/LANE1} -reg_name {GSSCLK_CTRL} -
value 0xffffffff
```

**Output:**

Register Name: GSSCLK\_CTRL value: 0xffffffff  
 The 'xcvr\_write\_register' command succeeded.

#### Writing Register GSSCLK\_CTRL field MCLK\_GSSCLK\_2\_SEL i.e. 16th to 20th bits (5 bits) of 32-bit register

```
xcvr_write_register -inst_name {CM1_PCIE_SS_0/PF_PCIE_0/LANE1} \
-reg_name {GSSCLK_CTRL:MCLK_GSSCLK_2_SEL} -value 0x6
```

**Output:**

Register Name: GSSCLK\_CTRL:MCLK\_GSSCLK\_2\_SEL value: 0x6  
 The 'xcvr\_write\_register' command succeeded.

### Exception:

#### SOFT\_RESET Register

The SOFT\_RESET register is an SCB read/write register containing information such as block ID and Map IDs. It is also used to provide a pulsed reset to the SCB registers. It is a group-specific register.

The SOFT\_RESET register is available with the four groups (pma\_lane, pma\_cm, pmslane, and pmscmn). To read or write this register or its field value, “group name” must be added before “SOFT\_RESET”.

-reg\_name <group name>\_<SOFT\_RESET> for register name

or

[<group name>\_<SOFT\_RESET>:field\_name] for register field name

where <group name> can be PCS, PCSCMN, PMA, or PMA\_CMN

## Examples

### Writing all four groups' SOFT\_RESET register and its field PERIPH

#### **Writing to the PCS SOFT\_RESET register (32-bits) and its field PERIPH (i.e. 8th bit):**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PCS_SOFT_RESET}
-value 0xffffffff
```

##### **Output:**

Register Name: PCS\_SOFT\_RESET value: 0xffffffff

The 'xcvr\_write\_register' command succeeded.

#### **Writing to field PERIPH:**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name
{PCS_SOFT_RESET:PERIPH} -value 0x1
```

##### **Output:**

Register Name: PCS\_SOFT\_RESET:PERIPH value: 0x1

The 'xcvr\_write\_register' command succeeded.

#### **Writing to PCSCMN's SOFT\_RESET register (32-bits) its field PERIPH (i.e. 8th bit):**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name
{PCSCMN_SOFT_RESET} -value 0xffffffff
```

##### **Output:**

Register Name: PCSCMN\_SOFT\_RESET value: 0xffffffff

The 'xcvr\_write\_register' command succeeded.

#### **Writing to field PERIPH:**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name
{PCSCMN_SOFT_RESET:PERIPH} -value 0x1
```

##### **Output:**

Register Name: PCSCMN\_SOFT\_RESET:PERIPH value: 0x1

The 'xcvr\_write\_register' command succeeded.

#### **Writing to PMA's SOFT\_RESET register its field PERIPH (i.e. 8th bit):**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name {PMA_SOFT_RESET}
-value 0xffffffff
```

##### **Output:**

Register Name: PMA\_SOFT\_RESET value: 0xffffffff

The 'xcvr\_write\_register' command succeeded.

#### **Writing to field PERIPH:**

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name
{PMA_SOFT_RESET:PERIPH} -value 0x1
```

##### **Output:**

Register Name: PMA\_SOFT\_RESET:PERIPH value: 0x1

The 'xcvr\_write\_register' command succeeded.

***Writing to PMA\_CMN's SOFT\_RESET register its field PERIPH (i.e. 8th bit):***

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name  
{PMA_CMN_SOFT_RESET} -value 0xffffffff
```

**Output:**

Register Name: PMA\_CMN\_SOFT\_RESET value: 0xffffffff

The 'xcvr\_write\_register' command succeeded.

***Writing to field PERIPH:***

```
xcvr_write_register -inst_name SmartBERT_L4_0/PF_XCVR_0/LANE0 -reg_name  
{PMA_CMN_SOFT_RESET:PERIPH} -value 0x1
```

**Output:**

Register Name: PMA\_CMN\_SOFT\_RESET:PERIPH value: 0x1

The 'xcvr\_write\_register' command succeeded.

**See Also**

[xcvr\\_read\\_register](#)

---

# Configure JTAG Chain Tcl Commands

---

These commands take a script that contains JTAG chain configuration-specific Tcl commands and passes them to FlashPro Express for execution.

Note that these commands cannot be executed directly from Libero.

## add\_actel\_device

Adds an Actel device to the chain. Either the *file* or *device* parameter must be specified. Chain programming mode must have been set.

```
add_actel_device [-file {filename}] [-device {device}] -name {name}
```

### Arguments

Where:

-file {*filename*}

Specifies a programming filename.

-device {*device*}

Specifies the device family (such as MPF300).

-name {*name*}

Specifies the device user name.

### Exceptions

None

### Example

```
add_actel_device -file {e:/design/stp/TOP.stp} -name {MyDevice1}  
add_actel_device -device {MPF300} -name {MyDevice2}
```

## add\_non\_actel\_device

Adds a non-Actel device in the chain. Either the file, or (-tck And -ir) parameters must be specified. The Chain programming mode must have been set.

```
add_non_actel_device [-file {file}] [-ir {ir}] [-tck {tck}] [-name {name}]
```

### Arguments

-file {*filename*}

Specifies a BSDL file.

-ir {*ir*}

Specifies the IR length.

-tck {*tck*}

Specifies the maximum TCK frequency (in MHz).

`-name {name}`

Specifies the device user name.

## Exceptions

None

## Examples

```
add_non_actel_device -file {e:/design/bsdl/DeviceX.bsd } -name {MyDevice3}
add_non_actel_device -ir 8 - tck 5 -name {MyDevice4}
```

## add\_non\_actel\_device\_to\_database

Imports settings via a BSDL file that adds non-Actel or non-Microsemi devices to the device database so that they are recognized during scan chain and auto-construction operations.

```
add_non_actel_device_to_database [-file {bsdl_filename}]
```

## Arguments

`-file {bsdl_filename}`

Specifies the path to the BSDL file and the BSDL filename add to the database.

## Exceptions

N/A

## Examples

The following example uses a BSDL file to add a non-Microsemi (1502AS J44) device to the device database:

```
add_non_actel_device_to_database -file {c:/bsdl/atmel/1502AS_J44.bsd}
```

The following example uses a BSDL file to add a non-Microsemi (80200) device to the device database:

```
add_non_actel_device_to_database -file {c:/bsdl/intel/80200_v1.0.bsd}
```

## construct\_chain\_automatically

Automatically starts chain construction for the specified programmer.

```
construct_chain_automatically[(-name {name})+]
```

## Arguments

`-name {name}`

Specifies the programmer(s) name(s).

## Exceptions

N/A

## Example

Example for one programmer:

```
construct_chain_automatically -name {21428}
```

Example for two programmers:

```
construct_chain_automatically -name {21428} -name {00579}
```

## copy\_device

Copies a device in the chain to the clipboard. Chain programming mode must be set. See the [paste\\_device command](#) for more information.

```
copy_device (-name {name})*
```

### Arguments

-name {name}

Specifies the device name. Repeat this argument to copy multiple devices.

### Exceptions

None

### Example

The example copies the device 'mydevice1' to the same location with a new name 'mydevice2'.

```
copy_device -name {MyDevice1} -name {MyDevice2}
```

## cut\_device

Removes one or more devices from the chain. It places the removed device in the clipboard. Chain programming mode must be set to use this command. See the [paste\\_device](#) command for more information.

```
cut_device (-name {name})*
```

### Arguments

-name {name}

Specifies the device name. You can repeat this argument for multiple devices.

### Exceptions

None

### Example

The following example removes the devices 'mydevice1' and 'mydevice2' from the chain.

```
cut_device -name {MyDevice1} -name {MyDevice2}
```

## enable\_device

Enables or disables a device in the chain (if the device is disabled, it is bypassed). Chain programming mode must be set. The device must be a Microsemi device.

```
enable_device -name {name} -enable {TRUE|FALSE}
```

### Arguments

-name {name}

Specifies your device name

-enable {TRUE|FALSE}

Specifies whether the device is to be enabled or disabled. If you specify multiple devices, this argument applies to all specified devices. (TRUE = enable. FALSE = disable)

## Exceptions

None

## Example

The following example disables the device 'mydevice1' in the chain.

```
enable_device -name {MyDevice1} -enable {FALSE}
```

## paste\_device

Pastes the devices that are on the clipboard in the chain, immediately above the *position\_name* device, if this parameter is specified. Otherwise it places the devices at the end of the chain. The chain programming mode must be enabled.

```
paste_device [-position_name {position_name}]
```

## Arguments

-position\_name {*position\_name*}

Optional argument that specifies the name of a device in the chain.

## Exceptions

None

## Examples

The following example pastes the devices on the clipboard immediately above the device 'mydevice3' in the chain.

```
paste_device -position_name {MyDevice3}
```

## remove\_device

Removes the device from the chain. Chain programming mode must be set.

```
remove_device (-name {name}) *
```

## Arguments

-name {*name*}

Specifies the device name. You can repeat this argument for multiple devices.

## Exceptions

None

## Example

Remove a device 'M2S050T' from the chain:

```
remove_device (-name {M2S050T}) *
```

## remove\_non\_actel\_device\_from\_database

Removes settings for non-Microsemi or non-Actel device from the device database.

```
remove_non_actel_device_from_database [-name {device_name}]
```

### Arguments

-name {*device\_name*}

Specifies the non-Actel or non-Microsemi device name to be removed from the database. You can repeat this argument for multiple devices.

### Supported Families

Non-Microsemi and non-Actel devices

### Exceptions

None

### Example

The following example removes the F1502AS\_J44 device from the database:

```
remove_non_actel_device_from_database -name {F1502AS_J44}
```

The following example removes the SA2\_PROCESSOR device from the database:

```
remove_non_actel_device_from_database -name {SA2_PROCESSOR}
```

## select\_libero\_design\_device

This command selects the Libero design device for the Programming Connectivity and Interface tool within Libero. This command is needed when the tool cannot automatically resolve the Libero design device when there are two or more identical devices that match the Libero design device in the configured JTAG chain.

### Syntax

```
select_libero_design_device -name {device_name}
```

### Arguments

-name {*device\_name*}

Specifies a user-assigned unique device name in the JTAG chain.

### Exceptions

None

### Example

```
select_libero_design_device -name {M2S050TS (2)}  
select_libero_design_device -name {my_design_device}
```

### Note

This Tcl command is typically used in a Tcl command script file that is passed to the Libero run\_tool command.

```
run_tool -name {CONFIGURE_CHAIN} -script {<flashPro_cmd>.tcl}
```

## set\_bsdfile

Sets a BSDL file to a non-Microsemi device in the chain. Chain programming mode must have been set. The device must be a non-Microsemi device.

```
set_bsdfile -name {name} -file {file}
```

### Arguments

name {*name*}

Specifies the device name.

-file {*file*}

Specifies the BSDL file.

### Supported Families

Any non-Microsemi device supported by FlashPro Express.

### Exceptions

None

### Example

The following example sets the BSDL file /design/bsdl/NewBSD2.bsd to the device 'MyDevice3':

```
set_bsdfile -name {MyDevice3} -file {e:/design/bsdl/NewBSD2.bsd}
```

## set\_device\_ir

Sets the IR length of a non-Microsemi device in the chain. Chain programming mode must be set. The device must be a non-Microsemi device.

```
set_device_ir -name {name} -ir {ir}
```

### Arguments

-name {*name*}

Specifies the device name.

-ir {*ir*}

Specifies the IR length.

### Supported Families

Any non-Microsemi device supported by FlashPro Express.

### Exceptions

None

### Example

The following example sets the IR length to '2' for the non-Microsemi device 'MyDevice4':

```
set_device_ir -name {MyDevice4} -ir {2}
```

## set\_device\_name

Changes the user name of a device in the chain. Chain programming mode must be set.

```
set_device_name -name {name} -new_name {new_name}
```

## Arguments

-name {*name*}

Identifies the old device name.

-new\_name {*new\_name*}

Specifies the new device name.

## Exceptions

None

## Example

The following example changes the user name of the device from 'MyDevice4' to 'MyDevice5':

```
set_device_name -name {MyDevice4} -new_name {MyDevice5}
```

## set\_device\_order

Sets the order of the devices in the chain to the order specified. Chain programming mode must have been set. Unspecified devices will be at the end of the chain.

```
set_device_order (-name {name}) *
```

## Arguments

-name {*name*}

Specifies the device name. To specify a new order you must repeat this argument and specify each device name in the order desired.

## Exceptions

None

## Example

The following example sets the device order for 'MyDevice1', 'MyDevice2', 'MyDevice3', and 'MyDevice4'. 'MyDevice2' is unspecified so it moves to the end of the chain.

```
set_device_order -name {MyDevice3} -name {MyDevice1} -name {MyDevice4}
```

the new order is:

```
MyDevice3 MyDevice1 MyDevice4 MyDevice2
```

## set\_device\_tck

Sets the maximum TCK frequency of a non-Microsemi device in the chain. Chain programming mode must be set. The device must be a non-Microsemi device.

```
set_device_tck -name {name} -tck {tck}
```

## Arguments

-name {*name*}

Specifies the device name.

-tck {*tck*}

Specifies the maximum TCK frequency (in MHz).

## Supported Families

Any non-Microsemi device supported by FlashPro Express.

## Exceptions

None

## Example

The following example sets the maximum TCK frequency of the non-Microsemi device 'MyDevice4':

```
set_device_tck -name {MyDevice4} -tck {2.25}
```

## set\_device\_type

Changes the family of a Microsemi device in the chain. The device must be a Microsemi device. The device parameter below is now optional.

```
set_device_type -name {name} -type {type}
```

## Arguments

-name {*name*}

Identifies the name of the device you want to change.

-type {*type*}

Specifies the device family.

## Exceptions

None

## Example

The following example sets the device 'MyDevice2' to the type MPF300.

```
set_device_type -name {MyDevice2} -type {MPF300}
```

## set\_programming\_action

This Tcl command is used to select the action for a device.

```
set_programming_action [-name {device_name}] -action {procedure_action}
```

## Arguments

-name

Specify the device name. This argument is mandatory.

-action

Specify the programming action. This argument is mandatory.

## Example

```
set_programming_action -name {MPF300(T_ES|TS_ES)} -action {DEVICE_INFO}  
set_programming_action -name {M2S/M2GL090(T|TS|TV)} -action {ERASE}
```

### See Also

[construct\\_chain\\_automatically](#)  
[scan\\_chain\\_prq](#)  
[enable\\_device](#)  
[set\\_debug\\_programmer](#)  
[set\\_device\\_name](#)  
[set\\_programming\\_file](#)  
[run\\_selected\\_actions](#)

## set\_programming\_file

This Tcl command is used to set the programming file for a device. Either the file or the no\_file flag must specified. A programming file must be loaded. The device must be a Microsemi device.

```
set_programming_file -name {device_name} -file {stapl_file_name_with_path}
```

### Arguments

-name

Specify the device name. This argument is mandatory.

-file

Specify the *file* path. This argument is mandatory.

### Example

```
set_programming_file -name {MPF300(T_ES|TS_ES)} -file  
{D:/export/CM1_PCIE_TOP_default_uic_l2_200_0_12.stp}
```

### See Also

[construct\\_chain\\_automatically](#)  
[scan\\_chain\\_prq](#)  
[enable\\_device](#)  
[set\\_debug\\_programmer](#)  
[set\\_device\\_name](#)  
[set\\_programming\\_action](#)  
[run\\_selected\\_actions](#)